

BAB VI

KESIMPULAN DAN SARAN

6.1 Kesimpulan

Berdasarkan hasil analisis yang telah dilakukan dalam mendeteksi kerusakan *bracing* pada portal bidang baja tipe *bracing* konsentrik, diperoleh beberapa kesimpulan sebagai berikut:

1. Metode matriks fleksibilitas dengan menggunakan vektor beban penentu lokasi kerusakan (VBPLK) dapat digunakan untuk mendeteksi kerusakan pada suatu portal bidang baja tipe *bracing* konsentrik lima lantai. VBPLK diperoleh dengan cara menghitung *Singular Value Decomposition* dari perbedaan matriks fleksibilitas pada kondisi tidak rusak dan rusak.
2. Variasi jumlah sensor mempengaruhi hasil deteksi kerusakan. Dengan lokasi kerusakan yang sama, semakin banyak jumlah sensor, hasil deteksi semakin akurat. Hal ini ditunjukkan pada kasus kerusakan 1, 2, 3, 4 dan 5. Pada kasus 3 dan 4 penggunaan sensor yang sedikit yaitu 2 buah dan 3 buah sensor ternyata tidak mampu mendeteksi kerusakan 3 buah *bracing*. Sedangkan pada kasus 5, penggunaan sensor sebanyak 5 buah memberikan indikasi yang lebih baik dibandingkan dengan kasus 3 dan 4 dengan lokasi *bracing* rusak yang sama.
3. Variasi penempatan sensor memberikan pengaruh yang cukup signifikan terhadap hasil deteksi.

Dengan jumlah sensor dan lokasi kerusakan yang sama, penempatan sensor yang jauh dari lokasi kerusakan memberikan hasil deteksi yang lebih akurat dibandingkan dengan penempatan sensor yang dekat dengan lokasi kerusakan. Hal ini ditunjukkan pada kasus kerusakan 5, 6 dan 7.

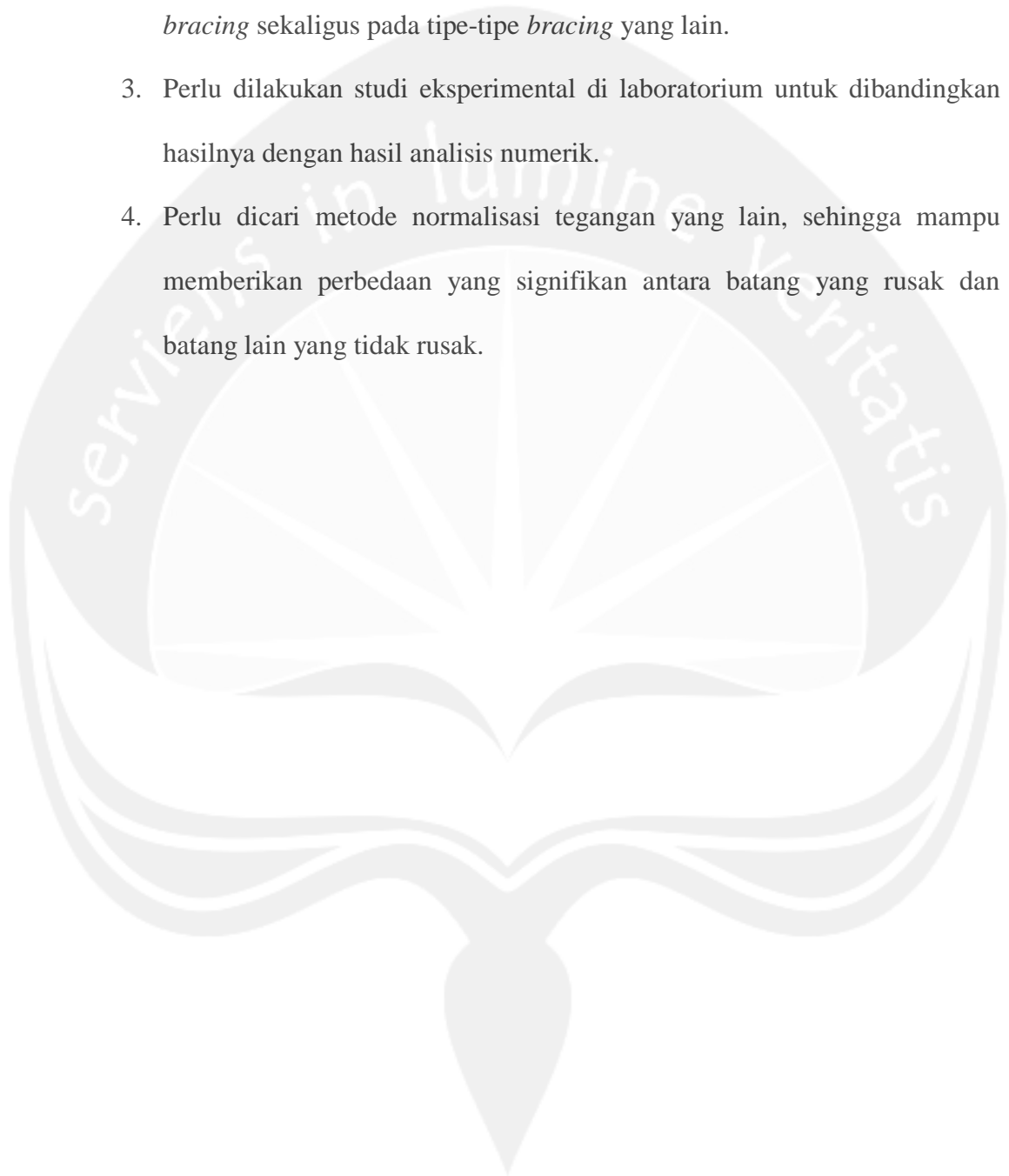
4. Metode matriks fleksibilitas dengan menggunakan vektor beban penentu lokasi kerusakan (VBPLK) dapat digunakan untuk mendeteksi kerusakan ganda (*balok-bracing* dan *kolom-bracing*) pada suatu portal bidang baja tipe *bracing* konsentrik lima lantai. Hal ini ditunjukkan pada kasus kerusakan 8 dan 9.
5. Normalisasi tegangan kumulatif (SRSS) memberikan indikasi yang baik untuk menentukan kerusakan struktur.
6. Perhitungan dengan analisis VBPLK mampu memberikan informasi yang benar, hal ini terbukti dengan sama besarnya nilai gaya-gaya batang yang dihitung dengan analisis VBPLK ataupun yang didapatkan dari analisis *software* ETABS.

6.2 Saran

Dari Tugas Akhir yang telah disusun ini, penulis memberikan beberapa saran sebagai berikut:

1. Perlu dicoba metode matriks fleksibilitas dengan VBPLK dengan lebih banyak variasi jumlah dan penempatan sensor dan juga dilakukan terhadap tipe-tipe *bracing* yang lain.

2. Perlu dicoba metode matriks fleksibilitas dengan VBPLK untuk beberapa kombinasi kerusakan elemen struktur lain, seperti kerusakan kolom-balok-*bracing* sekaligus pada tipe-tipe *bracing* yang lain.
3. Perlu dilakukan studi eksperimental di laboratorium untuk dibandingkan hasilnya dengan hasil analisis numerik.
4. Perlu dicari metode normalisasi tegangan yang lain, sehingga mampu memberikan perbedaan yang signifikan antara batang yang rusak dan batang lain yang tidak rusak.



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Lampiran 1: Coding Matlab Menghitung F_U Kasus Kerusakan 1

```

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n3=coor(12, 0);
n4=coor(18, 0);
n5=coor(0, 3. 5);
n6=coor(6, 3. 5);
n7=coor(12, 3. 5);
n8=coor(18, 3. 5);
n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);
n13=coor(0, 10. 5);
n14=coor(6, 10. 5);
n15=coor(12, 10. 5);
n16=coor(18, 10. 5);
n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);
n21=coor(0, 17. 5);
n22=coor(6, 17. 5);
n23=coor(12, 17. 5);
n24=coor(18, 17. 5);

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[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0. 0144; %m2%Kol om
A2=0. 0121; %Bal ok dan bracing
I1=5. 536e- 4; %m4
I2=2. 176e- 4;
r=78. 5; %kN/m3

vs=0. 3;
f1=2. 884; %Kol om
f2=3. 975; %Bal ok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
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k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

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id1=[5 6 7 8 9 10];
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Ks=assf(K1, id1, dof);
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Ks=Ks+assf(K3, id3, dof);
Ks=Ks+assf(K4, id4, dof);
Ks=Ks+assf(K5, id5, dof);
Ks=Ks+assf(K6, id6, dof);
Ks=Ks+assf(K7, id7, dof);
Ks=Ks+assf(K8, id8, dof);
Ks=Ks+assf(K9, id9, dof);
Ks=Ks+assf(K10, id10, dof);

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Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

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m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
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m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);

m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);
M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);
M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);
Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);
Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);

Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);
Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(Mr\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(20, i); mode(35, i)]
v=sqrt(m(mode'*Mr*mode)
wm=di ag(w(1:84));
Fu1=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```


Lampiran 2: Coding Matlab Menghitung F_D Kasus Kerusakan 1

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);
n5=coor(0, 3. 5);
n6=coor(6, 3. 5);
n7=coor(12, 3. 5);
n8=coor(18, 3. 5);
n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);
n13=coor(0, 10. 5);
n14=coor(6, 10. 5);
n15=coor(12, 10. 5);
n16=coor(18, 10. 5);
n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);
n21=coor(0, 17. 5);
n22=coor(6, 17. 5);
n23=coor(12, 17. 5);
n24=coor(18, 17. 5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15); %//---
--- damage member ----//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0. 0144; %m2%Kol om
A2=0. 0121; %Balok dan bracing
A40d=A2*0. 5; %//---- damage
member ----//

I1=5. 536e- 4; %m4
I2=2. 176e- 4;
I40d=I2*0. 5; %//---- damage
member ----//
r=78. 5; %kN/m3
vs=0. 3;
f1=2. 884; %Kol om
f2=3. 975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);
k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);
k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A40d, I40d, L40, f2,
vs); K40=kg(k40, T40); %//----
damage member ----//
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];
id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];
id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
%//---- damage member ----//
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];
Ks=assf(K1, id1, dof);
Ks=Ks+assf(K2, id2, dof);
Ks=Ks+assf(K3, id3, dof);
Ks=Ks+assf(K4, id4, dof);
Ks=Ks+assf(K5, id5, dof);

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```

Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);
Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);
Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof); %//
---- damage member ----//
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);
m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);
m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);

m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);
m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A40d, L40); %//----
---- damage member ----//
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);
M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);
M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40); %//----
---- damage member ----//
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);
Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);
Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof); %//
---- damage member ----//
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(Mr\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(20, i); mode(35, i)]
v=sqrtm(mode'*Mr*mode)
wm=di ag(w(1:84));
Fd1=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```

Lampiran 3: *Coding* Matlab Menghitung SVD Kasus Kerusakan 1

```
Fu1 =1. 0e- 004 * [0. 0583    0. 0685; 0. 0685    0. 1173]  
Fd1 =1. 0e- 004 * [0. 0585    0. 0674; 0. 0674    0. 1252]
```

```
Fdel =Fu1- Fd1  
[u, s, v]=svd(Fdel)
```



Lampiran 4: Coding Matlab Menghitung Gaya Batang Kasus Kerusakan 1

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);
n5=coor(0, 3. 5);
n6=coor(6, 3. 5);
n7=coor(12, 3. 5);
n8=coor(18, 3. 5);
n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);
n13=coor(0, 10. 5);
n14=coor(6, 10. 5);
n15=coor(12, 10. 5);
n16=coor(18, 10. 5);
n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);
n21=coor(0, 17. 5);
n22=coor(6, 17. 5);
n23=coor(12, 17. 5);
n24=coor(18, 17. 5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
%/-- damage member ---//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0. 0144; %m2%Kol om
A2=0. 0121; %Bal ok dan bracing
I1=5. 536e- 4; %m4
I2=2. 176e- 4;

r=78. 5; %kN/m3
vs=0. 3;
f1=2. 884; %Kol om
f2=3. 975; %Bal ok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);
k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];
id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];
id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

Ks=assf(K1, id1, dof);
Ks=Ks+assf(K2, id2, dof);
Ks=Ks+assf(K3, id3, dof);
Ks=Ks+assf(K4, id4, dof);
Ks=Ks+assf(K5, id5, dof);
Ks=Ks+assf(K6, id6, dof);
Ks=Ks+assf(K7, id7, dof);
Ks=Ks+assf(K8, id8, dof);

```

```

Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);
Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);
Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);
m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);
m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);
m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);

m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);
M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);
M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);
Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);
Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);

Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);
Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(Mr\Ks);
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder);

i=1:84;
pi m=[mode(20, i); mode(35, i)];
v=sqrt(m(mode'*Mr*mode));
wm=di ag(w(1:84));
Fu1=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

R=zeros(84, 1);
R(20, 1)=-0.9903;
R(35, 1)=-0.1387;

U=sol v(Ks, R);

u1=di ssf(U, i d1, T1);
u2=di ssf(U, i d2, T2);
u3=di ssf(U, i d3, T3);
u4=di ssf(U, i d4, T4);
u5=di ssf(U, i d5, T5);
u6=di ssf(U, i d6, T6);
u7=di ssf(U, i d7, T7);
u8=di ssf(U, i d8, T8);
u9=di ssf(U, i d9, T9);
u10=di ssf(U, i d10, T10);
u11=di ssf(U, i d11, T11);
u12=di ssf(U, i d12, T12);
u13=di ssf(U, i d13, T13);
u14=di ssf(U, i d14, T14);
u15=di ssf(U, i d15, T15);
u16=di ssf(U, i d16, T16);
u17=di ssf(U, i d17, T17);
u18=di ssf(U, i d18, T18);
u19=di ssf(U, i d19, T19);
u20=di ssf(U, i d20, T20);
u21=di ssf(U, i d21, T21);
u22=di ssf(U, i d22, T22);
u23=di ssf(U, i d23, T23);
u24=di ssf(U, i d24, T24);
u25=di ssf(U, i d25, T25);
u26=di ssf(U, i d26, T26);
u27=di ssf(U, i d27, T27);
u28=di ssf(U, i d28, T28);
u29=di ssf(U, i d29, T29);
u30=di ssf(U, i d30, T30);
u31=di ssf(U, i d31, T31);
u32=di ssf(U, i d32, T32);
u33=di ssf(U, i d33, T33);
u34=di ssf(U, i d34, T34);
u35=di ssf(U, i d35, T35);

```

u36=di ssf (U, i d36, T36) ;
 u37=di ssf (U, i d37, T37) ;
 u38=di ssf (U, i d38, T38) ;
 u39=di ssf (U, i d39, T39) ;
 u40=di ssf (U, i d40, T40) ;
 u41=di ssf (U, i d41, T41) ;
 u42=di ssf (U, i d42, T42) ;
 u43=di ssf (U, i d43, T43) ;
 u44=di ssf (U, i d44, T44) ;
 u45=di ssf (U, i d45, T45) ;

S20=stref (k20, u20, So20)
 S21=stref (k21, u21, So21)
 S22=stref (k22, u22, So22)
 S23=stref (k23, u23, So23)
 S24=stref (k24, u24, So24)
 S25=stref (k25, u25, So25)
 S26=stref (k26, u26, So26)
 S27=stref (k27, u27, So27)
 S28=stref (k28, u28, So28)
 S29=stref (k29, u29, So29)
 S30=stref (k30, u30, So30)
 S31=stref (k31, u31, So31)
 S32=stref (k32, u32, So32)
 S33=stref (k33, u33, So33)
 S34=stref (k34, u34, So34)
 S35=stref (k35, u35, So35)
 S36=stref (k36, u36, So36)
 S37=stref (k37, u37, So37)
 S38=stref (k38, u38, So38)
 S39=stref (k39, u39, So39)
 S40=stref (k40, u40, So40)
 S41=stref (k41, u41, So41)
 S42=stref (k42, u42, So42)
 S43=stref (k43, u43, So43)
 S44=stref (k44, u44, So44)
 S45=stref (k45, u45, So45)

So1=zeros (6, 1) ;
 So2=zeros (6, 1) ;
 So3=zeros (6, 1) ;
 So4=zeros (6, 1) ;
 So5=zeros (6, 1) ;
 So6=zeros (6, 1) ;
 So7=zeros (6, 1) ;
 So8=zeros (6, 1) ;
 So9=zeros (6, 1) ;
 So10=zeros (6, 1) ;
 So11=zeros (6, 1) ;
 So12=zeros (6, 1) ;
 So13=zeros (6, 1) ;
 So14=zeros (6, 1) ;
 So15=zeros (6, 1) ;
 So16=zeros (6, 1) ;
 So17=zeros (6, 1) ;
 So18=zeros (6, 1) ;
 So19=zeros (6, 1) ;
 So20=zeros (6, 1) ;
 So21=zeros (6, 1) ;
 So22=zeros (6, 1) ;
 So23=zeros (6, 1) ;
 So24=zeros (6, 1) ;
 So25=zeros (6, 1) ;
 So26=zeros (6, 1) ;
 So27=zeros (6, 1) ;
 So28=zeros (6, 1) ;
 So29=zeros (6, 1) ;
 So30=zeros (6, 1) ;
 So31=zeros (6, 1) ;
 So32=zeros (6, 1) ;
 So33=zeros (6, 1) ;
 So34=zeros (6, 1) ;
 So35=zeros (6, 1) ;
 So36=zeros (6, 1) ;
 So37=zeros (6, 1) ;
 So38=zeros (6, 1) ;
 So39=zeros (6, 1) ;
 So40=zeros (6, 1) ;
 So41=zeros (6, 1) ;
 So42=zeros (6, 1) ;
 So43=zeros (6, 1) ;
 So44=zeros (6, 1) ;
 So45=zeros (6, 1) ;

S1=stref (k1, u1, So1)
 S2=stref (k2, u2, So2)
 S3=stref (k3, u3, So3)
 S4=stref (k4, u4, So4)
 S5=stref (k5, u5, So5)
 S6=stref (k6, u6, So6)
 S7=stref (k7, u7, So7)
 S8=stref (k8, u8, So8)
 S9=stref (k9, u9, So9)
 S10=stref (k10, u10, So10)
 S11=stref (k11, u11, So11)
 S12=stref (k12, u12, So12)
 S13=stref (k13, u13, So13)
 S14=stref (k14, u14, So14)
 S15=stref (k15, u15, So15)
 S16=stref (k16, u16, So16)
 S17=stref (k17, u17, So17)
 S18=stref (k18, u18, So18)
 S19=stref (k19, u19, So19)

Lampiran 5: *Output* Gaya-gaya Batang dari *software* Matlab Kasus 1

S1 =	0.0087	0.0478	-0.0153	0.5069
-0.0291	0.0260	0.0031	S29 =	0.0000
0.0136	-0.0012	-0.0110	-0.0586	0.0000
0.0411	-0.0087	S20 =	-0.0103	-0.5069
-0.0291	0.0262	0.0357	-0.0206	-0.0000
-0.0136	S11 =	-0.0283	0.0586	0.0000
0.0404	-0.0102	-0.0440	0.0103	S39 =
S2 =	-0.0011	-0.0357	-0.0154	-0.6899
0.0462	-0.0028	0.0283	S30 =	0.0000
0.0047	0.0102	-0.0549	0.0310	0.0000
0.0152	0.0011	S21 =	-0.0012	0.6899
-0.0462	-0.0036	0.3504	0.0013	-0.0000
-0.0047	S12 =	-0.0346	-0.0310	0.0000
0.0131	0.0074	-0.0562	0.0012	S40 =
S3 =	0.0076	-0.3504	-0.0054	-0.0035
0.0111	0.0230	0.0346	S31 =	0.0000
0.0117	-0.0074	-0.0650	-0.0145	0.0000
0.0347	-0.0076	S22 =	-0.0026	0.0035
-0.0111	0.0229	-0.2579	-0.0014	-0.0000
-0.0117	S13 =	-0.0181	0.0145	0.0000
0.0355	0.0088	-0.0325	0.0026	S41 =
S4 =	0.0069	0.2579	-0.0078	-0.1508
0.0324	0.0202	0.0181	S32 =	0.0000
0.0123	-0.0088	-0.0307	0.0069	0.0000
0.0370	-0.0069	S23 =	-0.0088	0.1508
-0.0324	0.0209	-0.0361	-0.0107	-0.0000
-0.0123	S14 =	-0.0143	-0.0069	0
0.0368	0.0011	-0.0245	0.0088	S42 =
S5 =	-0.0019	0.0361	-0.0202	0.0123
-0.3178	-0.0059	0.0143	S33 =	0.0000
0.0023	-0.0011	-0.0255	-0.0171	0.0000
0.0067	0.0019	S24 =	-0.0066	-0.0123
0.3178	-0.0054	0.0234	-0.0081	-0.0000
-0.0023	S15 =	0.0041	0.0171	0.0000
0.0070	-0.0101	0.0179	0.0066	S43 =
S6 =	0.0069	-0.0234	-0.0151	0.0403
-0.0034	0.0210	-0.0041	S34 =	0.0000
0.0124	0.0101	-0.0034	0.0202	0.0000
0.0371	-0.0069	S25 =	-0.0084	-0.0403
0.0034	0.0201	0.0146	-0.0140	-0.0000
-0.0124	S16 =	0.0065	-0.0202	0.0000
0.0373	0.0493	0.0215	0.0084	S44 =
S7 =	0.0008	-0.0146	-0.0156	-0.0227
-0.0142	-0.0000	-0.0065	S35 =	0.0000
0.0078	-0.0493	0.0014	-0.0069	0.0000
0.0234	-0.0008	S26 =	-0.0101	0.0227
0.0142	0.0030	0.0635	-0.0151	-0.0000
-0.0078	S17 =	-0.0113	0.0069	0.0000
0.0235	0.9166	-0.0133	0.0101	S45 =
S8 =	0.0002	-0.0635	-0.0201	0.0166
0.0886	0	0.0113	S36 =	0.0000
-0.0012	-0.9166	-0.0264	0.6652	0.0000
-0.0044	-0.0002	S27 =	0.0000	-0.0166
-0.0886	0.0005	-0.0237	0.0000	-0.0000
0.0012	S18 =	-0.0108	-0.6652	0.0000
-0.0025	-0.9337	-0.0118	-0.0000	
S9 =	-0.0044	0.0237	0.0000	
-0.0082	0.0000	0.0108	S37 =	
0.0092	0.9337	-0.0261	-0.6343	
0.0276	0.0044	S28 =	0.0000	
0.0082	-0.0153	0.0156	0.0000	
-0.0092	S19 =	-0.0101	0.6343	
0.0275	-0.0478	-0.0200	-0.0000	
S10 =	-0.0031	-0.0156	0.0000	
0.0012	-0.0000	0.0101	S38 =	

Lampiran 6: Output Gaya-gaya Batang dari software ETABS Kasus 1

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C O L U M N F O R C E E N V E L O P E S

STORY	COLUMN	ITEM	P	V2	V3	T	M2	M3
LT5	C5	Min Value	-0.0069	-0.0089	0.0000	0.0000	0.0000	-0.0108
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0069	-0.0089	0.0000	0.0000	0.0000	0.0202
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C6	Min Value	0.0171	-0.0066	0.0000	0.0000	0.0000	-0.0081
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0171	-0.0066	0.0000	0.0000	0.0000	0.0151
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C7	Min Value	-0.0202	-0.0084	0.0000	0.0000	0.0000	-0.0140
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0202	-0.0084	0.0000	0.0000	0.0000	0.0156
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C8	Min Value	0.0069	-0.0101	0.0000	0.0000	0.0000	-0.0151
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0069	-0.0101	0.0000	0.0000	0.0000	0.0202
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C5	Min Value	-0.0156	-0.0101	0.0000	0.0000	0.0000	-0.0200
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0156	-0.0101	0.0000	0.0000	0.0000	0.0153
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C6	Min Value	0.0586	-0.0103	0.0000	0.0000	0.0000	-0.0206
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0586	-0.0103	0.0000	0.0000	0.0000	0.0154
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C7	Min Value	-0.0311	-0.0012	0.0000	0.0000	0.0000	0.0012
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0311	-0.0012	0.0000	0.0000	0.0000	0.0054
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C8	Min Value	0.0145	-0.0026	0.0000	0.0000	0.0000	-0.0014
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0145	-0.0026	0.0000	0.0000	0.0000	0.0078
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C5	Min Value	-0.0234	0.0041	0.0000	0.0000	0.0000	0.0034
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0234	0.0041	0.0000	0.0000	0.0000	0.0178
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C6	Min Value	-0.0145	0.0065	0.0000	0.0000	0.0000	-0.0014
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0145	0.0065	0.0000	0.0000	0.0000	0.0214
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C7	Min Value	-0.0635	-0.0113	0.0000	0.0000	0.0000	-0.0133
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0635	-0.0113	0.0000	0.0000	0.0000	0.0264
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C8	Min Value	0.0237	-0.0108	0.0000	0.0000	0.0000	-0.0118
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0237	-0.0108	0.0000	0.0000	0.0000	0.0261
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C5	Min Value	-0.0357	-0.0282	0.0000	0.0000	0.0000	-0.0440
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0357	-0.0282	0.0000	0.0000	0.0000	0.0549
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C6	Min Value	-0.3503	-0.0346	0.0000	0.0000	0.0000	-0.0561
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.3503	-0.0346	0.0000	0.0000	0.0000	0.0649
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C7	Min Value	0.2578	-0.0181	0.0000	0.0000	0.0000	-0.0325
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.2578	-0.0181	0.0000	0.0000	0.0000	0.0307
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C8	Min Value	0.0361	-0.0143	0.0000	0.0000	0.0000	-0.0245
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0361	-0.0143	0.0000	0.0000	0.0000	0.0254
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C5	Min Value	-0.0493	0.0008	0.0000	0.0000	0.0000	-0.0030

		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0493	0.0008	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C6	Min Value	-0.9166	0.0002	0.0000	0.0000	0.0000	-0.0006
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.9166	0.0002	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C7	Min Value	0.9336	-0.0044	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.9336	-0.0044	0.0000	0.0000	0.0000	0.0152
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C8	Min Value	0.0478	-0.0031	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0478	-0.0031	0.0000	0.0000	0.0000	0.0110
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD

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B E A M F O R C E E N V E L O P E S

STORY	BEAM	ITEM	P	V2	V3	T	M2	M3
LT5	B4	Min Value	-0.0089	-0.0069	0.0000	0.0000	0.0000	-0.0202
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0089	-0.0069	0.0000	0.0000	0.0000	0.0210
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	B5	Min Value	-0.0011	0.0019	0.0000	0.0000	0.0000	-0.0054
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0011	0.0019	0.0000	0.0000	0.0000	0.0059
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	B6	Min Value	0.0101	-0.0069	0.0000	0.0000	0.0000	-0.0210
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0101	-0.0069	0.0000	0.0000	0.0000	0.0202
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	B4	Min Value	-0.0012	-0.0087	0.0000	0.0000	0.0000	-0.0260
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0012	-0.0087	0.0000	0.0000	0.0000	0.0262
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	B5	Min Value	0.0103	0.0011	0.0000	0.0000	0.0000	-0.0036
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0103	0.0011	0.0000	0.0000	0.0000	0.0028
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	B6	Min Value	-0.0074	-0.0077	0.0000	0.0000	0.0000	-0.0230
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0074	-0.0077	0.0000	0.0000	0.0000	0.0229
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	B4	Min Value	0.0142	-0.0078	0.0000	0.0000	0.0000	-0.0235
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0142	-0.0078	0.0000	0.0000	0.0000	0.0236
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	B5	Min Value	-0.0886	0.0012	0.0000	0.0000	0.0000	-0.0025
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0886	0.0012	0.0000	0.0000	0.0000	0.0044
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	B6	Min Value	0.0082	-0.0092	0.0000	0.0000	0.0000	-0.0276
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0082	-0.0092	0.0000	0.0000	0.0000	0.0275
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	B4	Min Value	-0.0324	-0.0123	0.0000	0.0000	0.0000	-0.0370
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0324	-0.0123	0.0000	0.0000	0.0000	0.0368
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	B5	Min Value	0.3179	-0.0023	0.0000	0.0000	0.0000	-0.0067
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.3179	-0.0023	0.0000	0.0000	0.0000	0.0070
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	B6	Min Value	0.0034	-0.0124	0.0000	0.0000	0.0000	-0.0371
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0034	-0.0124	0.0000	0.0000	0.0000	0.0372
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	B4	Min Value	0.0291	-0.0136	0.0000	0.0000	0.0000	-0.0410

Lampiran 7: Coding Matlab Menghitung F_U Kasus Kerusakan 2

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);

k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

E=2e8; %kN/m2
Ks=assf(K1, id1, dof);

```

```

Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);

m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);

Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(M\r\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(11, i); mode(20, i); m
ode(35, i); mode(44, i)]
v=sqrt(m(mode'*Mr*mode)
wm=di ag(w(1:84));
Fu2=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```

Lampiran 8: Coding Matlab Menghitung F_D Kasus Kerusakan 2

```

n1=coor(0,0);
n2=coor(6,0);
n3=coor(12,0);
n4=coor(18,0);

n5=coor(0,3.5);
n6=coor(6,3.5);
n7=coor(12,3.5);
n8=coor(18,3.5);

n9=coor(0,7);
n10=coor(6,7);
n11=coor(12,7);
n12=coor(18,7);

n13=coor(0,10.5);
n14=coor(6,10.5);
n15=coor(12,10.5);
n16=coor(18,10.5);

n17=coor(0,14);
n18=coor(6,14);
n19=coor(12,14);
n20=coor(18,14);

n21=coor(0,17.5);
n22=coor(6,17.5);
n23=coor(12,17.5);
n24=coor(18,17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15); %//---
--- damage member ----//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
A40d=A2*0.5; %//----damage
member ----//
I1=5.536e-4; %m4
I2=2.176e-4;
I40d=I2*0.5; %//----damage
member ----//
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=klfs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=klfs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=klfs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=klfs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=klfs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=klfs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=klfs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=klfs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=klfs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=klfs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=klfs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=klfs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=klfs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=klfs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=klfs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=klfs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=klfs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=klfs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=klfs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=klfs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=klfs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=klfs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=klfs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=klfs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=klfs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=klfs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=klfs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=klfs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=klfs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=klfs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=klfs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);

k32=klfs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=klfs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=klfs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=klfs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=klfs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=klfs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=klfs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=klfs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=klfs(E, A40d, I40d, L40, f2,
vs); K40=kg(k40, T40); %//----
damage member ----//
k41=klfs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=klfs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=klfs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=klfs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=klfs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;

id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36
76]; %//----damage member ---
--//

```

```

id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

Ks=assf(K1, i d1, dof);
Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof); %//
---- damage member ----//
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);

m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);
m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A40d, L40); %//----
---- damage member ----//
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40); %//----
---- damage member ----//
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);
Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof); %//
---- damage member ----//
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(Mr\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(11, i); mode(20, i); m
ode(35, i); mode(44, i)]
v=sqrt m(mode' *Mr* mode)
wm=di ag(w(1:84));
Fd2=(pi m*i nv(v)) *i nv(wm^2) *
(pi m*i nv(v))'
i m*i nv(v))'

```

Lampiran 9: *Coding* Matlab Menghitung SVD Kasus Kerusakan 2

```
Fu2 =1. 0e-004 *[0. 0244    0. 0251    0. 0279    0. 0311; 0. 0251    0. 0583    0. 0685  
0. 0804; 0. 0279    0. 0685    0. 1173    0. 1426; 0. 0311    0. 0804    0. 1426    0. 2125]  
Fd2 =1. 0e-004 *[0. 0244    0. 0251    0. 0277    0. 0309; 0. 0251    0. 0585    0. 0674  
0. 0794; 0. 0277    0. 0674    0. 1252    0. 1494; 0. 0309    0. 0794    0. 1494    0. 2185]  
Fdel =Fu2- Fd2  
[u, s, v]=svd(Fdel)
```



Lampiran 10: Coding Matlab Menghitung Gaya Batang Kasus Kerusakan 2

```

n1=coor(0,0);
n2=coor(6,0);
n3=coor(12,0);
n4=coor(18,0);

n5=coor(0,3.5);
n6=coor(6,3.5);
n7=coor(12,3.5);
n8=coor(18,3.5);

n9=coor(0,7);
n10=coor(6,7);
n11=coor(12,7);
n12=coor(18,7);

n13=coor(0,10.5);
n14=coor(6,10.5);
n15=coor(12,10.5);
n16=coor(18,10.5);

n17=coor(0,14);
n18=coor(6,14);
n19=coor(12,14);
n20=coor(18,14);

n21=coor(0,17.5);
n22=coor(6,17.5);
n23=coor(12,17.5);
n24=coor(18,17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n8);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);

k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

E=2e8; %kN/m2
Ks=assf(K1, id1, dof);

```



```

Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);

m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);

Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(Mr\Ks);
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder);

i=1:84;
pi m=[mode(11, i); mode(20, i); m
ode(35, i); mode(44, i)];
v=sqrt(m(mode'*Mr*mode));
wm=di ag(w(1:84));

Untuk VBPLK 1:
Fu2=(pi m*i nv(v))*i nv(wm^2)*
(pi m*i nv(v))';

R=zeros(84, 1);
R(11, 1)=-0.8267;
R(20, 1)=-0.4834;
R(35, 1)=0.1317;
R(44, 1)=-0.2561;

Fu2=(pi m*i nv(v))*i nv(wm^2)*
(pi m*i nv(v))';

Untuk VBPLK 2:
R=zeros(84, 1);
R(11, 1)=-0.5612;
R(20, 1)=0.7442;
R(35, 1)=-0.1815;
R(44, 1)=0.3135;

U=sol v(Ks, R);

u1=di ssf(U, i d1, T1);
u2=di ssf(U, i d2, T2);
u3=di ssf(U, i d3, T3);
u4=di ssf(U, i d4, T4);
u5=di ssf(U, i d5, T5);

```

```

u6=di ssf(U, i d6, T6);
u7=di ssf(U, i d7, T7);
u8=di ssf(U, i d8, T8);
u9=di ssf(U, i d9, T9);
u10=di ssf(U, i d10, T10);
u11=di ssf(U, i d11, T11);
u12=di ssf(U, i d12, T12);
u13=di ssf(U, i d13, T13);
u14=di ssf(U, i d14, T14);
u15=di ssf(U, i d15, T15);

u16=di ssf(U, i d16, T16);
u17=di ssf(U, i d17, T17);
u18=di ssf(U, i d18, T18);
u19=di ssf(U, i d19, T19);
u20=di ssf(U, i d20, T20);
u21=di ssf(U, i d21, T21);
u22=di ssf(U, i d22, T22);
u23=di ssf(U, i d23, T23);
u24=di ssf(U, i d24, T24);
u25=di ssf(U, i d25, T25);
u26=di ssf(U, i d26, T26);
u27=di ssf(U, i d27, T27);
u28=di ssf(U, i d28, T28);
u29=di ssf(U, i d29, T29);
u30=di ssf(U, i d30, T30);
u31=di ssf(U, i d31, T31);
u32=di ssf(U, i d32, T32);
u33=di ssf(U, i d33, T33);
u34=di ssf(U, i d34, T34);
u35=di ssf(U, i d35, T35);

u36=di ssf(U, i d36, T36);
u37=di ssf(U, i d37, T37);
u38=di ssf(U, i d38, T38);
u39=di ssf(U, i d39, T39);
u40=di ssf(U, i d40, T40);
u41=di ssf(U, i d41, T41);
u42=di ssf(U, i d42, T42);
u43=di ssf(U, i d43, T43);
u44=di ssf(U, i d44, T44);
u45=di ssf(U, i d45, T45);

So1=zeros(6, 1);
So2=zeros(6, 1);
So3=zeros(6, 1);
So4=zeros(6, 1);
So5=zeros(6, 1);
So6=zeros(6, 1);
So7=zeros(6, 1);
So8=zeros(6, 1);
So9=zeros(6, 1);
So10=zeros(6, 1);
So11=zeros(6, 1);
So12=zeros(6, 1);
So13=zeros(6, 1);
So14=zeros(6, 1);
So15=zeros(6, 1);
So16=zeros(6, 1);
So17=zeros(6, 1);
So18=zeros(6, 1);
So19=zeros(6, 1);
So20=zeros(6, 1);
So21=zeros(6, 1);
So22=zeros(6, 1);
So23=zeros(6, 1);
So24=zeros(6, 1);
So25=zeros(6, 1);
So26=zeros(6, 1);
So27=zeros(6, 1);
So28=zeros(6, 1);
So29=zeros(6, 1);
So30=zeros(6, 1);
So31=zeros(6, 1);
So32=zeros(6, 1);
So33=zeros(6, 1);
So34=zeros(6, 1);

So35=zeros(6, 1);
So36=zeros(6, 1);
So37=zeros(6, 1);
So38=zeros(6, 1);
So39=zeros(6, 1);
So40=zeros(6, 1);
So41=zeros(6, 1);
So42=zeros(6, 1);
So43=zeros(6, 1);
So44=zeros(6, 1);
So45=zeros(6, 1);

S1=stref(k1, u1, So1)
S2=stref(k2, u2, So2)
S3=stref(k3, u3, So3)
S4=stref(k4, u4, So4)
S5=stref(k5, u5, So5)
S6=stref(k6, u6, So6)
S7=stref(k7, u7, So7)
S8=stref(k8, u8, So8)
S9=stref(k9, u9, So9)
S10=stref(k10, u10, So10)
S11=stref(k11, u11, So11)
S12=stref(k12, u12, So12)
S13=stref(k13, u13, So13)
S14=stref(k14, u14, So14)
S15=stref(k15, u15, So15)

S16=stref(k16, u16, So16)
S17=stref(k17, u17, So17)
S18=stref(k18, u18, So18)
S19=stref(k19, u19, So19)
S20=stref(k20, u20, So20)
S21=stref(k21, u21, So21)
S22=stref(k22, u22, So22)
S23=stref(k23, u23, So23)
S24=stref(k24, u24, So24)
S25=stref(k25, u25, So25)
S26=stref(k26, u26, So26)
S27=stref(k27, u27, So27)
S28=stref(k28, u28, So28)
S29=stref(k29, u29, So29)
S30=stref(k30, u30, So30)
S31=stref(k31, u31, So31)
S32=stref(k32, u32, So32)
S33=stref(k33, u33, So33)
S34=stref(k34, u34, So34)
S35=stref(k35, u35, So35)

S36=stref(k36, u36, So36)
S37=stref(k37, u37, So37)
S38=stref(k38, u38, So38)
S39=stref(k39, u39, So39)
S40=stref(k40, u40, So40)
S41=stref(k41, u41, So41)
S42=stref(k42, u42, So42)
S43=stref(k43, u43, So43)
S44=stref(k44, u44, So44)
S45=stref(k45, u45, So45)

```

Lampiran 11: *Output* Gaya-gaya Batang dari *software* Matlab Kasus 2

Aki bat VBPLK	S10 =	0.0462	0.0156	-0.2386
1:	-0.0080	-0.0041	0.0283	0.0000
S1 =	-0.0105	0	0.0178	0
0.0245	-0.0315	-0.0462	-0.0156	S38 =
-0.0089	0.0080	0.0041	0.0263	-0.3411
-0.0270	0.0105	-0.0143	S29 =	-0.0000
-0.0245	-0.0315	S20 =	-0.0560	0.0000
0.0089	S11 =	-0.0384	0.0169	0.3411
-0.0267	0.0950	0.0212	0.0307	0.0000
S2 =	0.0002	0.0384	0.0560	0.0000
0.1416	0.0007	0.0384	-0.0169	S39 =
-0.0024	-0.0950	-0.0212	0.0286	0.5720
-0.0078	-0.0002	0.0360	S30 =	-0.0000
-0.1416	0.0008	S21 =	0.0204	-0.0000
0.0024	S12 =	-0.4562	0.0103	-0.5720
-0.0068	-0.0000	0.0254	0.0178	0.0000
S3 =	-0.0098	0.0458	-0.0204	0.0000
-0.0228	-0.0293	0.4562	-0.0103	S40 =
-0.0079	0.0000	-0.0254	0.0181	1.0e-003 *
-0.0235	0.0098	0.0431	S31 =	-0.9081
0.0228	-0.0293	S22 =	0.0175	0
0.0079	S13 =	0.3399	0.0099	0.0000
-0.0237	-0.0076	0.0222	0.0170	0.9081
S4 =	-0.0073	0.0443	-0.0175	0
-0.0219	-0.0215	-0.3399	-0.0099	0.0000
-0.0106	0.0076	-0.0222	0.0175	S41 =
-0.0320	0.0073	0.0333	S32 =	0.1439
0.0219	-0.0224	S23 =	-0.0073	-0.0000
0.0106	S14 =	0.0384	0.0076	-0.0000
-0.0318	-0.0193	0.0187	0.0051	-0.0000
S5 =	0.0023	0.0380	0.0073	-0.1439
0.2012	0.0023	-0.0384	-0.0076	0.0000
-0.0017	0.0075	-0.0187	0.0215	-0.0000
-0.0047	0.0193	0.0274	S33 =	S42 =
-0.2012	-0.0023	S24 =	0.0056	-0.1153
0.0017	0.0062	-0.0278	0.0049	-0.0000
-0.0056	S15 =	-0.0007	0.0022	-0.0000
S6 =	0.0099	-0.0040	-0.0056	0.1153
0.0134	-0.0077	0.0278	-0.0049	0.0000
-0.0110	-0.0236	0.0007	0.0149	-0.0000
-0.0330	-0.0099	0.0016	S34 =	S43 =
-0.0134	0.0077	S25 =	-0.0317	0.1867
0.0110	-0.0227	-0.1764	0.0080	-0.0000
-0.0332	S16 =	-0.0024	0.0104	-0.0000
S7 =	-0.0473	-0.0065	0.0317	-0.1867
0.0163	-0.0033	0.1764	-0.0080	0.0000
-0.0100	0.0000	0.0024	0.0174	-0.0000
-0.0299	0.0473	-0.0018	S35 =	S44 =
-0.0163	0.0033	S26 =	0.0077	0.0430
0.0100	-0.0114	0.1048	0.0099	-0.0000
-0.0299	S17 =	0.0048	0.0118	-0.0000
S8 =	-0.7418	0.0053	-0.0077	-0.0430
0.0109	-0.0032	-0.1048	-0.0099	0.0000
0.0002	-0.0000	-0.0048	0.0227	-0.0000
0.0010	0.7418	0.0114	S36 =	S45 =
-0.0109	0.0032	S27 =	-0.1430	0.0079
-0.0002	-0.0113	-0.0000	-0.0000	-0.0000
0.0004	S18 =	0.0274	0.0000	0.0000
S9 =	0.6947	0.0052	0.1430	-0.0079
-0.0046	-0.0040	0.0058	0.0000	0.0000
-0.0099	0	-0.0274	0.0000	0.0000
-0.0295	-0.6947	-0.0052	S37 =	
0.0046	0.0040	0.0125	0.2386	
0.0099	-0.0140	S28 =	-0.0000	
-0.0296	S19 =	-0.0178	-0.0000	

Aki bat VBPLK	S10 =	-0.0102	-0.0255	-0.0000
2:	0.0064	-0.0000	-0.0169	0
S1 =	0.0098	0.0480	0.0140	S38 =
-0.0144	0.0295	0.0102	-0.0235	0.3585
0.0119	-0.0064	-0.0356	S29 =	0.0000
0.0359	-0.0098	S20 =	0.0372	0.0000
0.0144	0.0296	0.0367	-0.0151	-0.3585
-0.0119	S11 =	-0.0175	-0.0276	-0.0000
0.0352	-0.0775	-0.0252	-0.0372	0.0000
S2 =	-0.0004	-0.0367	0.0151	S39 =
0.2797	-0.0012	0.0175	-0.0253	-0.2947
0.0039	0.0775	-0.0360	S30 =	-0.0000
0.0125	0.0004	S21 =	-0.0086	-0.0000
-0.2797	-0.0014	0.2757	-0.0087	0.2947
-0.0039	S12 =	-0.0216	-0.0141	0.0000
0.0109	0.0012	-0.0338	0.0086	-0.0000
S3 =	0.0098	-0.2757	0.0087	S40 =
-0.0086	0.0294	0.0216	-0.0165	-0.0018
0.0107	-0.0012	-0.0417	S31 =	0.0000
0.0316	-0.0098	S22 =	-0.0177	0.0000
0.0086	0.0294	-0.3072	-0.0090	0.0018
-0.0107	S13 =	-0.0149	-0.0149	-0.0000
0.0325	0.0076	-0.0029	0.0177	0.0000
S4 =	0.0070	-0.0012	0.0090	S41 =
0.0181	0.0206	0.3072	-0.0167	-0.1256
0.0105	-0.0076	0.0029	S32 =	0.0000
0.0315	-0.0070	-0.0090	0.0070	0.0000
-0.0181	0.0215	S23 =	-0.0076	0.1256
-0.0105	S14 =	-0.0373	-0.0060	-0.0000
0.0315	0.0151	-0.0015	-0.0070	0.0000
S5 =	-0.0022	0.0031	0.0076	S42 =
-0.1852	-0.0071	0.0373	-0.0206	0.0936
0.0006	-0.0151	0.0015	S33 =	0.0000
0.0026	0.0022	-0.0085	-0.0078	0.0000
0.1852	-0.0062	S24 =	-0.0050	-0.0936
-0.0006	S15 =	0.0262	-0.0031	-0.0000
0.0010	-0.0103	0.0006	0.0078	0.0000
S6 =	0.0079	0.0045	0.0050	S43 =
0.0086	0.0241	-0.0262	-0.0144	-0.1486
0.0093	0.0103	-0.0006	S34 =	0.0000
0.0281	-0.0079	-0.0024	0.0298	0.1486
-0.0086	0.0232	S25 =	-0.0084	0.0000
-0.0093	S16 =	0.1380	-0.0115	0.0000
0.0280	0.0485	0.0024	-0.0298	0.1486
S7 =	-0.0031	0.0076	0.0084	-0.0000
-0.0146	-0.0000	-0.1380	-0.0179	0
0.0093	-0.0485	-0.0024	S35 =	S44 =
0.0280	0.0031	0.0009	-0.0079	-0.0390
0.0146	-0.0107	S26 =	-0.0103	0.0000
-0.0093	S17 =	-0.0720	-0.0127	0.0000
0.0280	0.8109	-0.0104	0.0079	0.0390
S8 =	-0.0040	-0.0201	0.0103	-0.0000
-0.0045	0	0.0720	-0.0232	0.0000
-0.0003	-0.8109	0.0104	S36 =	S45 =
-0.0013	0.0040	-0.0163	0.9077	-0.0028
0.0045	-0.0140	S27 =	0	0.0000
0.0003	S18 =	-0.0279	-0.0000	0.0000
-0.0004	-0.9063	-0.0101	-0.9077	0.0028
S9 =	-0.0118	-0.0195	0	-0.0000
-0.0011	-0.0000	0.0279	-0.0000	0.0000
0.0103	0.9063	0.0101	S37 =	
0.0309	0.0118	-0.0159	-0.7194	
0.0011	-0.0413	S28 =	0.0000	
-0.0103	S19 =	0.0169	0	
0.0308	-0.0480	-0.0140	0.7194	

Lampiran 12: *Output* Gaya-gaya Batang dari *software* ETABS Kasus 2

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C O L U M N F O R C E E N V E L O P E S

STORY	COLUMN	ITEM	P	V2	V3	T	M2	M3
LT5	C5	Min Value	-0.0070	-0.0076	0.0000	0.0000	0.0000	-0.0060
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0070	-0.0076	0.0000	0.0000	0.0000	0.0206
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C6	Min Value	0.0078	-0.0050	0.0000	0.0000	0.0000	-0.0032
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0078	-0.0050	0.0000	0.0000	0.0000	0.0144
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C7	Min Value	-0.0298	-0.0084	0.0000	0.0000	0.0000	-0.0116
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0298	-0.0084	0.0000	0.0000	0.0000	0.0179
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C8	Min Value	0.0079	-0.0103	0.0000	0.0000	0.0000	-0.0127
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0079	-0.0103	0.0000	0.0000	0.0000	0.0232
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C5	Min Value	-0.0169	-0.0140	0.0000	0.0000	0.0000	-0.0255
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0169	-0.0140	0.0000	0.0000	0.0000	0.0235
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C6	Min Value	-0.0371	-0.0151	0.0000	0.0000	0.0000	-0.0275
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0371	-0.0151	0.0000	0.0000	0.0000	0.0252
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C7	Min Value	0.0086	-0.0087	0.0000	0.0000	0.0000	-0.0141
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0086	-0.0087	0.0000	0.0000	0.0000	0.0165
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C8	Min Value	0.0177	-0.0090	0.0000	0.0000	0.0000	-0.0149
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0177	-0.0090	0.0000	0.0000	0.0000	0.0167
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C5	Min Value	-0.0262	0.0006	0.0000	0.0000	0.0000	0.0025
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0262	0.0006	0.0000	0.0000	0.0000	0.0044
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C6	Min Value	-0.1379	0.0024	0.0000	0.0000	0.0000	-0.0009
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.1379	0.0024	0.0000	0.0000	0.0000	0.0076
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C7	Min Value	0.0720	-0.0104	0.0000	0.0000	0.0000	-0.0201
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0720	-0.0104	0.0000	0.0000	0.0000	0.0163
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C8	Min Value	0.0280	-0.0101	0.0000	0.0000	0.0000	-0.0195
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0280	-0.0101	0.0000	0.0000	0.0000	0.0159
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C5	Min Value	-0.0367	-0.0175	0.0000	0.0000	0.0000	-0.0252
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0367	-0.0175	0.0000	0.0000	0.0000	0.0359
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C6	Min Value	-0.2756	-0.0215	0.0000	0.0000	0.0000	-0.0337
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.2756	-0.0215	0.0000	0.0000	0.0000	0.0416
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C7	Min Value	0.3071	-0.0029	0.0000	0.0000	0.0000	-0.0013
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.3071	-0.0029	0.0000	0.0000	0.0000	0.0090
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C8	Min Value	0.0373	-0.0016	0.0000	0.0000	0.0000	0.0030
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0373	-0.0016	0.0000	0.0000	0.0000	0.0085
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C5	Min Value	-0.0485	-0.0030	0.0000	0.0000	0.0000	0.0000

		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0485	-0.0030	0.0000	0.0000	0.0000	0.0106
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C6	Min Value	-0.8108	-0.0040	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.8108	-0.0040	0.0000	0.0000	0.0000	0.0139
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C7	Min Value	0.9063	-0.0118	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.9063	-0.0118	0.0000	0.0000	0.0000	0.0412
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C8	Min Value	0.0480	-0.0101	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0480	-0.0101	0.0000	0.0000	0.0000	0.0355
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD

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B E A M F O R C E E N V E L O P E S

STORY	BEAM	ITEM	P	V2	V3	T	M2	M3
LT5	B4	Min Value	-0.0076	-0.0070	0.0000	0.0000	0.0000	-0.0206
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0076	-0.0070	0.0000	0.0000	0.0000	0.0215
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	B5	Min Value	-0.0151	0.0022	0.0000	0.0000	0.0000	-0.0062
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0151	0.0022	0.0000	0.0000	0.0000	0.0071
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	B6	Min Value	0.0103	-0.0079	0.0000	0.0000	0.0000	-0.0241
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0103	-0.0079	0.0000	0.0000	0.0000	0.0232
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	B4	Min Value	-0.0064	-0.0099	0.0000	0.0000	0.0000	-0.0295
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0064	-0.0099	0.0000	0.0000	0.0000	0.0296
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	B5	Min Value	0.0775	0.0004	0.0000	0.0000	0.0000	-0.0014
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0775	0.0004	0.0000	0.0000	0.0000	0.0012
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	B6	Min Value	-0.0012	-0.0098	0.0000	0.0000	0.0000	-0.0294
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0012	-0.0098	0.0000	0.0000	0.0000	0.0294
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	B4	Min Value	0.0146	-0.0093	0.0000	0.0000	0.0000	-0.0280
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0146	-0.0093	0.0000	0.0000	0.0000	0.0280
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	B5	Min Value	0.0045	0.0003	0.0000	0.0000	0.0000	-0.0004
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0045	0.0003	0.0000	0.0000	0.0000	0.0013
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	B6	Min Value	0.0011	-0.0103	0.0000	0.0000	0.0000	-0.0309
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0011	-0.0103	0.0000	0.0000	0.0000	0.0308
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	B4	Min Value	-0.0180	-0.0105	0.0000	0.0000	0.0000	-0.0315
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0180	-0.0105	0.0000	0.0000	0.0000	0.0315
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	B5	Min Value	0.1852	-0.0006	0.0000	0.0000	0.0000	-0.0026
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.1852	-0.0006	0.0000	0.0000	0.0000	0.0010
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	B6	Min Value	-0.0086	-0.0094	0.0000	0.0000	0.0000	-0.0281
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0086	-0.0094	0.0000	0.0000	0.0000	0.0280
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	B4	Min Value	0.0144	-0.0118	0.0000	0.0000	0.0000	-0.0359

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C O L U M N F O R C E E N V E L O P E S

STORY	COLUMN	ITEM	P	V2	V3	T	M2	M3
LT5	C5	Min Value	0.0073	0.0076	0.0000	0.0000	0.0000	-0.0215
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0073	0.0076	0.0000	0.0000	0.0000	0.0051
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C6	Min Value	-0.0056	0.0049	0.0000	0.0000	0.0000	-0.0149
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0056	0.0049	0.0000	0.0000	0.0000	0.0022
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C7	Min Value	0.0317	0.0080	0.0000	0.0000	0.0000	-0.0174
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0317	0.0080	0.0000	0.0000	0.0000	0.0104
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C8	Min Value	-0.0077	0.0099	0.0000	0.0000	0.0000	-0.0228
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0077	0.0099	0.0000	0.0000	0.0000	0.0119
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C5	Min Value	0.0178	0.0156	0.0000	0.0000	0.0000	-0.0263
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0178	0.0156	0.0000	0.0000	0.0000	0.0283
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C6	Min Value	0.0560	0.0169	0.0000	0.0000	0.0000	-0.0286
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0560	0.0169	0.0000	0.0000	0.0000	0.0307
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C7	Min Value	-0.0203	0.0103	0.0000	0.0000	0.0000	-0.0181
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0203	0.0103	0.0000	0.0000	0.0000	0.0178
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C8	Min Value	-0.0175	0.0099	0.0000	0.0000	0.0000	-0.0175
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0175	0.0099	0.0000	0.0000	0.0000	0.0170
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C5	Min Value	0.0278	-0.0007	0.0000	0.0000	0.0000	-0.0039
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0278	-0.0007	0.0000	0.0000	0.0000	-0.0016
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C6	Min Value	0.1764	-0.0024	0.0000	0.0000	0.0000	-0.0065
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.1764	-0.0024	0.0000	0.0000	0.0000	0.0018
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C7	Min Value	-0.1048	0.0048	0.0000	0.0000	0.0000	-0.0114
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.1048	0.0048	0.0000	0.0000	0.0000	0.0053
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C8	Min Value	-0.0274	0.0052	0.0000	0.0000	0.0000	-0.0126
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0274	0.0052	0.0000	0.0000	0.0000	0.0058
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C5	Min Value	0.0384	0.0212	0.0000	0.0000	0.0000	-0.0359
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0384	0.0212	0.0000	0.0000	0.0000	0.0384
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C6	Min Value	0.4561	0.0254	0.0000	0.0000	0.0000	-0.0430
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.4561	0.0254	0.0000	0.0000	0.0000	0.0458
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C7	Min Value	-0.3398	0.0221	0.0000	0.0000	0.0000	-0.0333
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.3398	0.0221	0.0000	0.0000	0.0000	0.0443
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C8	Min Value	-0.0384	0.0187	0.0000	0.0000	0.0000	-0.0274
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0384	0.0187	0.0000	0.0000	0.0000	0.0380
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C5	Min Value	0.0474	-0.0033	0.0000	0.0000	0.0000	0.0000

		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0474	-0.0033	0.0000	0.0000	0.0000	0.0114
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C6	Min Value	0.7417	-0.0032	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.7417	-0.0032	0.0000	0.0000	0.0000	0.0113
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C7	Min Value	-0.6947	-0.0040	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.6947	-0.0040	0.0000	0.0000	0.0000	0.0140
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C8	Min Value	-0.0463	-0.0041	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0463	-0.0041	0.0000	0.0000	0.0000	0.0143
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD

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B E A M F O R C E E N V E L O P E S

STORY	BEAM	ITEM	P	V2	V3	T	M2	M3
LT5	B4	Min Value	0.0076	0.0073	0.0000	0.0000	0.0000	-0.0224
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0076	0.0073	0.0000	0.0000	0.0000	0.0215
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	B5	Min Value	0.0193	-0.0023	0.0000	0.0000	0.0000	-0.0075
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0193	-0.0023	0.0000	0.0000	0.0000	0.0062
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	B6	Min Value	-0.0099	0.0077	0.0000	0.0000	0.0000	-0.0228
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0099	0.0077	0.0000	0.0000	0.0000	0.0236
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	B4	Min Value	0.0080	0.0105	0.0000	0.0000	0.0000	-0.0315
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0080	0.0105	0.0000	0.0000	0.0000	0.0315
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	B5	Min Value	-0.0950	-0.0003	0.0000	0.0000	0.0000	-0.0008
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0950	-0.0003	0.0000	0.0000	0.0000	0.0008
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	B6	Min Value	0.0000	0.0098	0.0000	0.0000	0.0000	-0.0293
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0000	0.0098	0.0000	0.0000	0.0000	0.0293
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	B4	Min Value	-0.0162	0.0100	0.0000	0.0000	0.0000	-0.0299
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0162	0.0100	0.0000	0.0000	0.0000	0.0299
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	B5	Min Value	-0.0109	-0.0002	0.0000	0.0000	0.0000	-0.0010
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0109	-0.0002	0.0000	0.0000	0.0000	0.0004
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	B6	Min Value	0.0046	0.0099	0.0000	0.0000	0.0000	-0.0296
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0046	0.0099	0.0000	0.0000	0.0000	0.0296
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	B4	Min Value	0.0219	0.0106	0.0000	0.0000	0.0000	-0.0318
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0219	0.0106	0.0000	0.0000	0.0000	0.0320
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	B5	Min Value	-0.2012	0.0017	0.0000	0.0000	0.0000	-0.0056
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.2012	0.0017	0.0000	0.0000	0.0000	0.0047
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	B6	Min Value	-0.0134	0.0110	0.0000	0.0000	0.0000	-0.0332
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0134	0.0110	0.0000	0.0000	0.0000	0.0330
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	B4	Min Value	-0.0245	0.0089	0.0000	0.0000	0.0000	-0.0267

Lampiran 13: Coding Matlab Menghitung F_U Kasus Kerusakan 3

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);

k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

E=2e8; %kN/m2
Ks=assf(K1, id1, dof);

```

```

Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);

m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);

Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(M\r\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(23, i); mode(47, i)]
v=sqrt(mode'*Mr*mode)
wm=di ag(w(1:84));
Fu3=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```

Lampiran 14: Coding Matlab Menghitung F_D Kasus Kerusakan 3

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7); %//----
-damage member ----//
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15); %//--
---damage member ----//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23); %//--
---damage member ----//

[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
Ad=A2*0.5; %//----damage
member ----//
I1=5.536e-4; %m4
I2=2.176e-4;
Id=I2*0.5; %//----damage
member ----//
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=klfs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=klfs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=klfs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=klfs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=klfs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=klfs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=klfs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=klfs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=klfs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=klfs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=klfs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=klfs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=klfs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=klfs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=klfs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=klfs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=klfs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=klfs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=klfs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=klfs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=klfs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=klfs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=klfs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=klfs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=klfs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=klfs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=klfs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=klfs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=klfs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=klfs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);

k31=klfs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=klfs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=klfs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=klfs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=klfs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=klfs(E, Ad, Id, L36, f2, vs);
K36=kg(k36, T36); %//----
damage member ----//
k37=klfs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=klfs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=klfs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=klfs(E, Ad, Id, L40, f2, vs);
K40=kg(k40, T40); %//----
damage member ----//
k41=klfs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=klfs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=klfs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=klfs(E, Ad, Id, L44, f2, vs);
K44=kg(k44, T44); %//----
damage member ----//
k45=klfs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;

id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];
id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];

```

```

id39=[ 11 12 70 20 21 71];
id40=[ 20 21 73 35 36 76];
id41=[ 23 24 74 32 33 75];
id42=[ 32 33 77 47 48 80];
id43=[ 35 36 78 44 45 79];
id44=[ 44 45 81 59 60 84];
id45=[ 47 48 82 56 57 83];

Ks=assf(K1, id1, dof);
Ks=Ks+assf(K2, id2, dof);
Ks=Ks+assf(K3, id3, dof);
Ks=Ks+assf(K4, id4, dof);
Ks=Ks+assf(K5, id5, dof);
Ks=Ks+assf(K6, id6, dof);
Ks=Ks+assf(K7, id7, dof);
Ks=Ks+assf(K8, id8, dof);
Ks=Ks+assf(K9, id9, dof);
Ks=Ks+assf(K10, id10, dof);
Ks=Ks+assf(K11, id11, dof);
Ks=Ks+assf(K12, id12, dof);
Ks=Ks+assf(K13, id13, dof);
Ks=Ks+assf(K14, id14, dof);
Ks=Ks+assf(K15, id15, dof);

Ks=Ks+assf(K16, id16, dof);
Ks=Ks+assf(K17, id17, dof);
Ks=Ks+assf(K18, id18, dof);
Ks=Ks+assf(K19, id19, dof);
Ks=Ks+assf(K20, id20, dof);
Ks=Ks+assf(K21, id21, dof);
Ks=Ks+assf(K22, id22, dof);
Ks=Ks+assf(K23, id23, dof);
Ks=Ks+assf(K24, id24, dof);
Ks=Ks+assf(K25, id25, dof);
Ks=Ks+assf(K26, id26, dof);
Ks=Ks+assf(K27, id27, dof);
Ks=Ks+assf(K28, id28, dof);
Ks=Ks+assf(K29, id29, dof);
Ks=Ks+assf(K30, id30, dof);
Ks=Ks+assf(K31, id31, dof);
Ks=Ks+assf(K32, id32, dof);
Ks=Ks+assf(K33, id33, dof);
Ks=Ks+assf(K34, id34, dof);
Ks=Ks+assf(K35, id35, dof);

Ks=Ks+assf(K36, id36, dof);
Ks=Ks+assf(K37, id37, dof);
Ks=Ks+assf(K38, id38, dof);
Ks=Ks+assf(K39, id39, dof);
Ks=Ks+assf(K40, id40, dof);
Ks=Ks+assf(K41, id41, dof);
Ks=Ks+assf(K42, id42, dof);
Ks=Ks+assf(K43, id43, dof);
Ks=Ks+assf(K44, id44, dof);
Ks=Ks+assf(K45, id45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);

m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);
m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*Ad, L36); %//----
damage member ----//
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*Ad, L40); %//----
damage member ----//
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*Ad, L44); %//----
damage member ----//
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);

M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, id1, dof);
Mr=Mr+assf(M2, id2, dof);
Mr=Mr+assf(M3, id3, dof);
Mr=Mr+assf(M4, id4, dof);
Mr=Mr+assf(M5, id5, dof);
Mr=Mr+assf(M6, id6, dof);
Mr=Mr+assf(M7, id7, dof);
Mr=Mr+assf(M8, id8, dof);
Mr=Mr+assf(M9, id9, dof);
Mr=Mr+assf(M10, id10, dof);
Mr=Mr+assf(M11, id11, dof);
Mr=Mr+assf(M12, id12, dof);
Mr=Mr+assf(M13, id13, dof);
Mr=Mr+assf(M14, id14, dof);
Mr=Mr+assf(M15, id15, dof);

Mr=Mr+assf(M16, id16, dof);
Mr=Mr+assf(M17, id17, dof);
Mr=Mr+assf(M18, id18, dof);
Mr=Mr+assf(M19, id19, dof);
Mr=Mr+assf(M20, id20, dof);
Mr=Mr+assf(M21, id21, dof);
Mr=Mr+assf(M22, id22, dof);
Mr=Mr+assf(M23, id23, dof);
Mr=Mr+assf(M24, id24, dof);
Mr=Mr+assf(M25, id25, dof);
Mr=Mr+assf(M26, id26, dof);
Mr=Mr+assf(M27, id27, dof);
Mr=Mr+assf(M28, id28, dof);
Mr=Mr+assf(M29, id29, dof);
Mr=Mr+assf(M30, id30, dof);
Mr=Mr+assf(M31, id31, dof);
Mr=Mr+assf(M32, id32, dof);
Mr=Mr+assf(M33, id33, dof);
Mr=Mr+assf(M34, id34, dof);
Mr=Mr+assf(M35, id35, dof);

Mr=Mr+assf(M36, id36, dof);
Mr=Mr+assf(M37, id37, dof);
Mr=Mr+assf(M38, id38, dof);
Mr=Mr+assf(M39, id39, dof);
Mr=Mr+assf(M40, id40, dof);
Mr=Mr+assf(M41, id41, dof);
Mr=Mr+assf(M42, id42, dof);
Mr=Mr+assf(M43, id43, dof);
Mr=Mr+assf(M44, id44, dof);
Mr=Mr+assf(M45, id45, dof);

[ei gv, ei gval]=ei g(Mr\Ks);
[w, worder]=sort(sqrt(di ag(ei
gval)))
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(23, i); mode(47, i)]
v=sqrt m(mode'*Mr*mode)
wm=di ag(w(1:84));
Fd3=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```

Lampiran 15: *Coding* Matlab Menghitung SVD Kasus Kerusakan 3

```
Fu3 =1. 0e- 004 * [0. 0583    0. 0804; 0. 0804    0. 2125]  
Fd3 =1. 0e- 004 * [0. 0650    0. 0881; 0. 0881    0. 2247]
```

```
Fdel =Fu3- Fd3  
[u, s, v]=svd(Fdel)
```



Lampiran 16: Coding Matlab Menghitung Gaya Batang Kasus Kerusakan 3

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=klfs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=klfs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=klfs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=klfs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=klfs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=klfs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=klfs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=klfs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=klfs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=klfs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=klfs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=klfs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=klfs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=klfs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=klfs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=klfs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=klfs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=klfs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=klfs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=klfs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=klfs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=klfs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=klfs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=klfs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=klfs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=klfs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=klfs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=klfs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=klfs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=klfs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=klfs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=klfs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=klfs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);

k34=klfs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=klfs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=klfs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=klfs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=klfs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=klfs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=klfs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=klfs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=klfs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=klfs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=klfs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=klfs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

E=2e8; %kN/m2
Ks=assf(K1, id1, dof);

```



```

Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);

m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);

Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(M\r\Ks);
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder);

i=1:84;
pi m=[mode(23, i); mode(47, i)];
v=sqrt(m(mode'*Mr*mode));
wm=di ag(w(1:84));
Fu3=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))';

R=zeros(84, 1);
R(23, 1)=0.8174;
R(47, 1)=-0.5760;

U=sol v(Ks, R);

u1=di ssf(U, i d1, T1);
u2=di ssf(U, i d2, T2);
u3=di ssf(U, i d3, T3);
u4=di ssf(U, i d4, T4);
u5=di ssf(U, i d5, T5);
u6=di ssf(U, i d6, T6);
u7=di ssf(U, i d7, T7);
u8=di ssf(U, i d8, T8);
u9=di ssf(U, i d9, T9);
u10=di ssf(U, i d10, T10);
u11=di ssf(U, i d11, T11);
u12=di ssf(U, i d12, T12);
u13=di ssf(U, i d13, T13);
u14=di ssf(U, i d14, T14);
u15=di ssf(U, i d15, T15);

u16=di ssf(U, i d16, T16);
u17=di ssf(U, i d17, T17);
u18=di ssf(U, i d18, T18);
u19=di ssf(U, i d19, T19);

```

u20=di ssf (U, i d20, T20) ;
 u21=di ssf (U, i d21, T21) ;
 u22=di ssf (U, i d22, T22) ;
 u23=di ssf (U, i d23, T23) ;
 u24=di ssf (U, i d24, T24) ;
 u25=di ssf (U, i d25, T25) ;
 u26=di ssf (U, i d26, T26) ;
 u27=di ssf (U, i d27, T27) ;
 u28=di ssf (U, i d28, T28) ;
 u29=di ssf (U, i d29, T29) ;
 u30=di ssf (U, i d30, T30) ;
 u31=di ssf (U, i d31, T31) ;
 u32=di ssf (U, i d32, T32) ;
 u33=di ssf (U, i d33, T33) ;
 u34=di ssf (U, i d34, T34) ;
 u35=di ssf (U, i d35, T35) ;

 u36=di ssf (U, i d36, T36) ;
 u37=di ssf (U, i d37, T37) ;
 u38=di ssf (U, i d38, T38) ;
 u39=di ssf (U, i d39, T39) ;
 u40=di ssf (U, i d40, T40) ;
 u41=di ssf (U, i d41, T41) ;
 u42=di ssf (U, i d42, T42) ;
 u43=di ssf (U, i d43, T43) ;
 u44=di ssf (U, i d44, T44) ;
 u45=di ssf (U, i d45, T45) ;

 So1=zeros (6, 1) ;
 So2=zeros (6, 1) ;
 So3=zeros (6, 1) ;
 So4=zeros (6, 1) ;
 So5=zeros (6, 1) ;
 So6=zeros (6, 1) ;
 So7=zeros (6, 1) ;
 So8=zeros (6, 1) ;
 So9=zeros (6, 1) ;
 So10=zeros (6, 1) ;
 So11=zeros (6, 1) ;
 So12=zeros (6, 1) ;
 So13=zeros (6, 1) ;
 So14=zeros (6, 1) ;
 So15=zeros (6, 1) ;
 So16=zeros (6, 1) ;
 So17=zeros (6, 1) ;
 So18=zeros (6, 1) ;
 So19=zeros (6, 1) ;
 So20=zeros (6, 1) ;
 So21=zeros (6, 1) ;
 So22=zeros (6, 1) ;
 So23=zeros (6, 1) ;
 So24=zeros (6, 1) ;
 So25=zeros (6, 1) ;
 So26=zeros (6, 1) ;
 So27=zeros (6, 1) ;
 So28=zeros (6, 1) ;
 So29=zeros (6, 1) ;
 So30=zeros (6, 1) ;
 So31=zeros (6, 1) ;
 So32=zeros (6, 1) ;
 So33=zeros (6, 1) ;
 So34=zeros (6, 1) ;
 So35=zeros (6, 1) ;
 So36=zeros (6, 1) ;
 So37=zeros (6, 1) ;
 So38=zeros (6, 1) ;
 So39=zeros (6, 1) ;
 So40=zeros (6, 1) ;
 So41=zeros (6, 1) ;
 So42=zeros (6, 1) ;
 So43=zeros (6, 1) ;
 So44=zeros (6, 1) ;
 So45=zeros (6, 1) ;

 S1=stref (k1, u1, So1)
 S2=stref (k2, u2, So2)
 S3=stref (k3, u3, So3)
 S4=stref (k4, u4, So4)
 S5=stref (k5, u5, So5)
 S6=stref (k6, u6, So6)
 S7=stref (k7, u7, So7)
 S8=stref (k8, u8, So8)
 S9=stref (k9, u9, So9)
 S10=stref (k10, u10, So10)
 S11=stref (k11, u11, So11)
 S12=stref (k12, u12, So12)
 S13=stref (k13, u13, So13)
 S14=stref (k14, u14, So14)
 S15=stref (k15, u15, So15)

 S16=stref (k16, u16, So16)
 S17=stref (k17, u17, So17)
 S18=stref (k18, u18, So18)
 S19=stref (k19, u19, So19)
 S20=stref (k20, u20, So20)
 S21=stref (k21, u21, So21)
 S22=stref (k22, u22, So22)
 S23=stref (k23, u23, So23)
 S24=stref (k24, u24, So24)
 S25=stref (k25, u25, So25)
 S26=stref (k26, u26, So26)
 S27=stref (k27, u27, So27)
 S28=stref (k28, u28, So28)
 S29=stref (k29, u29, So29)
 S30=stref (k30, u30, So30)
 S31=stref (k31, u31, So31)
 S32=stref (k32, u32, So32)
 S33=stref (k33, u33, So33)
 S34=stref (k34, u34, So34)
 S35=stref (k35, u35, So35)

 S36=stref (k36, u36, So36)
 S37=stref (k37, u37, So37)
 S38=stref (k38, u38, So38)
 S39=stref (k39, u39, So39)
 S40=stref (k40, u40, So40)
 S41=stref (k41, u41, So41)
 S42=stref (k42, u42, So42)
 S43=stref (k43, u43, So43)
 S44=stref (k44, u44, So44)
 S45=stref (k45, u45, So45)

Lampiran 17: *Output* Gaya-gaya Batang dari *software* Matlab pada Kasus Kerusakan 3

S1 =	0.0114	0.0375	-0.0228	-0.2038
-0.0049	0.0342	0.0004	S29 =	-0.0000
0.0015	-0.0024	-0.0015	0.0800	-0.0000
0.0042	-0.0114	S20 =	-0.0142	0.2038
0.0049	0.0341	0.0382	-0.0250	0.0000
-0.0015	S11 =	-0.0022	-0.0800	-0.0000
0.0045	0.1812	-0.0137	0.0142	S39 =
S2 =	0.0003	-0.0382	-0.0248	0.0575
0.0379	0.0010	0.0022	S30 =	0
-0.0019	-0.1812	0.0060	-0.1473	-0.0000
-0.0048	-0.0003	S21 =	-0.0178	-0.0575
-0.0379	0.0007	0.5173	-0.0246	0
0.0019	S12 =	-0.0011	0.1473	-0.0000
-0.0064	-0.0110	-0.0112	0.0178	S40 =
S3 =	0.0109	-0.5173	-0.0375	0.2148
-0.0086	0.0326	0.0011	S31 =	0.0000
0.0000	0.0110	0.0072	-0.0176	-0.0000
0.0002	-0.0109	S22 =	-0.0161	-0.2148
0.0086	0.0328	-0.4443	-0.0216	-0.0000
-0.0000	S13 =	0.0108	0.0176	-0.0000
-0.0001	0.0105	0.0069	0.0161	S41 =
S4 =	0.0087	0.4443	-0.0347	-0.3794
-0.0087	0.0255	-0.0108	S32 =	-0.0000
0.0069	-0.0105	0.0311	0.0087	-0.0000
0.0207	-0.0087	S23 =	-0.0105	0.3794
0.0087	0.0264	-0.0375	-0.0114	0.0000
-0.0069	S14 =	0.0082	-0.0087	-0.0000
0.0207	-0.0361	0.0016	0.0105	S42 =
S5 =	-0.0025	0.0375	-0.0255	0.3625
-0.2549	-0.0064	-0.0082	S33 =	0.0000
0.0001	0.0361	0.0270	-0.0434	-0.0000
0.0003	0.0025	S24 =	-0.0087	-0.3625
0.2549	-0.0084	0.0313	-0.0103	-0.0000
-0.0001	S15 =	-0.0109	0.0434	-0.0000
0.0000	-0.0051	-0.0268	0.0087	S43 =
S6 =	0.0068	-0.0313	-0.0200	-0.2338
0.0267	0.0208	0.0109	S34 =	0
0.0065	0.0051	-0.0115	-0.0075	-0.0000
0.0195	-0.0068	S25 =	-0.0023	0.2338
-0.0267	0.0198	0.4449	0.0042	0
-0.0065	S16 =	-0.0121	0.0075	-0.0000
0.0195	0.0396	-0.0283	0.0023	S44 =
S7 =	0.0027	-0.4449	-0.0124	0.0333
-0.0020	-0.0000	0.0121	S35 =	-0.0000
0.0112	-0.0396	-0.0141	-0.0068	-0.0000
0.0338	-0.0027	S26 =	-0.0051	-0.0333
0.0020	0.0095	-0.3622	0.0020	0.0000
-0.0112	S17 =	-0.0211	0.0068	-0.0000
0.0336	0.3361	-0.0505	0.0051	S45 =
S8 =	0.0033	0.3622	-0.0198	0.0641
0.0105	0.0000	0.0211	S36 =	0.0000
0.0023	-0.3361	-0.0235	-0.1241	0.0000
0.0055	-0.0033	S27 =	0.0000	-0.0641
-0.0105	0.0116	-0.0310	0.0000	-0.0000
-0.0023	S18 =	-0.0186	0.1241	0
0.0082	-0.3509	-0.0465	-0.0000	
S9 =	-0.0002	0.0310	0.0000	
-0.0025	0.0000	0.0186	S37 =	
0.0133	0.3509	-0.0186	0.1492	
0.0399	0.0002	S28 =	-0.0000	
0.0025	-0.0006	0.0200	-0.0000	
-0.0133	S19 =	-0.0129	-0.1492	
0.0401	-0.0375	-0.0224	0.0000	
S10 =	-0.0004	-0.0200	-0.0000	
0.0024	0.0000	0.0129	S38 =	

Lampiran 18: *Output* Gaya-gaya Batang dari *software* ETABS Kasus 3

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C O L U M N F O R C E E N V E L O P E S

STORY	COLUMN	ITEM	P	V2	V3	T	M2	M3
LT5	C5	Min Value	-0.0087	-0.0105	0.0000	0.0000	0.0000	-0.0114
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0087	-0.0105	0.0000	0.0000	0.0000	0.0255
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C6	Min Value	0.0434	-0.0087	0.0000	0.0000	0.0000	-0.0103
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0434	-0.0087	0.0000	0.0000	0.0000	0.0200
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C7	Min Value	0.0075	-0.0024	0.0000	0.0000	0.0000	0.0042
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0075	-0.0024	0.0000	0.0000	0.0000	0.0124
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C8	Min Value	0.0068	-0.0051	0.0000	0.0000	0.0000	0.0019
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0068	-0.0051	0.0000	0.0000	0.0000	0.0198
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C5	Min Value	-0.0200	-0.0129	0.0000	0.0000	0.0000	-0.0224
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0200	-0.0129	0.0000	0.0000	0.0000	0.0228
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C6	Min Value	-0.0800	-0.0142	0.0000	0.0000	0.0000	-0.0250
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0800	-0.0142	0.0000	0.0000	0.0000	0.0248
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C7	Min Value	0.1472	-0.0177	0.0000	0.0000	0.0000	-0.0246
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.1472	-0.0177	0.0000	0.0000	0.0000	0.0375
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C8	Min Value	0.0177	-0.0161	0.0000	0.0000	0.0000	-0.0216
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0177	-0.0161	0.0000	0.0000	0.0000	0.0347
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C5	Min Value	-0.0313	-0.0109	0.0000	0.0000	0.0000	-0.0268
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0313	-0.0109	0.0000	0.0000	0.0000	0.0115
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C6	Min Value	-0.4449	-0.0121	0.0000	0.0000	0.0000	-0.0283
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.4449	-0.0121	0.0000	0.0000	0.0000	0.0141
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C7	Min Value	0.3622	-0.0211	0.0000	0.0000	0.0000	-0.0505
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.3622	-0.0211	0.0000	0.0000	0.0000	0.0234
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C8	Min Value	0.0310	-0.0186	0.0000	0.0000	0.0000	-0.0464
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0310	-0.0186	0.0000	0.0000	0.0000	0.0186
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C5	Min Value	-0.0382	-0.0022	0.0000	0.0000	0.0000	-0.0137
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0382	-0.0022	0.0000	0.0000	0.0000	-0.0060
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C6	Min Value	-0.5173	-0.0012	0.0000	0.0000	0.0000	-0.0112
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.5173	-0.0012	0.0000	0.0000	0.0000	-0.0072
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C7	Min Value	0.4443	0.0108	0.0000	0.0000	0.0000	-0.0310
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.4443	0.0108	0.0000	0.0000	0.0000	0.0069
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C8	Min Value	0.0375	0.0081	0.0000	0.0000	0.0000	-0.0269
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0375	0.0081	0.0000	0.0000	0.0000	0.0016
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C5	Min Value	-0.0397	0.0027	0.0000	0.0000	0.0000	-0.0095
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0397	0.0027	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C6	Min Value	-0.3360	0.0033	0.0000	0.0000	0.0000	-0.0115
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.3360	0.0033	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C7	Min Value	0.3508	-0.0002	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.3508	-0.0002	0.0000	0.0000	0.0000	0.0006
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD

LT5	D8	Min Value	-0.0641	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0641	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT4	D7	Min Value	-0.3625	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.3625	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT4	D8	Min Value	0.2338	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.2338	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT3	D7	Min Value	-0.2148	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.2148	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT3	D8	Min Value	0.3795	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.3795	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT2	D7	Min Value	0.2039	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.2039	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT2	D8	Min Value	-0.0576	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0576	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT1	D7	Min Value	0.1241	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.1241	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT1	D8	Min Value	-0.1492	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.1492	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	

Lampiran 19: Coding Matlab Menghitung F_U Kasus Kerusakan 4

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n8);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);

k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

E=2e8; %kN/m2
Ks=assf(K1, id1, dof);

```

```

Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);

m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);

Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(M\r\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(11, i); mode(35, i); m
ode(59, i)]
v=sqrt(m(mode'*Mr*mode)
wm=di ag(w(1:84));
Fu4=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```


Lampiran 20: Coding Matlab Menghitung F_D Kasus Kerusakan 4

```

n1=coor(0,0);
n2=coor(6,0);
n3=coor(12,0);
n4=coor(18,0);

n5=coor(0,3.5);
n6=coor(6,3.5);
n7=coor(12,3.5);
n8=coor(18,3.5);

n9=coor(0,7);
n10=coor(6,7);
n11=coor(12,7);
n12=coor(18,7);

n13=coor(0,10.5);
n14=coor(6,10.5);
n15=coor(12,10.5);
n16=coor(18,10.5);

n17=coor(0,14);
n18=coor(6,14);
n19=coor(12,14);
n20=coor(18,14);

n21=coor(0,17.5);
n22=coor(6,17.5);
n23=coor(12,17.5);
n24=coor(18,17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7); %//----
-damage member ----//
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15); %//--
-damage member ----//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);

[L44, T44]=memf(n18, n23); %//--
-damage member ----//
[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
Ad=A2*0.5; %//----
-damage member ----//
I1=5.536e-4; %m4
I2=2.176e-4;
Id=I2*0.5; %//----
-damage member ----//
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=klfs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=klfs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=klfs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=klfs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=klfs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=klfs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=klfs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=klfs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=klfs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=klfs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=klfs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=klfs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=klfs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=klfs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=klfs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=klfs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=klfs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=klfs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=klfs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=klfs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=klfs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=klfs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=klfs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=klfs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=klfs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=klfs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=klfs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=klfs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);

k29=klfs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=klfs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=klfs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=klfs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=klfs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=klfs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=klfs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=klfs(E, Ad, Id, L36, f2, vs);
K36=kg(k36, T36); %//----
-damage member ----//
k37=klfs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=klfs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=klfs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=klfs(E, Ad, Id, L40, f2, vs);
K40=kg(k40, T40); %//----
-damage member ----//
k41=klfs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=klfs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=klfs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=klfs(E, Ad, Id, L44, f2, vs);
K44=kg(k44, T44); %//----
-damage member ----//
k45=klfs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];

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```

id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

Ks=assf(K1, id1, dof);
Ks=Ks+assf(K2, id2, dof);
Ks=Ks+assf(K3, id3, dof);
Ks=Ks+assf(K4, id4, dof);
Ks=Ks+assf(K5, id5, dof);
Ks=Ks+assf(K6, id6, dof);
Ks=Ks+assf(K7, id7, dof);
Ks=Ks+assf(K8, id8, dof);
Ks=Ks+assf(K9, id9, dof);
Ks=Ks+assf(K10, id10, dof);
Ks=Ks+assf(K11, id11, dof);
Ks=Ks+assf(K12, id12, dof);
Ks=Ks+assf(K13, id13, dof);
Ks=Ks+assf(K14, id14, dof);
Ks=Ks+assf(K15, id15, dof);

Ks=Ks+assf(K16, id16, dof);
Ks=Ks+assf(K17, id17, dof);
Ks=Ks+assf(K18, id18, dof);
Ks=Ks+assf(K19, id19, dof);
Ks=Ks+assf(K20, id20, dof);
Ks=Ks+assf(K21, id21, dof);
Ks=Ks+assf(K22, id22, dof);
Ks=Ks+assf(K23, id23, dof);
Ks=Ks+assf(K24, id24, dof);
Ks=Ks+assf(K25, id25, dof);
Ks=Ks+assf(K26, id26, dof);
Ks=Ks+assf(K27, id27, dof);
Ks=Ks+assf(K28, id28, dof);
Ks=Ks+assf(K29, id29, dof);
Ks=Ks+assf(K30, id30, dof);
Ks=Ks+assf(K31, id31, dof);
Ks=Ks+assf(K32, id32, dof);
Ks=Ks+assf(K33, id33, dof);
Ks=Ks+assf(K34, id34, dof);
Ks=Ks+assf(K35, id35, dof);

Ks=Ks+assf(K36, id36, dof);
Ks=Ks+assf(K37, id37, dof);
Ks=Ks+assf(K38, id38, dof);
Ks=Ks+assf(K39, id39, dof);
Ks=Ks+assf(K40, id40, dof);
Ks=Ks+assf(K41, id41, dof);
Ks=Ks+assf(K42, id42, dof);
Ks=Ks+assf(K43, id43, dof);
Ks=Ks+assf(K44, id44, dof);
Ks=Ks+assf(K45, id45, dof);

rho=8.002;

m1=mlf(rho*A2, L1);
m2=mlf(rho*A2, L2);
m3=mlf(rho*A2, L3);
m4=mlf(rho*A2, L4);
m5=mlf(rho*A2, L5);
m6=mlf(rho*A2, L6);
m7=mlf(rho*A2, L7);
m8=mlf(rho*A2, L8);
m9=mlf(rho*A2, L9);
m10=mlf(rho*A2, L10);
m11=mlf(rho*A2, L11);
m12=mlf(rho*A2, L12);
m13=mlf(rho*A2, L13);

m14=mlf(rho*A2, L14);
m15=mlf(rho*A2, L15);

m16=mlf(rho*A1, L16);
m17=mlf(rho*A1, L17);
m18=mlf(rho*A1, L18);
m19=mlf(rho*A1, L19);
m20=mlf(rho*A1, L20);
m21=mlf(rho*A1, L21);
m22=mlf(rho*A1, L22);
m23=mlf(rho*A1, L23);
m24=mlf(rho*A1, L24);
m25=mlf(rho*A1, L25);
m26=mlf(rho*A1, L26);
m27=mlf(rho*A1, L27);
m28=mlf(rho*A1, L28);
m29=mlf(rho*A1, L29);
m30=mlf(rho*A1, L30);
m31=mlf(rho*A1, L31);
m32=mlf(rho*A1, L32);
m33=mlf(rho*A1, L33);
m34=mlf(rho*A1, L34);
m35=mlf(rho*A1, L35);

m36=mlf(rho*Ad, L36); %//----
damage member ----//
m37=mlf(rho*A2, L37);
m38=mlf(rho*A2, L38);
m39=mlf(rho*A2, L39);
m40=mlf(rho*Ad, L40); %//----
damage member ----//
m41=mlf(rho*A2, L41);
m42=mlf(rho*A2, L42);
m43=mlf(rho*A2, L43);
m44=mlf(rho*Ad, L44); %//----
damage member ----//
m45=mlf(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);

M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, id1, dof);
Mr=Mr+assf(M2, id2, dof);
Mr=Mr+assf(M3, id3, dof);
Mr=Mr+assf(M4, id4, dof);
Mr=Mr+assf(M5, id5, dof);
Mr=Mr+assf(M6, id6, dof);
Mr=Mr+assf(M7, id7, dof);
Mr=Mr+assf(M8, id8, dof);
Mr=Mr+assf(M9, id9, dof);
Mr=Mr+assf(M10, id10, dof);
Mr=Mr+assf(M11, id11, dof);
Mr=Mr+assf(M12, id12, dof);
Mr=Mr+assf(M13, id13, dof);
Mr=Mr+assf(M14, id14, dof);
Mr=Mr+assf(M15, id15, dof);

Mr=Mr+assf(M16, id16, dof);
Mr=Mr+assf(M17, id17, dof);
Mr=Mr+assf(M18, id18, dof);
Mr=Mr+assf(M19, id19, dof);
Mr=Mr+assf(M20, id20, dof);
Mr=Mr+assf(M21, id21, dof);
Mr=Mr+assf(M22, id22, dof);
Mr=Mr+assf(M23, id23, dof);
Mr=Mr+assf(M24, id24, dof);
Mr=Mr+assf(M25, id25, dof);
Mr=Mr+assf(M26, id26, dof);
Mr=Mr+assf(M27, id27, dof);
Mr=Mr+assf(M28, id28, dof);
Mr=Mr+assf(M29, id29, dof);
Mr=Mr+assf(M30, id30, dof);
Mr=Mr+assf(M31, id31, dof);
Mr=Mr+assf(M32, id32, dof);
Mr=Mr+assf(M33, id33, dof);
Mr=Mr+assf(M34, id34, dof);
Mr=Mr+assf(M35, id35, dof);

Mr=Mr+assf(M36, id36, dof);
Mr=Mr+assf(M37, id37, dof);
Mr=Mr+assf(M38, id38, dof);
Mr=Mr+assf(M39, id39, dof);
Mr=Mr+assf(M40, id40, dof);
Mr=Mr+assf(M41, id41, dof);
Mr=Mr+assf(M42, id42, dof);
Mr=Mr+assf(M43, id43, dof);
Mr=Mr+assf(M44, id44, dof);
Mr=Mr+assf(M45, id45, dof);

[ei gv, ei gval]=ei g(Mr\Ks);
[w, worder]=sort(sqrt(diag(ei
gval)))
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(11, i); mode(35, i); m
ode(59, i)]
v=sqrtm(mode'*Mr*mode)
wm=diag(w(1:84));
Fd4=(pi m*i nv(v))*i nv(wm^2)*
(pi m*i nv(v))'

```

Lampiran 21: *Coding* Matlab Menghitung SVD Kasus Kerusakan 4

```
Fu4 =1. 0e- 004 * [0. 0244    0. 0279    0. 0343; 0. 0279    0. 1173    0. 1691; 0. 0343    0. 1691    0. 3553]  
Fd4 =1. 0e- 004 * [0. 0336    0. 0356    0. 0420; 0. 0356    0. 1320    0. 1818; 0. 0420    0. 1818    0. 3745]
```

```
Fdel =Fu4- Fd4  
[u, s, v]=svd(Fdel)
```



Lampiran 22: Coding Matlab Menghitung Gaya Batang Kasus Kerusakan 4

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);

k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

E=2e8; %kN/m2
Ks=assf(K1, id1, dof);

```

```

Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);

m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);

Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(M\r\Ks);
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder);

i=1:84;
pi m=[mode(11, i); mode(35, i); m
ode(59, i)];
v=sqrt m(mode'*Mr*mode);
wm=di ag(w(1:84));
Fu4=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))';

R=zeros(84, 1);
R(11, 1)=-0.5572;
R(35, 1)=0.7585;
R(59, 1)=-0.3379;

U=sol v(Ks, R);

u1=di ssf(U, i d1, T1);
u2=di ssf(U, i d2, T2);
u3=di ssf(U, i d3, T3);
u4=di ssf(U, i d4, T4);
u5=di ssf(U, i d5, T5);
u6=di ssf(U, i d6, T6);
u7=di ssf(U, i d7, T7);
u8=di ssf(U, i d8, T8);
u9=di ssf(U, i d9, T9);
u10=di ssf(U, i d10, T10);
u11=di ssf(U, i d11, T11);
u12=di ssf(U, i d12, T12);
u13=di ssf(U, i d13, T13);
u14=di ssf(U, i d14, T14);
u15=di ssf(U, i d15, T15);

u16=di ssf(U, i d16, T16);
u17=di ssf(U, i d17, T17);

```

```

u18=di ssf(U, i d18, T18);
u19=di ssf(U, i d19, T19);
u20=di ssf(U, i d20, T20);
u21=di ssf(U, i d21, T21);
u22=di ssf(U, i d22, T22);
u23=di ssf(U, i d23, T23);
u24=di ssf(U, i d24, T24);
u25=di ssf(U, i d25, T25);
u26=di ssf(U, i d26, T26);
u27=di ssf(U, i d27, T27);
u28=di ssf(U, i d28, T28);
u29=di ssf(U, i d29, T29);
u30=di ssf(U, i d30, T30);
u31=di ssf(U, i d31, T31);
u32=di ssf(U, i d32, T32);
u33=di ssf(U, i d33, T33);
u34=di ssf(U, i d34, T34);
u35=di ssf(U, i d35, T35);

u36=di ssf(U, i d36, T36);
u37=di ssf(U, i d37, T37);
u38=di ssf(U, i d38, T38);
u39=di ssf(U, i d39, T39);
u40=di ssf(U, i d40, T40);
u41=di ssf(U, i d41, T41);
u42=di ssf(U, i d42, T42);
u43=di ssf(U, i d43, T43);
u44=di ssf(U, i d44, T44);
u45=di ssf(U, i d45, T45);

So1=zeros(6, 1);
So2=zeros(6, 1);
So3=zeros(6, 1);
So4=zeros(6, 1);
So5=zeros(6, 1);
So6=zeros(6, 1);
So7=zeros(6, 1);
So8=zeros(6, 1);
So9=zeros(6, 1);
So10=zeros(6, 1);
So11=zeros(6, 1);
So12=zeros(6, 1);
So13=zeros(6, 1);
So14=zeros(6, 1);
So15=zeros(6, 1);
So16=zeros(6, 1);
So17=zeros(6, 1);
So18=zeros(6, 1);
So19=zeros(6, 1);
So20=zeros(6, 1);
So21=zeros(6, 1);
So22=zeros(6, 1);
So23=zeros(6, 1);
So24=zeros(6, 1);
So25=zeros(6, 1);
So26=zeros(6, 1);
So27=zeros(6, 1);
So28=zeros(6, 1);
So29=zeros(6, 1);
So30=zeros(6, 1);
So31=zeros(6, 1);
So32=zeros(6, 1);
So33=zeros(6, 1);
So34=zeros(6, 1);
So35=zeros(6, 1);
So36=zeros(6, 1);
So37=zeros(6, 1);
So38=zeros(6, 1);
So39=zeros(6, 1);
So40=zeros(6, 1);
So41=zeros(6, 1);
So42=zeros(6, 1);
So43=zeros(6, 1);
So44=zeros(6, 1);
So45=zeros(6, 1);

S1=stref(k1, u1, So1)
S2=stref(k2, u2, So2)
S3=stref(k3, u3, So3)
S4=stref(k4, u4, So4)
S5=stref(k5, u5, So5)
S6=stref(k6, u6, So6)
S7=stref(k7, u7, So7)
S8=stref(k8, u8, So8)
S9=stref(k9, u9, So9)
S10=stref(k10, u10, So10)
S11=stref(k11, u11, So11)
S12=stref(k12, u12, So12)
S13=stref(k13, u13, So13)
S14=stref(k14, u14, So14)
S15=stref(k15, u15, So15)

S16=stref(k16, u16, So16)
S17=stref(k17, u17, So17)
S18=stref(k18, u18, So18)
S19=stref(k19, u19, So19)
S20=stref(k20, u20, So20)
S21=stref(k21, u21, So21)
S22=stref(k22, u22, So22)
S23=stref(k23, u23, So23)
S24=stref(k24, u24, So24)
S25=stref(k25, u25, So25)
S26=stref(k26, u26, So26)
S27=stref(k27, u27, So27)
S28=stref(k28, u28, So28)
S29=stref(k29, u29, So29)
S30=stref(k30, u30, So30)
S31=stref(k31, u31, So31)
S32=stref(k32, u32, So32)
S33=stref(k33, u33, So33)
S34=stref(k34, u34, So34)
S35=stref(k35, u35, So35)

S36=stref(k36, u36, So36)
S37=stref(k37, u37, So37)
S38=stref(k38, u38, So38)
S39=stref(k39, u39, So39)
S40=stref(k40, u40, So40)
S41=stref(k41, u41, So41)
S42=stref(k42, u42, So42)
S43=stref(k43, u43, So43)
S44=stref(k44, u44, So44)
S45=stref(k45, u45, So45)

```

Lampiran 23: Output Gaya-gaya Batang dari software Matlab Kasus 4

```

S1 =          -0.0139          -0.0367          0.0070          0.0000
      0.0069          -0.0017          0.0094          -0.0130          0
      -0.0014          0.0061          0.0233          S33 =          0.2484
      -0.0044          S12 =          0.0367          0.0621          -0.0000
      -0.0069          -0.0058          -0.0094          -0.0079          0
      0.0014          0.0061          0.0097          -0.0137          S44 =
      -0.0043          0.0183          S23 =          -0.0621          0.2268
      S2 =          0.0058          -0.0078          0.0079          -0.0000
      0.1708          -0.0061          0.0077          -0.0141          -0.0000
      -0.0007          0.0185          0.0208          S34 =          -0.2268
      -0.0022          S13 =          0.0078          -0.1098          0.0000
      -0.1708          0.0070          -0.0077          -0.0074          -0.0000
      0.0007          0.0043          0.0062          -0.0096          S45 =
      -0.0022          0.0130          S24 =          0.1098          -0.1310
      S3 =          -0.0070          0.0096          0.0074          0.0000
      -0.0126          -0.0043          0.0036          -0.0164          0.0000
      -0.0013          0.0130          0.0004          S35 =          0.1310
      -0.0038          S14 =          -0.0096          -0.0049          -0.0000
      0.0126          0.1281          -0.0036          -0.0065          -0.0000
      0.0013          0.0005          0.0123          -0.0078          0.0000
      -0.0039          0.0011          S25 =          0.0049
      S4 =          -0.1281          0.2729          0.0065
      -0.0014          -0.0005          0.0050          -0.0149
      -0.0023          0.0016          0.0034          S36 =
      -0.0071          S15 =          -0.2729          0.1288
      0.0014          -0.0065          -0.0050          0.0000
      0.0023          0.0049          0.0142          0.0000
      -0.0068          0.0147          S26 =          -0.1288
      S5 =          0.0065          -0.1941          -0.0000
      0.0087          -0.0049          0.0129          0.0000
      -0.0026          0.0149          0.0118          S37 =
      -0.0065          S16 =          0.1941          -0.0136
      -0.0087          0.0058          -0.0129          0.0000
      0.0026          -0.0019          0.0333          0.0000
      -0.0089          0          S27 =          0.0136
      S6 =          -0.0058          -0.0121          -0.0000
      -0.0026          0.0019          0.0103          0.0000
      -0.0042          -0.0066          0.0067          S38 =
      -0.0126          S17 =          0.0121          -0.1663
      0.0026          -0.0999          -0.0103          -0.0000
      0.0042          -0.0019          0.0293          0.0000
      -0.0129          0.0000          S28 =          0.1663
      S7 =          0.0999          0.0087          0.0000
      -0.0083          0.0019          -0.0047          0.0000
      0.0009          -0.0066          -0.0148          S39 =
      0.0025          S18 =          -0.0087          0.2873
      0.0083          0.0426          0.0047          -0.0000
      -0.0009          -0.0049          -0.0017          0
      0.0026          0.0000          S29 =          -0.2873
      S8 =          -0.0426          0.2989          0.0000
      -0.2344          0.0049          -0.0055          0.0000
      -0.0004          -0.0173          -0.0156          S40 =
      -0.0012          S19 =          -0.2989          -0.3008
      0.2344          -0.0066          0.0055          -0.0000
      0.0004          -0.0048          -0.0035          0.0000
      -0.0011          -0.0000          S30 =          0.3008
      S9 =          0.0066          -0.2219          0.0000
      0.0225          0.0048          -0.0143          0.0000
      0.0010          -0.0169          -0.0353          S41 =
      0.0031          S20 =          0.2219          0.1493
      -0.0225          0.0072          0.0143          -0.0000
      -0.0010          0.0051          -0.0148          -0.0000
      0.0030          0.0110          S31 =          -0.1493
      S10 =          -0.0072          -0.0111          0.0000
      -0.0023          -0.0051          -0.0123          -0.0000
      0.0044          0.0068          -0.0323          S42 =
      0.0132          S21 =          0.0111          0.1003
      0.0023          -0.0237          0.0123          0.0000
      -0.0044          0.0066          -0.0107          -0.0000
      0.0131          0.0131          S32 =          -0.1003
      S11 =          0.0237          0.0043          -0.0000
      0.0139          -0.0066          -0.0070          0
      0.0017          0.0100          -0.0116          S43 =
      0.0041          S22 =          -0.0043          -0.2484

```

Lampiran 24: Coding ETABS Menghitung Gaya Batang Kasus Kerusakan 4

ETABS v9.7.0 File: CASE 4 Units: KN-m April 20, 2013 11:26 PAGE 4

C O L U M N F O R C E E N V E L O P E S

STORY	COLUMN	ITEM	P	V2	V3	T	M2	M3
LT5	C5	Min Value	-0.0043	-0.0070	0.0000	0.0000	0.0000	-0.0116
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0043	-0.0070	0.0000	0.0000	0.0000	0.0130
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C6	Min Value	-0.0621	-0.0079	0.0000	0.0000	0.0000	-0.0137
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0621	-0.0079	0.0000	0.0000	0.0000	0.0141
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C7	Min Value	0.1098	-0.0074	0.0000	0.0000	0.0000	-0.0096
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.1098	-0.0074	0.0000	0.0000	0.0000	0.0164
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C8	Min Value	0.0049	-0.0065	0.0000	0.0000	0.0000	-0.0078
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0049	-0.0065	0.0000	0.0000	0.0000	0.0149
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C5	Min Value	-0.0087	-0.0047	0.0000	0.0000	0.0000	-0.0148
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0087	-0.0047	0.0000	0.0000	0.0000	0.0017
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C6	Min Value	-0.2989	-0.0054	0.0000	0.0000	0.0000	-0.0156
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.2989	-0.0054	0.0000	0.0000	0.0000	0.0035
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C7	Min Value	0.2219	-0.0143	0.0000	0.0000	0.0000	-0.0352
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.2219	-0.0143	0.0000	0.0000	0.0000	0.0148
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C8	Min Value	0.0111	-0.0122	0.0000	0.0000	0.0000	-0.0322
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0111	-0.0122	0.0000	0.0000	0.0000	0.0107
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C5	Min Value	-0.0096	0.0036	0.0000	0.0000	0.0000	-0.0123
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0096	0.0036	0.0000	0.0000	0.0000	0.0004
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C6	Min Value	-0.2729	0.0050	0.0000	0.0000	0.0000	-0.0142
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.2729	0.0050	0.0000	0.0000	0.0000	0.0034
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C7	Min Value	0.1941	0.0129	0.0000	0.0000	0.0000	-0.0332
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.1941	0.0129	0.0000	0.0000	0.0000	0.0118
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C8	Min Value	0.0121	0.0103	0.0000	0.0000	0.0000	-0.0292
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0121	0.0103	0.0000	0.0000	0.0000	0.0067
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C5	Min Value	-0.0073	0.0051	0.0000	0.0000	0.0000	-0.0067
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0073	0.0051	0.0000	0.0000	0.0000	0.0109
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C6	Min Value	0.0237	0.0066	0.0000	0.0000	0.0000	-0.0099
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0237	0.0066	0.0000	0.0000	0.0000	0.0131
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C7	Min Value	0.0367	0.0094	0.0000	0.0000	0.0000	-0.0097
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0367	0.0094	0.0000	0.0000	0.0000	0.0232
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C8	Min Value	0.0078	0.0077	0.0000	0.0000	0.0000	-0.0062
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0078	0.0077	0.0000	0.0000	0.0000	0.0208
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C5	Min Value	-0.0058	-0.0019	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0058	-0.0019	0.0000	0.0000	0.0000	0.0066
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C6	Min Value	0.0999	-0.0019	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0999	-0.0019	0.0000	0.0000	0.0000	0.0066
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C7	Min Value	-0.0426	-0.0049	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0426	-0.0049	0.0000	0.0000	0.0000	0.0173
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD

Lampiran 25: Coding Matlab Menghitung F_U Kasus Kerusakan 5

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n8);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);

k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

E=2e8; %kN/m2
Ks=assf(K1, id1, dof);

```

```

Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);

m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);

Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(M\r\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(11, i); mode(23, i); m
ode(35, i); mode(47, i); mode(59
, i)]
v=sqrt(m(mode'*Mr*mode))
wm=di ag(w(1:84));
Fu5=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```

Lampiran 26: Coding Matlab Menghitung F_D Kasus Kerusakan 5

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7); %//----
-damage member ----//
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15); %//--
---damage member ----//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23); %//--
---damage member ----//

[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
Ad=A2*0.5; %//----damage
member ----//
I1=5.536e-4; %m4
I2=2.176e-4;
Id=I2*0.5; %//----damage
member ----//
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=klfs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=klfs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=klfs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=klfs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=klfs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=klfs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=klfs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=klfs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=klfs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=klfs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=klfs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=klfs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=klfs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=klfs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=klfs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=klfs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=klfs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=klfs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=klfs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=klfs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=klfs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=klfs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=klfs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=klfs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=klfs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=klfs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=klfs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=klfs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=klfs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=klfs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);

k31=klfs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=klfs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=klfs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=klfs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=klfs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=klfs(E, Ad, Id, L36, f2, vs);
K36=kg(k36, T36); %//----
damage member ----//
k37=klfs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=klfs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=klfs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=klfs(E, Ad, Id, L40, f2, vs);
K40=kg(k40, T40); %//----
damage member ----//
k41=klfs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=klfs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=klfs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=klfs(E, Ad, Id, L44, f2, vs);
K44=kg(k44, T44); %//----
damage member ----//
k45=klfs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;

id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];
id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];

```

```

id39=[ 11 12 70 20 21 71];
id40=[ 20 21 73 35 36 76];
id41=[ 23 24 74 32 33 75];
id42=[ 32 33 77 47 48 80];
id43=[ 35 36 78 44 45 79];
id44=[ 44 45 81 59 60 84];
id45=[ 47 48 82 56 57 83];

Ks=assf(K1, id1, dof);
Ks=Ks+assf(K2, id2, dof);
Ks=Ks+assf(K3, id3, dof);
Ks=Ks+assf(K4, id4, dof);
Ks=Ks+assf(K5, id5, dof);
Ks=Ks+assf(K6, id6, dof);
Ks=Ks+assf(K7, id7, dof);
Ks=Ks+assf(K8, id8, dof);
Ks=Ks+assf(K9, id9, dof);
Ks=Ks+assf(K10, id10, dof);
Ks=Ks+assf(K11, id11, dof);
Ks=Ks+assf(K12, id12, dof);
Ks=Ks+assf(K13, id13, dof);
Ks=Ks+assf(K14, id14, dof);
Ks=Ks+assf(K15, id15, dof);

Ks=Ks+assf(K16, id16, dof);
Ks=Ks+assf(K17, id17, dof);
Ks=Ks+assf(K18, id18, dof);
Ks=Ks+assf(K19, id19, dof);
Ks=Ks+assf(K20, id20, dof);
Ks=Ks+assf(K21, id21, dof);
Ks=Ks+assf(K22, id22, dof);
Ks=Ks+assf(K23, id23, dof);
Ks=Ks+assf(K24, id24, dof);
Ks=Ks+assf(K25, id25, dof);
Ks=Ks+assf(K26, id26, dof);
Ks=Ks+assf(K27, id27, dof);
Ks=Ks+assf(K28, id28, dof);
Ks=Ks+assf(K29, id29, dof);
Ks=Ks+assf(K30, id30, dof);
Ks=Ks+assf(K31, id31, dof);
Ks=Ks+assf(K32, id32, dof);
Ks=Ks+assf(K33, id33, dof);
Ks=Ks+assf(K34, id34, dof);
Ks=Ks+assf(K35, id35, dof);

Ks=Ks+assf(K36, id36, dof);
Ks=Ks+assf(K37, id37, dof);
Ks=Ks+assf(K38, id38, dof);
Ks=Ks+assf(K39, id39, dof);
Ks=Ks+assf(K40, id40, dof);
Ks=Ks+assf(K41, id41, dof);
Ks=Ks+assf(K42, id42, dof);
Ks=Ks+assf(K43, id43, dof);
Ks=Ks+assf(K44, id44, dof);
Ks=Ks+assf(K45, id45, dof);

rho=8.002;

m1=mlf(rho*A2, L1);
m2=mlf(rho*A2, L2);
m3=mlf(rho*A2, L3);
m4=mlf(rho*A2, L4);
m5=mlf(rho*A2, L5);
m6=mlf(rho*A2, L6);
m7=mlf(rho*A2, L7);
m8=mlf(rho*A2, L8);
m9=mlf(rho*A2, L9);
m10=mlf(rho*A2, L10);
m11=mlf(rho*A2, L11);
m12=mlf(rho*A2, L12);
m13=mlf(rho*A2, L13);
m14=mlf(rho*A2, L14);
m15=mlf(rho*A2, L15);

m16=mlf(rho*A1, L16);
m17=mlf(rho*A1, L17);
m18=mlf(rho*A1, L18);

m19=mlf(rho*A1, L19);
m20=mlf(rho*A1, L20);
m21=mlf(rho*A1, L21);
m22=mlf(rho*A1, L22);
m23=mlf(rho*A1, L23);
m24=mlf(rho*A1, L24);
m25=mlf(rho*A1, L25);
m26=mlf(rho*A1, L26);
m27=mlf(rho*A1, L27);
m28=mlf(rho*A1, L28);
m29=mlf(rho*A1, L29);
m30=mlf(rho*A1, L30);
m31=mlf(rho*A1, L31);
m32=mlf(rho*A1, L32);
m33=mlf(rho*A1, L33);
m34=mlf(rho*A1, L34);
m35=mlf(rho*A1, L35);

m36=mlf(rho*Ad, L36);%//----
damage member ----//
m37=mlf(rho*A2, L37);
m38=mlf(rho*A2, L38);
m39=mlf(rho*A2, L39);
m40=mlf(rho*Ad, L40);%//----
damage member ----//
m41=mlf(rho*A2, L41);
m42=mlf(rho*A2, L42);
m43=mlf(rho*A2, L43);
m44=mlf(rho*Ad, L44);%//----
damage member ----//
m45=mlf(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);

M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, id1, dof);
Mr=Mr+assf(M2, id2, dof);
Mr=Mr+assf(M3, id3, dof);
Mr=Mr+assf(M4, id4, dof);
Mr=Mr+assf(M5, id5, dof);
Mr=Mr+assf(M6, id6, dof);
Mr=Mr+assf(M7, id7, dof);
Mr=Mr+assf(M8, id8, dof);
Mr=Mr+assf(M9, id9, dof);
Mr=Mr+assf(M10, id10, dof);
Mr=Mr+assf(M11, id11, dof);
Mr=Mr+assf(M12, id12, dof);
Mr=Mr+assf(M13, id13, dof);
Mr=Mr+assf(M14, id14, dof);
Mr=Mr+assf(M15, id15, dof);

Mr=Mr+assf(M16, id16, dof);
Mr=Mr+assf(M17, id17, dof);
Mr=Mr+assf(M18, id18, dof);
Mr=Mr+assf(M19, id19, dof);
Mr=Mr+assf(M20, id20, dof);
Mr=Mr+assf(M21, id21, dof);
Mr=Mr+assf(M22, id22, dof);
Mr=Mr+assf(M23, id23, dof);
Mr=Mr+assf(M24, id24, dof);
Mr=Mr+assf(M25, id25, dof);
Mr=Mr+assf(M26, id26, dof);
Mr=Mr+assf(M27, id27, dof);
Mr=Mr+assf(M28, id28, dof);
Mr=Mr+assf(M29, id29, dof);
Mr=Mr+assf(M30, id30, dof);
Mr=Mr+assf(M31, id31, dof);
Mr=Mr+assf(M32, id32, dof);
Mr=Mr+assf(M33, id33, dof);
Mr=Mr+assf(M34, id34, dof);
Mr=Mr+assf(M35, id35, dof);

Mr=Mr+assf(M36, id36, dof);
Mr=Mr+assf(M37, id37, dof);
Mr=Mr+assf(M38, id38, dof);
Mr=Mr+assf(M39, id39, dof);
Mr=Mr+assf(M40, id40, dof);
Mr=Mr+assf(M41, id41, dof);
Mr=Mr+assf(M42, id42, dof);
Mr=Mr+assf(M43, id43, dof);
Mr=Mr+assf(M44, id44, dof);
Mr=Mr+assf(M45, id45, dof);

[ei gv, ei gval]=eig(M\r\Ks);
[w, worder]=sort(sqrt(diag(ei
gval)))
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(11, i); mode(23, i); m
ode(35, i); mode(47, i); mode(59
, i)]
v=sqrtm(mode'*Mr*mode)
wm=diag(w(1:84));
Fd5=(pi m*inv(v))*inv(wm^2)*(
pi m*inv(v))'

```

Lampiran 27: Coding Matlab Menghitung SVD Kasus Kerusakan 5

```
Fu5 =1.0e-004 * [0.0244    0.0239    0.0279    0.0311    0.0343; 0.0239    0.0583  
0.0674    0.0804    0.0924; 0.0279    0.0674    0.1173    0.1414    0.1691; 0.0311  
0.0804    0.1414    0.2125    0.2567; 0.0343    0.0924    0.1691    0.2567    0.3553]  
  
Fd5 =1.0e-004 * [0.0336    0.0316    0.0356    0.0389    0.0420; 0.0316    0.0650  
0.0752    0.0881    0.0999; 0.0356    0.0752    0.1320    0.1547    0.1818; 0.0389  
0.0881    0.1547    0.2247    0.2694; 0.0420    0.0999    0.1818    0.2694    0.3745]  
  
Fdel =Fu5- Fd5  
[u, s, v]=svd(Fdel)
```



Lampiran 28: Coding Matlab Menghitung Gaya Batang Kasus Kerusakan 5

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);

k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

E=2e8; %kN/m2
Ks=assf(K1, id1, dof);

```



```

Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);

m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);

Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(M\r\Ks);
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder);

i=1:84;
pi m=[mode(11, i); mode(23, i); m
ode(35, i); mode(47, i); mode(59
, i)];
v=sqrtm(mode'*Mr*mode);
wm=di ag(w(1:84));
Fu5=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))';

R=zeros(84, 1);
R(11, 1)=0.5532;
R(23, 1)=-0.7414;
R(35, 1)=0.2930;
R(47, 1)=-0.2397;
R(59, 1)=0.0325;

U=sol v(Ks, R);

u1=di ssf(U, i d1, T1);
u2=di ssf(U, i d2, T2);
u3=di ssf(U, i d3, T3);
u4=di ssf(U, i d4, T4);
u5=di ssf(U, i d5, T5);
u6=di ssf(U, i d6, T6);
u7=di ssf(U, i d7, T7);
u8=di ssf(U, i d8, T8);
u9=di ssf(U, i d9, T9);
u10=di ssf(U, i d10, T10);
u11=di ssf(U, i d11, T11);
u12=di ssf(U, i d12, T12);
u13=di ssf(U, i d13, T13);
u14=di ssf(U, i d14, T14);
u15=di ssf(U, i d15, T15);

```

```

u16=di ssf(U, i d16, T16);
u17=di ssf(U, i d17, T17);
u18=di ssf(U, i d18, T18);
u19=di ssf(U, i d19, T19);
u20=di ssf(U, i d20, T20);
u21=di ssf(U, i d21, T21);
u22=di ssf(U, i d22, T22);
u23=di ssf(U, i d23, T23);
u24=di ssf(U, i d24, T24);
u25=di ssf(U, i d25, T25);
u26=di ssf(U, i d26, T26);
u27=di ssf(U, i d27, T27);
u28=di ssf(U, i d28, T28);
u29=di ssf(U, i d29, T29);
u30=di ssf(U, i d30, T30);
u31=di ssf(U, i d31, T31);
u32=di ssf(U, i d32, T32);
u33=di ssf(U, i d33, T33);
u34=di ssf(U, i d34, T34);
u35=di ssf(U, i d35, T35);

u36=di ssf(U, i d36, T36);
u37=di ssf(U, i d37, T37);
u38=di ssf(U, i d38, T38);
u39=di ssf(U, i d39, T39);
u40=di ssf(U, i d40, T40);
u41=di ssf(U, i d41, T41);
u42=di ssf(U, i d42, T42);
u43=di ssf(U, i d43, T43);
u44=di ssf(U, i d44, T44);
u45=di ssf(U, i d45, T45);

So1=zeros(6, 1);
So2=zeros(6, 1);
So3=zeros(6, 1);
So4=zeros(6, 1);
So5=zeros(6, 1);
So6=zeros(6, 1);
So7=zeros(6, 1);
So8=zeros(6, 1);
So9=zeros(6, 1);
So10=zeros(6, 1);
So11=zeros(6, 1);
So12=zeros(6, 1);
So13=zeros(6, 1);
So14=zeros(6, 1);
So15=zeros(6, 1);
So16=zeros(6, 1);
So17=zeros(6, 1);
So18=zeros(6, 1);
So19=zeros(6, 1);
So20=zeros(6, 1);
So21=zeros(6, 1);
So22=zeros(6, 1);
So23=zeros(6, 1);
So24=zeros(6, 1);
So25=zeros(6, 1);
So26=zeros(6, 1);
So27=zeros(6, 1);
So28=zeros(6, 1);
So29=zeros(6, 1);
So30=zeros(6, 1);
So31=zeros(6, 1);
So32=zeros(6, 1);
So33=zeros(6, 1);
So34=zeros(6, 1);
So35=zeros(6, 1);
So36=zeros(6, 1);
So37=zeros(6, 1);
So38=zeros(6, 1);
So39=zeros(6, 1);
So40=zeros(6, 1);
So41=zeros(6, 1);
So42=zeros(6, 1);
So43=zeros(6, 1);
So44=zeros(6, 1);

So45=zeros(6, 1);

S1=stref(k1, u1, So1)
S2=stref(k2, u2, So2)
S3=stref(k3, u3, So3)
S4=stref(k4, u4, So4)
S5=stref(k5, u5, So5)
S6=stref(k6, u6, So6)
S7=stref(k7, u7, So7)
S8=stref(k8, u8, So8)
S9=stref(k9, u9, So9)
S10=stref(k10, u10, So10)
S11=stref(k11, u11, So11)
S12=stref(k12, u12, So12)
S13=stref(k13, u13, So13)
S14=stref(k14, u14, So14)
S15=stref(k15, u15, So15)

S16=stref(k16, u16, So16)
S17=stref(k17, u17, So17)
S18=stref(k18, u18, So18)
S19=stref(k19, u19, So19)
S20=stref(k20, u20, So20)
S21=stref(k21, u21, So21)
S22=stref(k22, u22, So22)
S23=stref(k23, u23, So23)
S24=stref(k24, u24, So24)
S25=stref(k25, u25, So25)
S26=stref(k26, u26, So26)
S27=stref(k27, u27, So27)
S28=stref(k28, u28, So28)
S29=stref(k29, u29, So29)
S30=stref(k30, u30, So30)
S31=stref(k31, u31, So31)
S32=stref(k32, u32, So32)
S33=stref(k33, u33, So33)
S34=stref(k34, u34, So34)
S35=stref(k35, u35, So35)

S36=stref(k36, u36, So36)
S37=stref(k37, u37, So37)
S38=stref(k38, u38, So38)
S39=stref(k39, u39, So39)
S40=stref(k40, u40, So40)
S41=stref(k41, u41, So41)
S42=stref(k42, u42, So42)
S43=stref(k43, u43, So43)
S44=stref(k44, u44, So44)
S45=stref(k45, u45, So45)

```

Lampiran 29: Output Gaya-gaya Batang dari software Matlab Kasus 5

S1 =	-0.0950	-0.1982	0.0058	0.0000
-0.0066	-0.0000	-0.0295	-0.0119	0.0000
0.0041	0.0006	-0.0501	S33 =	0.1142
0.0126	S12 =	0.1982	-0.0289	-0.0000
0.0066	-0.0135	0.0295	-0.0051	0.0000
-0.0041	0.0055	-0.0530	-0.0084	S44 =
0.0123	0.0166	S23 =	0.0289	-0.0030
S2 =	0.0135	-0.0180	0.0051	0.0000
-0.2078	-0.0055	-0.0247	-0.0093	0
0.0018	0.0165	-0.0420	S34 =	0.0030
0.0043	S13 =	0.0180	0.0056	-0.0000
0.2078	0.0058	0.0247	0.0012	0
-0.0018	0.0041	-0.0444	0.0081	S45 =
0.0064	0.0119	S24 =	-0.0056	0.0468
S3 =	-0.0058	0.0137	-0.0012	0.0000
0.0317	-0.0041	-0.0057	-0.0039	0.0000
0.0059	0.0124	-0.0084	S35 =	-0.0468
0.0177	S14 =	-0.0137	-0.0028	-0.0000
-0.0317	-0.0296	0.0057	-0.0009	0.0000
-0.0059	-0.0013	-0.0117	0.0051	0.0000
0.0177	-0.0031	S25 =	0.0028	
S4 =	0.0296	0.0167	0.0009	
0.0006	0.0013	-0.0060	-0.0081	
0.0057	-0.0046	-0.0091	S36 =	
0.0171	S15 =	-0.0167	-0.0023	
-0.0006	-0.0009	0.0060	-0.0000	
-0.0057	0.0028	-0.0118	-0.0000	
0.0170	0.0085	S26 =	0.0023	
S5 =	0.0009	-0.0635	0.0000	
0.2729	-0.0028	0.0159	-0.0000	
0.0010	0.0081	0.0324	S37 =	
0.0030	S16 =	0.0635	-0.1377	
-0.2729	0.0235	-0.0159	0.0000	
-0.0010	0.0002	0.0232	-0.0000	
0.0032	-0.0000	S27 =	0.1377	
S6 =	-0.0235	-0.0122	-0.0000	
-0.0373	-0.0002	0.0126	-0.0000	
0.0058	0.0008	0.0269	S38 =	
0.0174	S17 =	0.0122	0.3618	
0.0373	0.4242	-0.0126	0.0000	
-0.0058	-0.0001	0.0171	-0.0000	
0.0176	-0.0000	S28 =	-0.3618	
S7 =	-0.4242	0.0087	-0.0000	
0.0032	0.0001	-0.0025	0	
0.0050	-0.0003	-0.0034	S39 =	
0.0151	S18 =	-0.0087	-0.3182	
-0.0032	-0.3533	0.0025	0.0000	
-0.0050	0.0074	-0.0053	0.0000	
0.0151	0.0000	S29 =	0.3182	
S8 =	0.3533	0.0225	-0.0000	
-0.1392	-0.0074	-0.0021	-0.0000	
-0.0005	0.0260	-0.0025	S40 =	
-0.0008	S19 =	-0.0225	0.0049	
0.1392	-0.0239	0.0021	0.0000	
0.0005	0.0070	-0.0049	0.0000	
-0.0020	-0.0000	S30 =	-0.0049	
S9 =	0.0239	-0.0078	-0.0000	
0.0270	-0.0070	-0.0166	0.0000	
0.0039	0.0243	-0.0329	S41 =	
0.0117	S20 =	0.0078	0.0849	
-0.0270	0.0194	0.0166	-0.0000	
-0.0039	-0.0063	-0.0253	-0.0000	
0.0118	-0.0134	S31 =	-0.0849	
S10 =	-0.0194	-0.0083	0.0000	
-0.0033	0.0063	-0.0144	-0.0000	
0.0046	-0.0087	-0.0288	S42 =	
0.0139	S21 =	0.0083	0.0844	
0.0033	0.1749	0.0144	0.0000	
-0.0046	-0.0077	-0.0216	0.0000	
0.0138	-0.0163	S32 =	-0.0844	
S11 =	-0.1749	0.0041	-0.0000	
0.0950	0.0077	-0.0058	0.0000	
0.0000	-0.0108	-0.0085	S43 =	
-0.0005	S22 =	-0.0041	-0.1142	

Lampiran 30: *Output* Gaya-gaya Batang dari *software* ETABS Kasus 5

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C O L U M N F O R C E E N V E L O P E S

STORY	COLUMN	ITEM	P	V2	V3	T	M2	M3
LT5	C5	Min Value	-0.0041	-0.0058	0.0000	0.0000	0.0000	-0.0085
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0041	-0.0058	0.0000	0.0000	0.0000	0.0119
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C6	Min Value	0.0290	-0.0051	0.0000	0.0000	0.0000	-0.0084
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0290	-0.0051	0.0000	0.0000	0.0000	0.0093
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C7	Min Value	-0.0056	0.0012	0.0000	0.0000	0.0000	0.0039
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0056	0.0012	0.0000	0.0000	0.0000	0.0081
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C8	Min Value	0.0028	-0.0009	0.0000	0.0000	0.0000	0.0051
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0028	-0.0009	0.0000	0.0000	0.0000	0.0081
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C5	Min Value	-0.0087	-0.0025	0.0000	0.0000	0.0000	-0.0034
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0087	-0.0025	0.0000	0.0000	0.0000	0.0053
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C6	Min Value	-0.0225	-0.0021	0.0000	0.0000	0.0000	-0.0026
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0225	-0.0021	0.0000	0.0000	0.0000	0.0049
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C7	Min Value	0.0078	-0.0166	0.0000	0.0000	0.0000	-0.0329
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0078	-0.0166	0.0000	0.0000	0.0000	0.0252
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C8	Min Value	0.0083	-0.0144	0.0000	0.0000	0.0000	-0.0288
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0083	-0.0144	0.0000	0.0000	0.0000	0.0216
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C5	Min Value	-0.0137	-0.0057	0.0000	0.0000	0.0000	-0.0084
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0137	-0.0057	0.0000	0.0000	0.0000	0.0116
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C6	Min Value	-0.0167	-0.0060	0.0000	0.0000	0.0000	-0.0091
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0167	-0.0060	0.0000	0.0000	0.0000	0.0118
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C7	Min Value	0.0634	0.0158	0.0000	0.0000	0.0000	-0.0231
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0634	0.0158	0.0000	0.0000	0.0000	0.0323
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C8	Min Value	0.0122	0.0125	0.0000	0.0000	0.0000	-0.0170
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0122	0.0125	0.0000	0.0000	0.0000	0.0268
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C5	Min Value	-0.0194	-0.0063	0.0000	0.0000	0.0000	-0.0134
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0194	-0.0063	0.0000	0.0000	0.0000	0.0087
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C6	Min Value	-0.1749	-0.0077	0.0000	0.0000	0.0000	-0.0163
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.1749	-0.0077	0.0000	0.0000	0.0000	0.0108
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C7	Min Value	0.1982	-0.0294	0.0000	0.0000	0.0000	-0.0500
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.1982	-0.0294	0.0000	0.0000	0.0000	0.0529
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C8	Min Value	0.0180	-0.0247	0.0000	0.0000	0.0000	-0.0420
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0180	-0.0247	0.0000	0.0000	0.0000	0.0444
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C5	Min Value	-0.0235	0.0002	0.0000	0.0000	0.0000	-0.0009
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0235	0.0002	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C6	Min Value	-0.4242	-0.0001	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.4242	-0.0001	0.0000	0.0000	0.0000	0.0003
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C7	Min Value	0.3533	0.0074	0.0000	0.0000	0.0000	-0.0260
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.3533	0.0074	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD

Lampiran 31: Coding Matlab Menghitung F_U Kasus Kerusakan 6

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n8);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);

k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

E=2e8; %kN/m2
Ks=assf(K1, id1, dof);

```

```

Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);

m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);

Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(M\r\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(20, i); mode(23, i); m
ode(32, i); mode(35, i); mode(44
, i); mode(47, i)]
v=sqrt(m(mode'*Mr*mode))
wm=di ag(w(1:84));
Fu6=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```


Lampiran 32: Coding Matlab Menghitung F_D Kasus Kerusakan 6

```

n1=coor(0,0);
n2=coor(6,0);
n3=coor(12,0);
n4=coor(18,0);

n5=coor(0,3.5);
n6=coor(6,3.5);
n7=coor(12,3.5);
n8=coor(18,3.5);

n9=coor(0,7);
n10=coor(6,7);
n11=coor(12,7);
n12=coor(18,7);

n13=coor(0,10.5);
n14=coor(6,10.5);
n15=coor(12,10.5);
n16=coor(18,10.5);

n17=coor(0,14);
n18=coor(6,14);
n19=coor(12,14);
n20=coor(18,14);

n21=coor(0,17.5);
n22=coor(6,17.5);
n23=coor(12,17.5);
n24=coor(18,17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7); %//----
-damage member ----//
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15); %//--
-damage member ----//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);

[L44, T44]=memf(n18, n23); %//--
-damage member ----//
[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
Ad=A2*0.5; %//----damage
member ----//
I1=5.536e-4; %m4
I2=2.176e-4;
Id=I2*0.5; %//----damage
member ----//
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=klfs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=klfs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=klfs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=klfs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=klfs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=klfs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=klfs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=klfs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=klfs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=klfs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=klfs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=klfs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=klfs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=klfs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=klfs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=klfs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=klfs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=klfs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=klfs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=klfs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=klfs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=klfs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=klfs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=klfs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=klfs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=klfs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=klfs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=klfs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);

k29=klfs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=klfs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=klfs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=klfs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=klfs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=klfs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=klfs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=klfs(E, Ad, Id, L36, f2, vs);
K36=kg(k36, T36); %//----
-damage member ----//
k37=klfs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=klfs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=klfs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=klfs(E, Ad, Id, L40, f2, vs);
K40=kg(k40, T40); %//----
-damage member ----//
k41=klfs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=klfs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=klfs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=klfs(E, Ad, Id, L44, f2, vs);
K44=kg(k44, T44); %//----
-damage member ----//
k45=klfs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];

```

```

id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

Ks=assf(K1, id1, dof);
Ks=Ks+assf(K2, id2, dof);
Ks=Ks+assf(K3, id3, dof);
Ks=Ks+assf(K4, id4, dof);
Ks=Ks+assf(K5, id5, dof);
Ks=Ks+assf(K6, id6, dof);
Ks=Ks+assf(K7, id7, dof);
Ks=Ks+assf(K8, id8, dof);
Ks=Ks+assf(K9, id9, dof);
Ks=Ks+assf(K10, id10, dof);
Ks=Ks+assf(K11, id11, dof);
Ks=Ks+assf(K12, id12, dof);
Ks=Ks+assf(K13, id13, dof);
Ks=Ks+assf(K14, id14, dof);
Ks=Ks+assf(K15, id15, dof);

Ks=Ks+assf(K16, id16, dof);
Ks=Ks+assf(K17, id17, dof);
Ks=Ks+assf(K18, id18, dof);
Ks=Ks+assf(K19, id19, dof);
Ks=Ks+assf(K20, id20, dof);
Ks=Ks+assf(K21, id21, dof);
Ks=Ks+assf(K22, id22, dof);
Ks=Ks+assf(K23, id23, dof);
Ks=Ks+assf(K24, id24, dof);
Ks=Ks+assf(K25, id25, dof);
Ks=Ks+assf(K26, id26, dof);
Ks=Ks+assf(K27, id27, dof);
Ks=Ks+assf(K28, id28, dof);
Ks=Ks+assf(K29, id29, dof);
Ks=Ks+assf(K30, id30, dof);
Ks=Ks+assf(K31, id31, dof);
Ks=Ks+assf(K32, id32, dof);
Ks=Ks+assf(K33, id33, dof);
Ks=Ks+assf(K34, id34, dof);
Ks=Ks+assf(K35, id35, dof);

Ks=Ks+assf(K36, id36, dof);
Ks=Ks+assf(K37, id37, dof);
Ks=Ks+assf(K38, id38, dof);
Ks=Ks+assf(K39, id39, dof);
Ks=Ks+assf(K40, id40, dof);
Ks=Ks+assf(K41, id41, dof);
Ks=Ks+assf(K42, id42, dof);
Ks=Ks+assf(K43, id43, dof);
Ks=Ks+assf(K44, id44, dof);
Ks=Ks+assf(K45, id45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);

m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);
m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*Ad, L36); %//----
damage member ----//
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*Ad, L40); %//----
damage member ----//
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*Ad, L44); %//----
damage member ----//
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);

M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, id1, dof);
Mr=Mr+assf(M2, id2, dof);
Mr=Mr+assf(M3, id3, dof);
Mr=Mr+assf(M4, id4, dof);
Mr=Mr+assf(M5, id5, dof);
Mr=Mr+assf(M6, id6, dof);
Mr=Mr+assf(M7, id7, dof);
Mr=Mr+assf(M8, id8, dof);
Mr=Mr+assf(M9, id9, dof);
Mr=Mr+assf(M10, id10, dof);
Mr=Mr+assf(M11, id11, dof);
Mr=Mr+assf(M12, id12, dof);
Mr=Mr+assf(M13, id13, dof);
Mr=Mr+assf(M14, id14, dof);
Mr=Mr+assf(M15, id15, dof);

Mr=Mr+assf(M16, id16, dof);
Mr=Mr+assf(M17, id17, dof);
Mr=Mr+assf(M18, id18, dof);
Mr=Mr+assf(M19, id19, dof);
Mr=Mr+assf(M20, id20, dof);
Mr=Mr+assf(M21, id21, dof);
Mr=Mr+assf(M22, id22, dof);
Mr=Mr+assf(M23, id23, dof);
Mr=Mr+assf(M24, id24, dof);
Mr=Mr+assf(M25, id25, dof);
Mr=Mr+assf(M26, id26, dof);
Mr=Mr+assf(M27, id27, dof);
Mr=Mr+assf(M28, id28, dof);
Mr=Mr+assf(M29, id29, dof);
Mr=Mr+assf(M30, id30, dof);
Mr=Mr+assf(M31, id31, dof);
Mr=Mr+assf(M32, id32, dof);
Mr=Mr+assf(M33, id33, dof);
Mr=Mr+assf(M34, id34, dof);
Mr=Mr+assf(M35, id35, dof);

Mr=Mr+assf(M36, id36, dof);
Mr=Mr+assf(M37, id37, dof);
Mr=Mr+assf(M38, id38, dof);
Mr=Mr+assf(M39, id39, dof);
Mr=Mr+assf(M40, id40, dof);
Mr=Mr+assf(M41, id41, dof);
Mr=Mr+assf(M42, id42, dof);
Mr=Mr+assf(M43, id43, dof);
Mr=Mr+assf(M44, id44, dof);
Mr=Mr+assf(M45, id45, dof);

[ei gv, ei gval]=ei g(Mr\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(20, i); mode(23, i); m
ode(32, i); mode(35, i); mode(44
, i); mode(47, i)]
v=sqrt(m(mode'*Mr*mode)
wm=di ag(w(1:84));
Fd6=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```

Lampiran 33: *Coding* Matlab Menghitung SVD Kasus Kerusakan 6

```
Fu6=1.0e-004 * [0.0583    0.0505    0.0674    0.0685    0.0804    0.0803; 0.0505  
0.0583    0.0685    0.0674    0.0803    0.0804; 0.0674    0.0685    0.1173    0.1095  
0.1414    0.1426; 0.0685    0.0674    0.1095    0.1173    0.1426    0.1414; 0.0804  
0.0803    0.1414    0.1426    0.2125    0.2045; 0.0803    0.0804    0.1426    0.1414  
0.2045    0.2125]
```

```
Fd6 =1.0e-004 * [0.0657    0.0572    0.0736    0.0744    0.0865    0.0864; 0.0572  
0.0650    0.0760    0.0752    0.0881    0.0881; 0.0736    0.0760    0.1280    0.1218  
0.1531    0.1539; 0.0744    0.0752    0.1218    0.1320    0.1564    0.1547; 0.0865  
0.0881    0.1531    0.1564    0.2257    0.2170; 0.0864    0.0881    0.1539    0.1547  
0.2170    0.2247]
```

```
Fdel =Fu6- Fd6  
[u, s, v]=svd(Fdel)
```



Lampiran 34: Coding Matlab Menghitung Gaya Batang Kasus Kerusakan 6

```

n1=coor(0,0);
n2=coor(6,0);
n3=coor(12,0);
n4=coor(18,0);

n5=coor(0,3.5);
n6=coor(6,3.5);
n7=coor(12,3.5);
n8=coor(18,3.5);

n9=coor(0,7);
n10=coor(6,7);
n11=coor(12,7);
n12=coor(18,7);

n13=coor(0,10.5);
n14=coor(6,10.5);
n15=coor(12,10.5);
n16=coor(18,10.5);

n17=coor(0,14);
n18=coor(6,14);
n19=coor(12,14);
n20=coor(18,14);

n21=coor(0,17.5);
n22=coor(6,17.5);
n23=coor(12,17.5);
n24=coor(18,17.5);

[L1,T1]=memf(n5,n6);
[L2,T2]=memf(n6,n7);
[L3,T3]=memf(n7,n8);
[L4,T4]=memf(n9,n10);
[L5,T5]=memf(n10,n11);
[L6,T6]=memf(n11,n12);
[L7,T7]=memf(n13,n14);
[L8,T8]=memf(n14,n15);
[L9,T9]=memf(n15,n16);
[L10,T10]=memf(n17,n18);
[L11,T11]=memf(n18,n19);
[L12,T12]=memf(n19,n20);
[L13,T13]=memf(n21,n22);
[L14,T14]=memf(n22,n23);
[L15,T15]=memf(n23,n24);
[L16,T16]=memf(n1,n5);
[L17,T17]=memf(n2,n6);
[L18,T18]=memf(n3,n7);
[L19,T19]=memf(n4,n8);
[L20,T20]=memf(n5,n9);
[L21,T21]=memf(n6,n10);
[L22,T22]=memf(n7,n11);
[L23,T23]=memf(n8,n12);
[L24,T24]=memf(n9,n13);
[L25,T25]=memf(n10,n14);
[L26,T26]=memf(n11,n15);
[L27,T27]=memf(n12,n16);
[L28,T28]=memf(n13,n17);
[L29,T29]=memf(n14,n18);
[L30,T30]=memf(n15,n19);
[L31,T31]=memf(n16,n20);
[L32,T32]=memf(n17,n21);
[L33,T33]=memf(n18,n22);
[L34,T34]=memf(n19,n23);
[L35,T35]=memf(n20,n24);
[L36,T36]=memf(n2,n7);%//---
-damage member ----//
[L37,T37]=memf(n3,n6);
[L38,T38]=memf(n6,n11);
[L39,T39]=memf(n7,n10);
[L40,T40]=memf(n10,n15);%//--
---damage member ----//
[L41,T41]=memf(n11,n14);
[L42,T42]=memf(n14,n19);
[L43,T43]=memf(n15,n18);
[L44,T44]=memf(n18,n23);%//--
---damage member ----//

[L45,T45]=memf(n19,n22);

E=2e8;%kN/m2
A1=0.0144;%m2%Kolom
A2=0.0121;%Balok dan bracing
I1=5.536e-4;%m4
I2=2.176e-4;
r=78.5;%kN/m3
vs=0.3;
f1=2.884;%Kolom
f2=3.975;%Balok dan bracing

k1=klfs(E,A2,I2,L1,f2,vs);
K1=kg(k1,T1);
k2=klfs(E,A2,I2,L2,f2,vs);
K2=kg(k2,T2);
k3=klfs(E,A2,I2,L3,f2,vs);
K3=kg(k3,T3);
k4=klfs(E,A2,I2,L4,f2,vs);
K4=kg(k4,T4);
k5=klfs(E,A2,I2,L5,f2,vs);
K5=kg(k5,T5);
k6=klfs(E,A2,I2,L6,f2,vs);
K6=kg(k6,T6);
k7=klfs(E,A2,I2,L7,f2,vs);
K7=kg(k7,T7);
k8=klfs(E,A2,I2,L8,f2,vs);
K8=kg(k8,T8);
k9=klfs(E,A2,I2,L9,f2,vs);
K9=kg(k9,T9);
k10=klfs(E,A2,I2,L10,f2,vs);
K10=kg(k10,T10);
k11=klfs(E,A2,I2,L11,f2,vs);
K11=kg(k11,T11);
k12=klfs(E,A2,I2,L12,f2,vs);
K12=kg(k12,T12);
k13=klfs(E,A2,I2,L13,f2,vs);
K13=kg(k13,T13);
k14=klfs(E,A2,I2,L14,f2,vs);
K14=kg(k14,T14);
k15=klfs(E,A2,I2,L15,f2,vs);
K15=kg(k15,T15);

k16=klfs(E,A1,I1,L16,f1,vs);
K16=kg(k16,T16);
k17=klfs(E,A1,I1,L17,f1,vs);
K17=kg(k17,T17);
k18=klfs(E,A1,I1,L18,f1,vs);
K18=kg(k18,T18);
k19=klfs(E,A1,I1,L19,f1,vs);
K19=kg(k19,T19);
k20=klfs(E,A1,I1,L20,f1,vs);
K20=kg(k20,T20);
k21=klfs(E,A1,I1,L21,f1,vs);
K21=kg(k21,T21);
k22=klfs(E,A1,I1,L22,f1,vs);
K22=kg(k22,T22);
k23=klfs(E,A1,I1,L23,f1,vs);
K23=kg(k23,T23);
k24=klfs(E,A1,I1,L24,f1,vs);
K24=kg(k24,T24);
k25=klfs(E,A1,I1,L25,f1,vs);
K25=kg(k25,T25);
k26=klfs(E,A1,I1,L26,f1,vs);
K26=kg(k26,T26);
k27=klfs(E,A1,I1,L27,f1,vs);
K27=kg(k27,T27);
k28=klfs(E,A1,I1,L28,f1,vs);
K28=kg(k28,T28);
k29=klfs(E,A1,I1,L29,f1,vs);
K29=kg(k29,T29);
k30=klfs(E,A1,I1,L30,f1,vs);
K30=kg(k30,T30);
k31=klfs(E,A1,I1,L31,f1,vs);
K31=kg(k31,T31);
k32=klfs(E,A1,I1,L32,f1,vs);
K32=kg(k32,T32);

k33=klfs(E,A1,I1,L33,f1,vs);
K33=kg(k33,T33);
k34=klfs(E,A1,I1,L34,f1,vs);
K34=kg(k34,T34);
k35=klfs(E,A1,I1,L35,f1,vs);
K35=kg(k35,T35);

k36=klfs(E,A2,I2,L36,f2,vs);
K36=kg(k36,T36);
k37=klfs(E,A2,I2,L37,f2,vs);
K37=kg(k37,T37);
k38=klfs(E,A2,I2,L38,f2,vs);
K38=kg(k38,T38);
k39=klfs(E,A2,I2,L39,f2,vs);
K39=kg(k39,T39);
k40=klfs(E,A2,I2,L40,f2,vs);
K40=kg(k40,T40);
k41=klfs(E,A2,I2,L41,f2,vs);
K41=kg(k41,T41);
k42=klfs(E,A2,I2,L42,f2,vs);
K42=kg(k42,T42);
k43=klfs(E,A2,I2,L43,f2,vs);
K43=kg(k43,T43);
k44=klfs(E,A2,I2,L44,f2,vs);
K44=kg(k44,T44);
k45=klfs(E,A2,I2,L45,f2,vs);
K45=kg(k45,T45);

dof=84;

id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

```

```

Ks=assf(K1, i d1, dof);
Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);

m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);
m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);

Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);
Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(Mr\Ks);
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder);

i=1:84;
pi m=[mode(20, i); mode(23, i); m
ode(32, i); mode(35, i); mode(44
, i); mode(47, i)];
v=sqrtm(mode'*Mr*mode);
wm=di ag(w(1:84));

Fu6=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))';

Untuk VBPLK 1:
R=zeros(84, 1);
R(20)=-0.3074;
R(23)=0.6333;
R(32)=-0.2;
R(35)=0.5037;
R(44)=-0.1809;
R(47)=-0.4219;

Untuk VBPLK 2:
R=zeros(84, 1);
R(20)=-0.452;
R(23)=0.5346;
R(32)=-0.0213;
R(35)=-0.5868;
R(44)=0.1823;
R(47)=0.3632;

U=sol v(Ks, R);

```

```

u1=di ssf(U, i d1, T1);
u2=di ssf(U, i d2, T2);
u3=di ssf(U, i d3, T3);
u4=di ssf(U, i d4, T4);
u5=di ssf(U, i d5, T5);
u6=di ssf(U, i d6, T6);
u7=di ssf(U, i d7, T7);
u8=di ssf(U, i d8, T8);
u9=di ssf(U, i d9, T9);
u10=di ssf(U, i d10, T10);
u11=di ssf(U, i d11, T11);
u12=di ssf(U, i d12, T12);
u13=di ssf(U, i d13, T13);
u14=di ssf(U, i d14, T14);
u15=di ssf(U, i d15, T15);

u16=di ssf(U, i d16, T16);
u17=di ssf(U, i d17, T17);
u18=di ssf(U, i d18, T18);
u19=di ssf(U, i d19, T19);
u20=di ssf(U, i d20, T20);
u21=di ssf(U, i d21, T21);
u22=di ssf(U, i d22, T22);
u23=di ssf(U, i d23, T23);
u24=di ssf(U, i d24, T24);
u25=di ssf(U, i d25, T25);
u26=di ssf(U, i d26, T26);
u27=di ssf(U, i d27, T27);
u28=di ssf(U, i d28, T28);
u29=di ssf(U, i d29, T29);
u30=di ssf(U, i d30, T30);
u31=di ssf(U, i d31, T31);
u32=di ssf(U, i d32, T32);
u33=di ssf(U, i d33, T33);
u34=di ssf(U, i d34, T34);
u35=di ssf(U, i d35, T35);

u36=di ssf(U, i d36, T36);
u37=di ssf(U, i d37, T37);
u38=di ssf(U, i d38, T38);
u39=di ssf(U, i d39, T39);
u40=di ssf(U, i d40, T40);
u41=di ssf(U, i d41, T41);
u42=di ssf(U, i d42, T42);
u43=di ssf(U, i d43, T43);
u44=di ssf(U, i d44, T44);
u45=di ssf(U, i d45, T45);

So1=zeros(6, 1);
So2=zeros(6, 1);
So3=zeros(6, 1);
So4=zeros(6, 1);
So5=zeros(6, 1);
So6=zeros(6, 1);
So7=zeros(6, 1);
So8=zeros(6, 1);
So9=zeros(6, 1);
So10=zeros(6, 1);
So11=zeros(6, 1);
So12=zeros(6, 1);
So13=zeros(6, 1);
So14=zeros(6, 1);
So15=zeros(6, 1);
So16=zeros(6, 1);
So17=zeros(6, 1);
So18=zeros(6, 1);
So19=zeros(6, 1);
So20=zeros(6, 1);
So21=zeros(6, 1);
So22=zeros(6, 1);
So23=zeros(6, 1);
So24=zeros(6, 1);
So25=zeros(6, 1);
So26=zeros(6, 1);
So27=zeros(6, 1);
So28=zeros(6, 1);
So29=zeros(6, 1);

So30=zeros(6, 1);
So31=zeros(6, 1);
So32=zeros(6, 1);
So33=zeros(6, 1);
So34=zeros(6, 1);
So35=zeros(6, 1);
So36=zeros(6, 1);
So37=zeros(6, 1);
So38=zeros(6, 1);
So39=zeros(6, 1);
So40=zeros(6, 1);
So41=zeros(6, 1);
So42=zeros(6, 1);
So43=zeros(6, 1);
So44=zeros(6, 1);
So45=zeros(6, 1);

S1=stref(k1, u1, So1)
S2=stref(k2, u2, So2)
S3=stref(k3, u3, So3)
S4=stref(k4, u4, So4)
S5=stref(k5, u5, So5)
S6=stref(k6, u6, So6)
S7=stref(k7, u7, So7)
S8=stref(k8, u8, So8)
S9=stref(k9, u9, So9)
S10=stref(k10, u10, So10)
S11=stref(k11, u11, So11)
S12=stref(k12, u12, So12)
S13=stref(k13, u13, So13)
S14=stref(k14, u14, So14)
S15=stref(k15, u15, So15)

S16=stref(k16, u16, So16)
S17=stref(k17, u17, So17)
S18=stref(k18, u18, So18)
S19=stref(k19, u19, So19)
S20=stref(k20, u20, So20)
S21=stref(k21, u21, So21)
S22=stref(k22, u22, So22)
S23=stref(k23, u23, So23)
S24=stref(k24, u24, So24)
S25=stref(k25, u25, So25)
S26=stref(k26, u26, So26)
S27=stref(k27, u27, So27)
S28=stref(k28, u28, So28)
S29=stref(k29, u29, So29)
S30=stref(k30, u30, So30)
S31=stref(k31, u31, So31)
S32=stref(k32, u32, So32)
S33=stref(k33, u33, So33)
S34=stref(k34, u34, So34)
S35=stref(k35, u35, So35)

S36=stref(k36, u36, So36)
S37=stref(k37, u37, So37)
S38=stref(k38, u38, So38)
S39=stref(k39, u39, So39)
S40=stref(k40, u40, So40)
S41=stref(k41, u41, So41)
S42=stref(k42, u42, So42)
S43=stref(k43, u43, So43)
S44=stref(k44, u44, So44)
S45=stref(k45, u45, So45)

```

Lampiran 35: Output Gaya-gaya Batang dari software Matlab Kasus 6

Aki bat VBPLK	0.0005	-0.0042	-0.0103	-0.0000
1:	0.0012	S22 =	-0.0081	-0.0000
S1 =	-0.1060	-0.3714	0.0098	S43 =
-0.0083	-0.0005	0.0037	-0.0239	-0.3371
0.0030	0.0021	-0.0001	S33 =	0.0000
0.0090	S12 =	0.3714	-0.0319	0.0000
0.0083	-0.0159	-0.0037	-0.0078	0.3371
-0.0030	0.0109	0.0130	-0.0091	-0.0000
0.0092	0.0326	S23 =	0.0319	0.0000
S2 =	0.0159	-0.0344	0.0078	S44 =
0.0408	-0.0109	0.0025	-0.0183	0.0158
-0.0007	0.0328	-0.0023	S34 =	0.0000
-0.0014	S13 =	0.0344	0.0008	0.0000
-0.0408	0.0098	-0.0025	-0.0014	-0.0158
0.0007	0.0081	0.0113	0.0069	-0.0000
-0.0029	0.0239	S24 =	-0.0008	0.0000
S3 =	-0.0098	0.0288	0.0014	S45 =
-0.0033	-0.0081	-0.0070	-0.0118	0.0424
0.0017	0.0248	-0.0171	S35 =	0.0000
0.0052	S14 =	-0.0288	-0.0064	0.0000
0.0033	-0.0191	0.0070	-0.0041	-0.0424
-0.0017	-0.0024	-0.0074	0.0044	-0.0000
0.0051	-0.0065	S25 =	0.0064	0.0000
S4 =	0.0191	0.4234	0.0041	
-0.0010	0.0024	-0.0072	-0.0187	
0.0070	-0.0078	-0.0170	S36 =	
0.0210	S15 =	-0.4234	1.0e-004 *	
0.0010	-0.0041	0.0072		
-0.0070	0.0064	-0.0082	0.1984	
0.0210	0.0195	S26 =	0.0000	
S5 =	0.0041	-0.2697	0.0000	
-0.2630	-0.0064	-0.0091	-0.1984	
-0.0002	0.0187	-0.0283	-0.0000	
0.0002	S16 =	0.2697	0.0000	
0.2630	0.0389	0.0091	S37 =	
0.0002	0.0023	-0.0034	0.0269	
-0.0012	-0.0000	S27 =	0.0000	
S6 =	-0.0389	-0.0289	0.0000	
0.0111	-0.0023	-0.0086	-0.0269	
0.0055	0.0081	-0.0278	-0.0000	
0.0165	S17 =	0.0289	0.0000	
-0.0111	0.3810	0.0086	S38 =	
-0.0055	0.0027	-0.0023	-0.0939	
0.0166	-0.0000	S28 =	0.0000	
S7 =	-0.3810	0.0188	0.0000	
-0.0058	-0.0027	-0.0128	0.0939	
0.0101	0.0093	-0.0229	-0.0000	
0.0303	S18 =	-0.0188	0.0000	
0.0058	-0.3973	0.0128	S39 =	
-0.0101	-0.0006	-0.0218	-0.0561	
0.0301	0.0000	S29 =	0.0000	
S8 =	0.3973	0.1358	0.0000	
-0.1896	0.0006	-0.0141	0.0561	
0.0016	-0.0022	-0.0254	-0.0000	
0.0035	S19 =	-0.1358	0.0000	
0.1896	-0.0361	0.0141	S40 =	
-0.0016	-0.0008	-0.0240	0.0022	
0.0058	0	S30 =	0.0000	
S9 =	0.0361	-0.1088	0.0000	
0.0114	0.0008	-0.0225	-0.0022	
0.0116	-0.0027	-0.0371	-0.0000	
0.0348	S20 =	0.1088	0.0000	
-0.0114	0.0358	0.0225	S41 =	
-0.0116	-0.0060	-0.0417	-0.3071	
0.0350	-0.0171	S31 =	0.0000	
S10 =	-0.0358	-0.0173	0.0000	
0.0030	0.0060	-0.0200	0.3071	
0.0107	-0.0039	-0.0327	-0.0000	
0.0320	S21 =	0.0173	-0.0000	
-0.0030	0.4456	0.0200	S42 =	
-0.0107	-0.0061	-0.0372	0.2805	
0.0319	-0.0171	S32 =	0.0000	
S11 =	-0.4456	0.0081	-0.0000	
0.1060	0.0061	-0.0098	-0.2805	

Aki bat VBPLK	-0.0009	-0.0170	0.0063	S43 =
2:	-0.0019	S22 =	0.0051	0.3266
S1 =	0.0878	0.2724	-0.0061	-0.0000
-0.0069	0.0009	0.0129	0.0150	0.0000
-0.0006	-0.0036	0.0201	S33 =	-0.3266
-0.0019	S12 =	-0.2724	0.0220	0.0000
0.0069	0.0220	-0.0129	0.0051	0.0000
0.0006	-0.0084	0.0252	0.0064	S44 =
-0.0019	-0.0251	S23 =	-0.0220	-0.0184
S2 =	-0.0220	0.0206	-0.0051	0.0000
0.0475	0.0084	0.0112	0.0115	0.0000
0.0001	-0.0252	0.0174	S34 =	0.0184
0.0016	S13 =	-0.0206	0.0036	-0.0000
-0.0475	-0.0061	-0.0112	-0.0016	0.0000
-0.0001	-0.0051	0.0219	-0.0123	S45 =
-0.0008	-0.0150	S24 =	-0.0036	-0.0304
S3 =	0.0061	-0.0187	0.0016	0
-0.0139	0.0051	0.0095	0.0067	0.0000
-0.0027	-0.0156	0.0240	S35 =	0.0304
-0.0083	S14	0.0187	0.0040	0
0.0139	0.0151	-0.0095	0.0008	0.0000
0.0027	0.0016	0.0094	-0.0092	
-0.0082	0.0042	S25 =	-0.0040	
S4 =	-0.0151	-0.2220	-0.0008	
0.0148	-0.0016	0.0105	0.0119	
-0.0033	0.0057	0.0253	S36 =	
-0.0098	S15 =	0.2220	0.0031	
-0.0148	0.0008	-0.0105	-0.0000	
0.0033	-0.0040	0.0114	-0.0000	
-0.0099	-0.0124	S26 =	-0.0031	
S5 =	-0.0008	0.2583	0.0000	
-0.3367	0.0040	-0.0155	-0.0000	
0.0008	-0.0119	-0.0209	S37 =	
0.0017	S16 =	-0.2583	0.0288	
0.3367	-0.0226	0.0155	-0.0000	
-0.0008	0.0017	-0.0332	-0.0000	
0.0029	0.0000	S27 =	-0.0288	
S6 =	0.0226	0.0182	0.0000	
0.0234	-0.0017	-0.0122	-0.0000	
-0.0024	0.0060	-0.0148	S38 =	
-0.0072	S17 =	-0.0182	-0.1017	
-0.0234	-0.2381	0.0122	-0.0000	
0.0024	0.0019	-0.0277	-0.0000	
-0.0072	0.0000	S28 =	0.1017	
S7 =	0.2381	-0.0118	0.0000	
-0.0024	-0.0019	0.0072	-0.0000	
-0.0069	0.0066	0.0113	S39 =	
-0.0208	S18 =	0.0118	-0.0928	
0.0024	0.2212	-0.0072	-0.0000	
0.0069	-0.0031	0.0139	-0.0000	
-0.0207	0	S29 =	0.0928	
S8 =	-0.2212	-0.1461	0.0000	
0.2310	0.0031	0.0079	-0.0000	
-0.0007	-0.0110	0.0123	S40 =	
-0.0030	S19 =	0.1461	-0.0037	
-0.2310	0.0234	-0.0079	-0.0000	
0.0007	-0.0026	0.0154	-0.0000	
-0.0014	0.0000	S30 =	0.0037	
S9 =	-0.0234	0.0969	0.0000	
-0.0349	0.0026	0.0266	-0.0000	
-0.0058	-0.0092	0.0520	S41 =	
-0.0173	S20 =	-0.0969	-0.0674	
0.0349	-0.0220	-0.0266	-0.0000	
0.0058	-0.0052	0.0410	-0.0000	
-0.0174	-0.0041	S31 =	0.0674	
S10 =	0.0220	0.0124	0.0000	
-0.0011	0.0052	0.0227	0.0000	
-0.0067	-0.0142	0.0452	S42 =	
-0.0201	S21 =	-0.0124	-0.2303	
0.0011	-0.1730	-0.0227	-0.0000	
0.0067	-0.0067	0.0344	0.0000	
-0.0199	-0.0064	S32 =	0.2303	
S11 =	0.1730	-0.0051	0.0000	
-0.0878	0.0067	0.0061	0.0000	

Lampiran 36: *Output* Gaya-gaya Batang dari *software* ETABS Kasus 6

ETABS v9.7.0 File: CASE 6 VBPLK 1 Units: KN-m April 20, 2013 12:07 PAGE 4

C O L U M N F O R C E E N V E L O P E S

STORY	COLUMN	ITEM	P	V2	V3	T	M2	M3
LT5	C5	Min Value	-0.0081	-0.0098	0.0000	0.0000	0.0000	-0.0103
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0081	-0.0098	0.0000	0.0000	0.0000	0.0239
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C6	Min Value	0.0319	-0.0078	0.0000	0.0000	0.0000	-0.0091
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0319	-0.0078	0.0000	0.0000	0.0000	0.0183
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C7	Min Value	-0.0008	-0.0014	0.0000	0.0000	0.0000	0.0069
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0008	-0.0014	0.0000	0.0000	0.0000	0.0118
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C8	Min Value	0.0064	-0.0041	0.0000	0.0000	0.0000	0.0043
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0064	-0.0041	0.0000	0.0000	0.0000	0.0187
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C5	Min Value	-0.0188	-0.0127	0.0000	0.0000	0.0000	-0.0229
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0188	-0.0127	0.0000	0.0000	0.0000	0.0218
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C6	Min Value	-0.1358	-0.0141	0.0000	0.0000	0.0000	-0.0254
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.1358	-0.0141	0.0000	0.0000	0.0000	0.0240
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C7	Min Value	0.1087	-0.0225	0.0000	0.0000	0.0000	-0.0371
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.1087	-0.0225	0.0000	0.0000	0.0000	0.0416
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C8	Min Value	0.0173	-0.0199	0.0000	0.0000	0.0000	-0.0327
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0173	-0.0199	0.0000	0.0000	0.0000	0.0371
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C5	Min Value	-0.0288	-0.0070	0.0000	0.0000	0.0000	-0.0171
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0288	-0.0070	0.0000	0.0000	0.0000	0.0074
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C6	Min Value	-0.4233	-0.0072	0.0000	0.0000	0.0000	-0.0170
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.4233	-0.0072	0.0000	0.0000	0.0000	0.0082
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C7	Min Value	0.2696	-0.0091	0.0000	0.0000	0.0000	-0.0283
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.2696	-0.0091	0.0000	0.0000	0.0000	0.0035
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C8	Min Value	0.0289	-0.0086	0.0000	0.0000	0.0000	-0.0278
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0289	-0.0086	0.0000	0.0000	0.0000	0.0023
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C5	Min Value	-0.0358	-0.0060	0.0000	0.0000	0.0000	-0.0171
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0358	-0.0060	0.0000	0.0000	0.0000	0.0039
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C6	Min Value	-0.4456	-0.0061	0.0000	0.0000	0.0000	-0.0171
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.4456	-0.0061	0.0000	0.0000	0.0000	0.0042
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C7	Min Value	0.3714	0.0037	0.0000	0.0000	0.0000	-0.0130
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.3714	0.0037	0.0000	0.0000	0.0000	-0.0001
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C8	Min Value	0.0344	0.0025	0.0000	0.0000	0.0000	-0.0112
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0344	0.0025	0.0000	0.0000	0.0000	-0.0024
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C5	Min Value	-0.0389	0.0023	0.0000	0.0000	0.0000	-0.0081
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0389	0.0023	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C6	Min Value	-0.3809	0.0027	0.0000	0.0000	0.0000	-0.0093
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.3809	0.0027	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C7	Min Value	0.3972	-0.0006	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.3972	-0.0006	0.0000	0.0000	0.0000	0.0022
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD

LT5	D8	Min Value	0.0304	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0304	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT4	D7	Min Value	0.2304	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.2304	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT4	D8	Min Value	-0.3267	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.3267	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT3	D7	Min Value	0.0037	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0037	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT3	D8	Min Value	0.0674	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0674	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT2	D7	Min Value	0.1017	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.1017	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT2	D8	Min Value	0.0928	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0928	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT1	D7	Min Value	-0.0031	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0031	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	
LT1	D8	Min Value	-0.0288	0.0000	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0288	0.0000	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	

Lampiran 37: Coding Matlab Menghitung F_U Kasus Kerusakan 7

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);

k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

E=2e8; %kN/m2
Ks=assf(K1, id1, dof);

```

```

Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);

m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);

Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(M\r\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(14, i); mode(26, i); m
ode(38, i); mode(50, i); mode(62
, i)]
v=sqrt(m(mode'*Mr*mode))
wm=di ag(w(1:84));
Fu7=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```


Lampiran 38: Coding Matlab Menghitung F_D Kasus Kerusakan 7

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7); %//----
-damage member ----//
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15); %//--
---damage member ----//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23); %//--
---damage member ----//

[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0.0144; %m2/Kolom
A2=0.0121; %Balok dan bracing
Ad=A2*0.5; %//----damage
member ----//
I1=5.536e-4; %m4
I2=2.176e-4;
Id=I2*0.5; %//----damage
member ----//
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=klfs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=klfs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=klfs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=klfs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=klfs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=klfs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=klfs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=klfs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=klfs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=klfs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=klfs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=klfs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=klfs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=klfs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=klfs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=klfs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=klfs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=klfs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=klfs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=klfs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=klfs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=klfs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=klfs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=klfs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=klfs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=klfs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=klfs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=klfs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=klfs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=klfs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);

k31=klfs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=klfs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=klfs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=klfs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=klfs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=klfs(E, Ad, Id, L36, f2, vs);
K36=kg(k36, T36); %//----
damage member ----//
k37=klfs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=klfs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=klfs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=klfs(E, Ad, Id, L40, f2, vs);
K40=kg(k40, T40); %//----
damage member ----//
k41=klfs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=klfs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=klfs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=klfs(E, Ad, Id, L44, f2, vs);
K44=kg(k44, T44); %//----
damage member ----//
k45=klfs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];
id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];
id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];

```

```

id39=[ 11 12 70 20 21 71];
id40=[ 20 21 73 35 36 76];
id41=[ 23 24 74 32 33 75];
id42=[ 32 33 77 47 48 80];
id43=[ 35 36 78 44 45 79];
id44=[ 44 45 81 59 60 84];
id45=[ 47 48 82 56 57 83];

Ks=assf(K1, id1, dof);
Ks=Ks+assf(K2, id2, dof);
Ks=Ks+assf(K3, id3, dof);
Ks=Ks+assf(K4, id4, dof);
Ks=Ks+assf(K5, id5, dof);
Ks=Ks+assf(K6, id6, dof);
Ks=Ks+assf(K7, id7, dof);
Ks=Ks+assf(K8, id8, dof);
Ks=Ks+assf(K9, id9, dof);
Ks=Ks+assf(K10, id10, dof);
Ks=Ks+assf(K11, id11, dof);
Ks=Ks+assf(K12, id12, dof);
Ks=Ks+assf(K13, id13, dof);
Ks=Ks+assf(K14, id14, dof);
Ks=Ks+assf(K15, id15, dof);

Ks=Ks+assf(K16, id16, dof);
Ks=Ks+assf(K17, id17, dof);
Ks=Ks+assf(K18, id18, dof);
Ks=Ks+assf(K19, id19, dof);
Ks=Ks+assf(K20, id20, dof);
Ks=Ks+assf(K21, id21, dof);
Ks=Ks+assf(K22, id22, dof);
Ks=Ks+assf(K23, id23, dof);
Ks=Ks+assf(K24, id24, dof);
Ks=Ks+assf(K25, id25, dof);
Ks=Ks+assf(K26, id26, dof);
Ks=Ks+assf(K27, id27, dof);
Ks=Ks+assf(K28, id28, dof);
Ks=Ks+assf(K29, id29, dof);
Ks=Ks+assf(K30, id30, dof);
Ks=Ks+assf(K31, id31, dof);
Ks=Ks+assf(K32, id32, dof);
Ks=Ks+assf(K33, id33, dof);
Ks=Ks+assf(K34, id34, dof);
Ks=Ks+assf(K35, id35, dof);

Ks=Ks+assf(K36, id36, dof);
Ks=Ks+assf(K37, id37, dof);
Ks=Ks+assf(K38, id38, dof);
Ks=Ks+assf(K39, id39, dof);
Ks=Ks+assf(K40, id40, dof);
Ks=Ks+assf(K41, id41, dof);
Ks=Ks+assf(K42, id42, dof);
Ks=Ks+assf(K43, id43, dof);
Ks=Ks+assf(K44, id44, dof);
Ks=Ks+assf(K45, id45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);

m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);
m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*Ad, L36); %//----
damage member ----//
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*Ad, L40); %//----
damage member ----//
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*Ad, L44); %//----
damage member ----//
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);

M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, id1, dof);
Mr=Mr+assf(M2, id2, dof);
Mr=Mr+assf(M3, id3, dof);
Mr=Mr+assf(M4, id4, dof);
Mr=Mr+assf(M5, id5, dof);
Mr=Mr+assf(M6, id6, dof);
Mr=Mr+assf(M7, id7, dof);
Mr=Mr+assf(M8, id8, dof);
Mr=Mr+assf(M9, id9, dof);
Mr=Mr+assf(M10, id10, dof);
Mr=Mr+assf(M11, id11, dof);
Mr=Mr+assf(M12, id12, dof);
Mr=Mr+assf(M13, id13, dof);
Mr=Mr+assf(M14, id14, dof);
Mr=Mr+assf(M15, id15, dof);

Mr=Mr+assf(M16, id16, dof);
Mr=Mr+assf(M17, id17, dof);
Mr=Mr+assf(M18, id18, dof);
Mr=Mr+assf(M19, id19, dof);
Mr=Mr+assf(M20, id20, dof);
Mr=Mr+assf(M21, id21, dof);
Mr=Mr+assf(M22, id22, dof);
Mr=Mr+assf(M23, id23, dof);
Mr=Mr+assf(M24, id24, dof);
Mr=Mr+assf(M25, id25, dof);
Mr=Mr+assf(M26, id26, dof);
Mr=Mr+assf(M27, id27, dof);
Mr=Mr+assf(M28, id28, dof);
Mr=Mr+assf(M29, id29, dof);
Mr=Mr+assf(M30, id30, dof);
Mr=Mr+assf(M31, id31, dof);
Mr=Mr+assf(M32, id32, dof);
Mr=Mr+assf(M33, id33, dof);
Mr=Mr+assf(M34, id34, dof);
Mr=Mr+assf(M35, id35, dof);

Mr=Mr+assf(M36, id36, dof);
Mr=Mr+assf(M37, id37, dof);
Mr=Mr+assf(M38, id38, dof);
Mr=Mr+assf(M39, id39, dof);
Mr=Mr+assf(M40, id40, dof);
Mr=Mr+assf(M41, id41, dof);
Mr=Mr+assf(M42, id42, dof);
Mr=Mr+assf(M43, id43, dof);
Mr=Mr+assf(M44, id44, dof);
Mr=Mr+assf(M45, id45, dof);

[ei gv, ei gval]=ei g(Mr\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(14, i); mode(26, i); m
ode(38, i); mode(50, i); mode(62
, i)]
v=sqrt m(mode'*Mr*mode)
wm=di ag(w(1:84));
Fd7=(pi m*inv(v))*inv(wm^2)*(
pi m*inv(v))'

```

Lampiran 39: *Coding* Matlab Menghitung SVD Kasus Kerusakan 7

```
Fu7 =1.0e-004 * [0.0469    0.0260    0.0279    0.0318    0.0349; 0.0260    0.0799  
0.0693    0.0801    0.0924; 0.0279    0.0693    0.1389    0.1434    0.1684; 0.0318  
0.0801    0.1434    0.2348    0.2575; 0.0349    0.0924    0.1684    0.2575    0.3768]  
  
Fd7 =1.0e-004 * [0.0557    0.0336    0.0353    0.0393    0.0424; 0.0336    0.0868  
0.0774    0.0881    0.1002; 0.0353    0.0774    0.1530    0.1565    0.1808; 0.0393  
0.0881    0.1565    0.2473    0.2704; 0.0424    0.1002    0.1808    0.2704    0.3958]  
  
Fdel =Fu7- Fd7  
[u, s, v]=svd(Fdel)
```



Lampiran 40: Coding Matlab Menghitung Gaya Batang Kasus Kerusakan 7

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n22, n7); %//---
-damage member ----//
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15); %//--
---damage member ----//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23); %//--
---damage member ----//

[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=klfs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=klfs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=klfs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=klfs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=klfs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=klfs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=klfs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=klfs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=klfs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=klfs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=klfs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=klfs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=klfs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=klfs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=klfs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=klfs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=klfs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=klfs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=klfs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=klfs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=klfs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=klfs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=klfs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=klfs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=klfs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=klfs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=klfs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=klfs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=klfs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=klfs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=klfs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=klfs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);

k33=klfs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=klfs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=klfs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=klfs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=klfs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=klfs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=klfs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=klfs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=klfs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=klfs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=klfs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=klfs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=klfs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;

id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

```

```

Ks=assf(K1, i d1, dof);
Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);

m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);
m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);

Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);
Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(Mr\Ks);
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder);

i=1:84;
pi m=[mode(14, i); mode(26, i); m
ode(38, i); mode(50, i); mode(62
, i)];
v=sqrtm(mode'*Mr*mode);
wm=di ag(w(1:84));
Fu7=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))';

Untuk VBPLK 1:
R=zeros(84, 1);
R(14, 1)=-0.4859;
R(26, 1)=0.7740;
R(38, 1)=0.1143;
R(50, 1)=-0.3849;
R(62, 1)=0.0607;

Untuk VBPLK 2:
R=zeros(84, 1);
R(14, 1)=0.2596;
R(26, 1)=-0.2828;
R(38, 1)=0.5862;
R(50, 1)=-0.7049;
R(62, 1)=0.1098;

U=sol v(Ks, R);

u1=di ssf(U, i d1, T1);
u2=di ssf(U, i d2, T2);
u3=di ssf(U, i d3, T3);
u4=di ssf(U, i d4, T4);

```

```

u5=di ssf(U, i d5, T5);
u6=di ssf(U, i d6, T6);
u7=di ssf(U, i d7, T7);
u8=di ssf(U, i d8, T8);
u9=di ssf(U, i d9, T9);
u10=di ssf(U, i d10, T10);
u11=di ssf(U, i d11, T11);
u12=di ssf(U, i d12, T12);
u13=di ssf(U, i d13, T13);
u14=di ssf(U, i d14, T14);
u15=di ssf(U, i d15, T15);

u16=di ssf(U, i d16, T16);
u17=di ssf(U, i d17, T17);
u18=di ssf(U, i d18, T18);
u19=di ssf(U, i d19, T19);
u20=di ssf(U, i d20, T20);
u21=di ssf(U, i d21, T21);
u22=di ssf(U, i d22, T22);
u23=di ssf(U, i d23, T23);
u24=di ssf(U, i d24, T24);
u25=di ssf(U, i d25, T25);
u26=di ssf(U, i d26, T26);
u27=di ssf(U, i d27, T27);
u28=di ssf(U, i d28, T28);
u29=di ssf(U, i d29, T29);
u30=di ssf(U, i d30, T30);
u31=di ssf(U, i d31, T31);
u32=di ssf(U, i d32, T32);
u33=di ssf(U, i d33, T33);
u34=di ssf(U, i d34, T34);
u35=di ssf(U, i d35, T35);

u36=di ssf(U, i d36, T36);
u37=di ssf(U, i d37, T37);
u38=di ssf(U, i d38, T38);
u39=di ssf(U, i d39, T39);
u40=di ssf(U, i d40, T40);
u41=di ssf(U, i d41, T41);
u42=di ssf(U, i d42, T42);
u43=di ssf(U, i d43, T43);
u44=di ssf(U, i d44, T44);
u45=di ssf(U, i d45, T45);

So1=zeros(6, 1);
So2=zeros(6, 1);
So3=zeros(6, 1);
So4=zeros(6, 1);
So5=zeros(6, 1);
So6=zeros(6, 1);
So7=zeros(6, 1);
So8=zeros(6, 1);
So9=zeros(6, 1);
So10=zeros(6, 1);
So11=zeros(6, 1);
So12=zeros(6, 1);
So13=zeros(6, 1);
So14=zeros(6, 1);
So15=zeros(6, 1);
So16=zeros(6, 1);
So17=zeros(6, 1);
So18=zeros(6, 1);
So19=zeros(6, 1);
So20=zeros(6, 1);
So21=zeros(6, 1);
So22=zeros(6, 1);
So23=zeros(6, 1);
So24=zeros(6, 1);
So25=zeros(6, 1);
So26=zeros(6, 1);
So27=zeros(6, 1);
So28=zeros(6, 1);
So29=zeros(6, 1);
So30=zeros(6, 1);
So31=zeros(6, 1);
So32=zeros(6, 1);
So33=zeros(6, 1);

So34=zeros(6, 1);
So35=zeros(6, 1);
So36=zeros(6, 1);
So37=zeros(6, 1);
So38=zeros(6, 1);
So39=zeros(6, 1);
So40=zeros(6, 1);
So41=zeros(6, 1);
So42=zeros(6, 1);
So43=zeros(6, 1);
So44=zeros(6, 1);
So45=zeros(6, 1);

S1=stref(k1, u1, So1)
S2=stref(k2, u2, So2)
S3=stref(k3, u3, So3)
S4=stref(k4, u4, So4)
S5=stref(k5, u5, So5)
S6=stref(k6, u6, So6)
S7=stref(k7, u7, So7)
S8=stref(k8, u8, So8)
S9=stref(k9, u9, So9)
S10=stref(k10, u10, So10)
S11=stref(k11, u11, So11)
S12=stref(k12, u12, So12)
S13=stref(k13, u13, So13)
S14=stref(k14, u14, So14)
S15=stref(k15, u15, So15)

S16=stref(k16, u16, So16)
S17=stref(k17, u17, So17)
S18=stref(k18, u18, So18)
S19=stref(k19, u19, So19)
S20=stref(k20, u20, So20)
S21=stref(k21, u21, So21)
S22=stref(k22, u22, So22)
S23=stref(k23, u23, So23)
S24=stref(k24, u24, So24)
S25=stref(k25, u25, So25)
S26=stref(k26, u26, So26)
S27=stref(k27, u27, So27)
S28=stref(k28, u28, So28)
S29=stref(k29, u29, So29)
S30=stref(k30, u30, So30)
S31=stref(k31, u31, So31)
S32=stref(k32, u32, So32)
S33=stref(k33, u33, So33)
S34=stref(k34, u34, So34)
S35=stref(k35, u35, So35)

S36=stref(k36, u36, So36)
S37=stref(k37, u37, So37)
S38=stref(k38, u38, So38)
S39=stref(k39, u39, So39)
S40=stref(k40, u40, So40)
S41=stref(k41, u41, So41)
S42=stref(k42, u42, So42)
S43=stref(k43, u43, So43)
S44=stref(k44, u44, So44)
S45=stref(k45, u45, So45)

```

Lampiran 41: Output Gaya-gaya Batang dari software Matlab Kasus 7

Aki bat VBPLK	0.0005	0.0115	-0.0007	S43 =
1:	0.0016	S22 =	-0.0018	-0.1340
S1 =	-0.1231	-0.0812	0.0017	0.0000
0.0034	-0.0005	0.0223	-0.0052	-0.0000
-0.0018	0.0013	0.0359	S33 =	0.1340
-0.0055	S12 =	0.0812	-0.0291	-0.0000
-0.0034	0.3562	-0.0223	-0.0013	-0.0000
0.0018	0.0025	0.0423	-0.0005	S44 =
-0.0053	0.0075	S23 =	0.0291	1.0e-003 *
S2 =	-0.3562	-0.0051	0.0013	0.4533
0.1656	-0.0025	0.0584	-0.0041	0
-0.0017	0.0076	0.0961	S34 =	-0.0000
-0.0043	S13 =	0.0051	-0.0013	-0.4533
-0.1656	0.0017	-0.0584	0.0048	0
0.0017	0.0018	0.1084	0.0120	-0.0000
-0.0057	0.0052	S24 =	0.0013	S45 =
S3 =	-0.0017	0.0067	-0.0048	0.0530
0.4056	-0.0018	-0.0014	0.0047	0.0000
-0.0055	0.0053	-0.0075	S35 =	-0.0000
-0.0137	S14 =	-0.0067	0.0017	-0.0530
-0.4056	-0.0428	0.0014	0.0135	-0.0000
0.0055	-0.0006	0.0027	0.0396	-0.0000
-0.0194	-0.0013	S25 =	-0.0017	
S4 =	0.0428	0.2274	-0.0135	
-0.0052	0.0006	-0.0016	0.0078	
-0.0005	-0.0024	-0.0074	S36 =	
-0.0016	S15 =	-0.2274	-0.0047	
0.0052	-0.0472	0.0016	0.0000	
0.0005	-0.0017	0.0018	0.0000	
-0.0015	-0.0023	S26 =	0.0047	
S5 =	0.0472	-0.1379	-0.0000	
-0.2347	0.0017	-0.0116	0.0000	
-0.0010	-0.0078	-0.0311	S37 =	
-0.0025	S16 =	0.1379	0.1154	
0.2347	0.0043	0.0116	-0.0000	
0.0010	0.0004	-0.0095	0.0000	
-0.0035	0.0000	S27 =	-0.1154	
S6 =	-0.0043	-0.0084	0.0000	
-0.6821	-0.0004	-0.0335	0.0000	
-0.0033	0.0013	-0.0964	S38 =	
-0.0077	S17 =	0.0084	-0.2979	
0.6821	-0.1044	0.0335	-0.0000	
0.0033	0.0007	-0.0209	0	
-0.0120	0.0000	S28 =	0.2979	
S7 =	0.1044	0.0045	0.0000	
-0.0035	-0.0007	-0.0048	0	
0.0022	0.0025	-0.0094	S39 =	
0.0066	S18 =	-0.0045	0.2511	
0.0035	0.0438	0.0048	-0.0000	
-0.0022	-0.0047	-0.0075	-0.0000	
0.0065	-0.0000	S29 =	-0.2511	
S8 =	-0.0438	0.0365	0.0000	
-0.0243	0.0047	-0.0058	0.0000	
0.0013	-0.0165	-0.0113	S40 =	
0.0030	S19 =	-0.0365	0.0066	
0.0243	0.0004	0.0058	0.0000	
-0.0013	-0.0219	-0.0091	0.0000	
0.0048	-0.0000	S30 =	-0.0066	
S9 =	-0.0004	-0.0733	-0.0000	
-0.1326	0.0219	-0.0099	0.0000	
0.0075	-0.0767	-0.0139	S41 =	
0.0186	S20 =	0.0733	-0.1807	
0.1326	0.0061	0.0099	0.0000	
-0.0075	0.0038	-0.0208	0.0000	
0.0267	0.0042	S31 =	0.1807	
S10 =	-0.0061	-0.0008	-0.0000	
0.0032	-0.0038	-0.0152	0	
0.0027	0.0092	-0.0058	S42 =	
0.0082	S21 =	0.0008	0.1999	
-0.0032	0.1037	0.0152	0.0000	
-0.0027	0.0053	-0.0472	0.0000	
0.0081	0.0071	S32 =	-0.1999	
S11 =	-0.1037	0.0018	-0.0000	
0.1231	-0.0053	-0.0017	0.0000	

Aki bat VBPLK	0.0004	-0.0015	-0.0106	0.0000
2:	0.0008	S22 =	-0.0063	S43 =
S1 =	-0.2295	-0.3021	0.0083	-0.2651
-0.0041	-0.0004	-0.0145	-0.0186	0.0000
0.0031	0.0015	-0.0270	S33 =	0.0000
0.0092	S12 =	0.3021	-0.0606	0.2651
0.0041	0.6036	0.0145	-0.0072	-0.0000
-0.0031	0.0105	-0.0238	-0.0103	0.0000
0.0092	0.0293	S23 =	0.0606	S44 =
S2 =	-0.6036	-0.0233	0.0072	1.0e-003 *
-0.0815	-0.0105	-0.0388	-0.0149	-0.9174
0.0004	0.0335	-0.0578	S34 =	0.0000
0.0007	S13 =	0.0233	0.0018	-0.0000
0.0815	0.0083	0.0388	0.0066	0.9174
-0.0004	0.0063	-0.0781	0.0204	-0.0000
0.0015	0.0186	S24 =	-0.0018	0
S3 =	-0.0083	0.0219	-0.0066	S45 =
-0.2090	-0.0063	-0.0077	0.0027	0.1041
0.0050	0.0193	-0.0164	S35 =	0.0000
0.0137	S14 =	-0.0219	0.0005	-0.0000
0.2090	-0.0744	0.0077	0.0280	-0.1041
-0.0050	-0.0018	-0.0105	0.0911	-0.0000
0.0164	-0.0044	S25 =	-0.0005	-0.0000
S4 =	0.0744	0.2335	-0.0280	
-0.0042	0.0018	-0.0082	0.0071	
0.0059	-0.0067	-0.0171	S36 =	
0.0178	S15 =	-0.2335	1.0e-003 *	
0.0042	-0.0818	0.0082	0.2432	
-0.0059	-0.0005	-0.0116	0.0000	
0.0178	0.0039	S26 =	0.0000	
S5 =	0.0818	-0.2045	-0.2432	
0.1028	0.0005	0.0093	-0.0000	
0.0002	-0.0071	0.0105	0.0000	
0.0008	S16 =	0.2045	S37 =	
-0.1028	0.0309	-0.0093	-0.0557	
-0.0002	0.0005	0.0219	0.0000	
0.0001	-0.0000	S27 =	0.0000	
S6 =	-0.0309	-0.0194	0.0557	
0.1954	-0.0005	0.0486	-0.0000	
0.0039	0.0018	0.0676	0.0000	
0.0132	S17 =	0.0194	S38 =	
-0.1954	0.3869	-0.0486	0.1405	
-0.0039	0.0005	0.1023	0.0000	
0.0105	0.0000	S28 =	0.0000	
S7 =	-0.3869	0.0142	-0.1405	
0.0003	-0.0005	-0.0074	-0.0000	
0.0078	0.0017	-0.0128	0	
0.0233	S18 =	-0.0142	S39 =	
-0.0003	-0.3616	0.0074	-0.1271	
-0.0078	0.0034	-0.0130	0.0000	
0.0232	-0.0000	S29 =	0.0000	
S8 =	0.3616	0.0650	0.1271	
-0.1951	-0.0034	-0.0079	-0.0000	
0.0008	0.0118	-0.0136	0.0000	
0.0020	S19 =	-0.0650	S40 =	
0.1951	-0.0283	0.0079	-0.0019	
-0.0008	0.0118	-0.0139	0.0000	
0.0026	0.0000	S30 =	0.0000	
S9 =	0.0283	-0.0805	0.0019	
-0.4644	-0.0118	-0.0293	-0.0000	
0.0094	0.0414	-0.0515	0.0000	
0.0270	S20 =	0.0805	S41 =	
0.4644	0.0278	0.0293	-0.0608	
-0.0094	-0.0035	-0.0512	0.0000	
0.0296	-0.0111	S31 =	0.0000	
S10 =	-0.0278	-0.0099	0.0608	
-0.0010	0.0035	-0.0733	-0.0000	
0.0078	-0.0013	-0.1319	-0.0000	
0.0236	S21 =	0.0099	S42 =	
0.0010	0.2908	0.0733	0.2874	
-0.0078	-0.0037	-0.1246	0.0000	
0.0235	-0.0115	S32 =	0.0000	
S11 =	-0.2908	0.0063	-0.2874	
0.2295	0.0037	-0.0083	-0.0000	

Lampiran 42: *Output* Gaya-gaya Batang dari *software* ETABS Kasus 7

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C O L U M N F O R C E E N V E L O P E S

STORY	COLUMN	ITEM	P	V2	V3	T	M2	M3
LT5	C5	Min Value	-0.0018	-0.0017	0.0000	0.0000	0.0000	-0.0007
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0018	-0.0017	0.0000	0.0000	0.0000	0.0052
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C6	Min Value	0.0291	-0.0013	0.0000	0.0000	0.0000	-0.0005
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0291	-0.0013	0.0000	0.0000	0.0000	0.0041
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C7	Min Value	0.0013	0.0048	0.0000	0.0000	0.0000	-0.0047
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0013	0.0048	0.0000	0.0000	0.0000	0.0120
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C8	Min Value	-0.0017	0.0135	0.0000	0.0000	0.0000	-0.0078
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0017	0.0135	0.0000	0.0000	0.0000	0.0395
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C5	Min Value	-0.0045	-0.0048	0.0000	0.0000	0.0000	-0.0094
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0045	-0.0048	0.0000	0.0000	0.0000	0.0075
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C6	Min Value	-0.0365	-0.0058	0.0000	0.0000	0.0000	-0.0113
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0365	-0.0058	0.0000	0.0000	0.0000	0.0091
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C7	Min Value	0.0733	-0.0099	0.0000	0.0000	0.0000	-0.0139
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0733	-0.0099	0.0000	0.0000	0.0000	0.0208
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C8	Min Value	0.0008	-0.0151	0.0000	0.0000	0.0000	-0.0058
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0008	-0.0151	0.0000	0.0000	0.0000	0.0472
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C5	Min Value	-0.0067	-0.0014	0.0000	0.0000	0.0000	-0.0075
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0067	-0.0014	0.0000	0.0000	0.0000	-0.0027
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C6	Min Value	-0.2274	-0.0016	0.0000	0.0000	0.0000	-0.0074
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.2274	-0.0016	0.0000	0.0000	0.0000	-0.0018
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C7	Min Value	0.1380	-0.0116	0.0000	0.0000	0.0000	-0.0310
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.1380	-0.0116	0.0000	0.0000	0.0000	0.0095
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C8	Min Value	0.0084	-0.0334	0.0000	0.0000	0.0000	-0.0962
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0084	-0.0334	0.0000	0.0000	0.0000	0.0208
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C5	Min Value	-0.0061	0.0038	0.0000	0.0000	0.0000	-0.0091
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0061	0.0038	0.0000	0.0000	0.0000	0.0042
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C6	Min Value	-0.1037	0.0053	0.0000	0.0000	0.0000	-0.0114
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.1037	0.0053	0.0000	0.0000	0.0000	0.0070
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C7	Min Value	0.0812	0.0223	0.0000	0.0000	0.0000	-0.0422
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0812	0.0223	0.0000	0.0000	0.0000	0.0359
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C8	Min Value	0.0051	0.0583	0.0000	0.0000	0.0000	-0.1082
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0051	0.0583	0.0000	0.0000	0.0000	0.0959
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C5	Min Value	-0.0043	0.0004	0.0000	0.0000	0.0000	-0.0013
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0043	0.0004	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C6	Min Value	0.1044	0.0007	0.0000	0.0000	0.0000	-0.0025
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.1044	0.0007	0.0000	0.0000	0.0000	0.0000
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C7	Min Value	-0.0439	-0.0047	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0439	-0.0047	0.0000	0.0000	0.0000	0.0165
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD

Lampiran 43: Coding Matlab Menghitung F_U Kasus Kerusakan 8

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n8);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);

k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

E=2e8; %kN/m2
Ks=assf(K1, id1, dof);

```

```

Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);

m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);

Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(M\r\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(14, i); mode(26, i); m
ode(38, i); mode(50, i); mode(62
, i)]
v=sqrt(m(mode'*Mr*mode))
wm=di ag(w(1:84));
Fu8=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```


Lampiran 44: Coding Matlab Menghitung F_D Kasus Kerusakan 8

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11); %//----
-damage member ----//
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15); %//--
---damage member ----//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
Ad=A2*0.5; %//----damage
member ----//
I1=5.536e-4; %m4
I2=2.176e-4;
Id=I2*0.5; %//----damage
member ----//
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, Ad, Id, L5, f2, vs);
K5=kg(k5, T5); %//----damage
member ----//
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);

k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, Ad, Id, L40, f2, vs);
K40=kg(k40, T40); %//----
damage member ----//
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];
id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];
id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];

```

```

id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

Ks=assf(K1, i d1, dof);
Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*Ad, L5); %//----
damage member ----//
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);

m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);
m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*Ad, L40); %//----
damage member ----//
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);
Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(M\rKs)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(14, i); mode(26, i); m
ode(38, i); mode(50, i); mode(62
, i)]
v=sqrtm(mode'*Mr*mode)
wm=di ag(w(1:84));
Fd8=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```

Lampiran 45: *Coding* Matlab Menghitung SVD Kasus Kerusakan 8

```
Fu8 =1.0e-004 * [0.0469    0.0260    0.0279    0.0318    0.0349; 0.0260    0.0799  
0.0693    0.0801    0.0924; 0.0279    0.0693    0.1389    0.1434    0.1684; 0.0318  
0.0801    0.1434    0.2348    0.2575; 0.0349    0.0924    0.1684    0.2575    0.3768]  
  
Fd8 =1.0e-004 * [0.0470    0.0258    0.0276    0.0315    0.0346; 0.0258    0.0818  
0.0710    0.0818    0.0941; 0.0276    0.0710    0.1463    0.1499    0.1748; 0.0315  
0.0818    0.1499    0.2406    0.2631; 0.0346    0.0941    0.1748    0.2631    0.3823]  
Fdel =Fu8- Fd8  
[u, s, v]=svd(Fdel)
```



Lampiran 46: Coding Matlab Menghitung Gaya Batang Kasus Kerusakan 8

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11); %//---
-damage member ----//
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15); %//--
---damage member ----//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);

k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

```

```

Ks=assf(K1, i d1, dof);
Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);

m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);
m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);

Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);
Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(Mr\Ks);
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder);

i=1:84;
pi m=[mode(14, i); mode(26, i); m
ode(38, i); mode(50, i); mode(62
, i)];
v=sqrtm(mode'*Mr*mode);
wm=di ag(w(1:84));
Fu8=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))';

R=zeros(84, 1);
R(14, 1)=0.1455;
R(26, 1)=-0.1121;
R(38, 1)=-0.6773;
R(50, 1)=0.1206;
R(62, 1)=0.7021;

U=sol v(Ks, R);

u1=di ssf(U, i d1, T1);
u2=di ssf(U, i d2, T2);
u3=di ssf(U, i d3, T3);
u4=di ssf(U, i d4, T4);
u5=di ssf(U, i d5, T5);
u6=di ssf(U, i d6, T6);
u7=di ssf(U, i d7, T7);
u8=di ssf(U, i d8, T8);
u9=di ssf(U, i d9, T9);
u10=di ssf(U, i d10, T10);
u11=di ssf(U, i d11, T11);
u12=di ssf(U, i d12, T12);
u13=di ssf(U, i d13, T13);

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```

u14=di ssf(U, i d14, T14);
u15=di ssf(U, i d15, T15);

u16=di ssf(U, i d16, T16);
u17=di ssf(U, i d17, T17);
u18=di ssf(U, i d18, T18);
u19=di ssf(U, i d19, T19);
u20=di ssf(U, i d20, T20);
u21=di ssf(U, i d21, T21);
u22=di ssf(U, i d22, T22);
u23=di ssf(U, i d23, T23);
u24=di ssf(U, i d24, T24);
u25=di ssf(U, i d25, T25);
u26=di ssf(U, i d26, T26);
u27=di ssf(U, i d27, T27);
u28=di ssf(U, i d28, T28);
u29=di ssf(U, i d29, T29);
u30=di ssf(U, i d30, T30);
u31=di ssf(U, i d31, T31);
u32=di ssf(U, i d32, T32);
u33=di ssf(U, i d33, T33);
u34=di ssf(U, i d34, T34);
u35=di ssf(U, i d35, T35);

u36=di ssf(U, i d36, T36);
u37=di ssf(U, i d37, T37);
u38=di ssf(U, i d38, T38);
u39=di ssf(U, i d39, T39);
u40=di ssf(U, i d40, T40);
u41=di ssf(U, i d41, T41);
u42=di ssf(U, i d42, T42);
u43=di ssf(U, i d43, T43);
u44=di ssf(U, i d44, T44);
u45=di ssf(U, i d45, T45);

So1=zeros(6, 1);
So2=zeros(6, 1);
So3=zeros(6, 1);
So4=zeros(6, 1);
So5=zeros(6, 1);
So6=zeros(6, 1);
So7=zeros(6, 1);
So8=zeros(6, 1);
So9=zeros(6, 1);
So10=zeros(6, 1);
So11=zeros(6, 1);
So12=zeros(6, 1);
So13=zeros(6, 1);
So14=zeros(6, 1);
So15=zeros(6, 1);
So16=zeros(6, 1);
So17=zeros(6, 1);
So18=zeros(6, 1);
So19=zeros(6, 1);
So20=zeros(6, 1);
So21=zeros(6, 1);
So22=zeros(6, 1);
So23=zeros(6, 1);
So24=zeros(6, 1);
So25=zeros(6, 1);
So26=zeros(6, 1);
So27=zeros(6, 1);
So28=zeros(6, 1);
So29=zeros(6, 1);
So30=zeros(6, 1);
So31=zeros(6, 1);
So32=zeros(6, 1);
So33=zeros(6, 1);
So34=zeros(6, 1);
So35=zeros(6, 1);
So36=zeros(6, 1);
So37=zeros(6, 1);
So38=zeros(6, 1);
So39=zeros(6, 1);
So40=zeros(6, 1);
So41=zeros(6, 1);
So42=zeros(6, 1);

So43=zeros(6, 1);
So44=zeros(6, 1);
So45=zeros(6, 1);

S1=stref(k1, u1, So1)
S2=stref(k2, u2, So2)
S3=stref(k3, u3, So3)
S4=stref(k4, u4, So4)
S5=stref(k5, u5, So5)
S6=stref(k6, u6, So6)
S7=stref(k7, u7, So7)
S8=stref(k8, u8, So8)
S9=stref(k9, u9, So9)
S10=stref(k10, u10, So10)
S11=stref(k11, u11, So11)
S12=stref(k12, u12, So12)
S13=stref(k13, u13, So13)
S14=stref(k14, u14, So14)
S15=stref(k15, u15, So15)

S16=stref(k16, u16, So16)
S17=stref(k17, u17, So17)
S18=stref(k18, u18, So18)
S19=stref(k19, u19, So19)
S20=stref(k20, u20, So20)
S21=stref(k21, u21, So21)
S22=stref(k22, u22, So22)
S23=stref(k23, u23, So23)
S24=stref(k24, u24, So24)
S25=stref(k25, u25, So25)
S26=stref(k26, u26, So26)
S27=stref(k27, u27, So27)
S28=stref(k28, u28, So28)
S29=stref(k29, u29, So29)
S30=stref(k30, u30, So30)
S31=stref(k31, u31, So31)
S32=stref(k32, u32, So32)
S33=stref(k33, u33, So33)
S34=stref(k34, u34, So34)
S35=stref(k35, u35, So35)

S36=stref(k36, u36, So36)
S37=stref(k37, u37, So37)
S38=stref(k38, u38, So38)
S39=stref(k39, u39, So39)
S40=stref(k40, u40, So40)
S41=stref(k41, u41, So41)
S42=stref(k42, u42, So42)
S43=stref(k43, u43, So43)
S44=stref(k44, u44, So44)
S45=stref(k45, u45, So45)

```

Lampiran 47: *Output* Gaya-gaya Batang dari *software* Matlab Kasus 8

S1 =	0.0174	0.7534	-0.0280	-0.0000
0.0072	0.0017	0.0052	0.0591	-0.0000
-0.0058	-0.0060	0.0163	S33 =	-0.4653
-0.0175	S12 =	-0.7534	-0.1004	0.0000
-0.0072	-0.1057	-0.0052	0.0267	-0.0000
0.0058	-0.0285	0.0019	0.0403	S44 =
-0.0176	-0.0814	S23 =	0.1004	-0.4342
S2 =	0.1057	0.0792	-0.0267	-0.0000
-0.0470	0.0285	0.0058	0.0531	-0.0000
0.0005	-0.0896	0.0060	S34 =	0.4342
0.0016	S13 =	-0.0792	0.1931	0.0000
0.0470	-0.0280	-0.0058	0.0313	-0.0000
-0.0005	-0.0199	0.0143	0.0470	S45 =
0.0016	-0.0591	S24 =	-0.1931	0.2433
S3 =	0.0280	-0.0619	-0.0313	-0.0000
-0.1482	0.0199	0.0124	0.0625	-0.0000
-0.0057	-0.0605	0.0335	S35 =	-0.2433
-0.0173	S14 =	0.0619	0.0234	0.0000
0.1482	-0.2649	-0.0124	0.0309	-0.0000
0.0057	0.0022	0.0100	0.0362	
-0.0169	0.0074	S25 =	-0.0234	
S4 =	0.2649	-0.7620	-0.0309	
0.0061	-0.0022	0.0119	0.0720	
-0.0118	0.0060	0.0322	S36 =	
-0.0353	S15 =	0.7620	-0.1192	
-0.0061	-0.6712	-0.0119	0.0000	
0.0118	-0.0234	0.0096	0.0000	
-0.0355	-0.0685	S26 =	0.1192	
S5 =	0.6712	0.6813	-0.0000	
0.0187	0.0234	0.0045	0.0000	
0.0011	-0.0720	0.0217	S37 =	
0.0027	S16 =	-0.6813	0.0866	
-0.0187	-0.0795	-0.0045	-0.0000	
-0.0011	-0.0008	-0.0060	0	
0.0038	-0.0000	S27 =	-0.0866	
S6 =	0.0795	0.0710	0.0000	
0.1299	0.0008	-0.0120	0	
-0.0082	-0.0029	0.0075	S38 =	
-0.0274	S17 =	-0.0710	-0.0159	
-0.1299	-0.7940	0.0120	0	
0.0082	-0.0011	-0.0495	0.0000	
-0.0219	-0.0000	S28 =	0.0159	
S7 =	0.7940	-0.0432	0	
0.0096	0.0011	0.0220	0.0000	
-0.0187	-0.0037	0.0462	S39 =	
-0.0562	S18 =	0.0432	-0.0042	
-0.0096	0.8051	-0.0220	-0.0000	
0.0187	-0.0002	0.0309	0	
-0.0561	0.0000	S29 =	0.0042	
S8 =	-0.8051	-0.5321	0.0000	
0.1951	0.0002	0.0231	0.0000	
-0.0004	-0.0006	0.0476	S40 =	
-0.0011	S19 =	0.5321	-0.0033	
-0.1951	0.0849	-0.0231	-0.0000	
0.0004	0.0031	0.0333	-0.0000	
-0.0011	-0.0000	S30 =	0.0033	
S9 =	-0.0849	0.4639	0.0000	
0.6194	-0.0031	0.0297	-0.0000	
-0.0190	0.0109	0.0636	S41 =	
-0.0565	S20 =	-0.4639	0.1455	
-0.6194	-0.0737	-0.0297	-0.0000	
0.0190	0.0063	0.0404	0.0000	
-0.0577	0.0205	S31 =	-0.1455	
S10 =	0.0737	0.0519	0.0000	
0.0060	-0.0063	0.0459	0.0000	
-0.0233	0.0018	0.1072	S42 =	
-0.0699	S21 =	-0.0519	-0.3473	
-0.0060	-0.7487	-0.0459	-0.0000	
0.0233	0.0058	0.0534	-0.0000	
-0.0697	0.0197	S32 =	0.3473	
S11 =	0.7487	-0.0199	0.0000	
-0.0174	-0.0058	0.0280	-0.0000	
-0.0017	0.0006	0.0390	S43 =	
-0.0039	S22 =	0.0199	0.4653	

Lampiran 48: *Output* Gaya-gaya Batang dari *software* ETABS Kasus 8

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C O L U M N F O R C E E N V E L O P E S

STORY	COLUMN	ITEM	P	V2	V3	T	M2	M3
LT5	C5	Min Value	0.0199	0.0280	0.0000	0.0000	0.0000	-0.0591
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0199	0.0280	0.0000	0.0000	0.0000	0.0390
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C6	Min Value	0.1004	0.0267	0.0000	0.0000	0.0000	-0.0531
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.1004	0.0267	0.0000	0.0000	0.0000	0.0403
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C7	Min Value	-0.1931	0.0313	0.0000	0.0000	0.0000	-0.0625
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.1931	0.0313	0.0000	0.0000	0.0000	0.0470
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C8	Min Value	-0.0234	0.0309	0.0000	0.0000	0.0000	-0.0720
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0234	0.0309	0.0000	0.0000	0.0000	0.0363
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C5	Min Value	0.0432	0.0220	0.0000	0.0000	0.0000	-0.0309
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0432	0.0220	0.0000	0.0000	0.0000	0.0462
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C6	Min Value	0.5320	0.0231	0.0000	0.0000	0.0000	-0.0333
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.5320	0.0231	0.0000	0.0000	0.0000	0.0476
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C7	Min Value	-0.4639	0.0297	0.0000	0.0000	0.0000	-0.0404
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.4639	0.0297	0.0000	0.0000	0.0000	0.0635
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C8	Min Value	-0.0519	0.0458	0.0000	0.0000	0.0000	-0.0533
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0519	0.0458	0.0000	0.0000	0.0000	0.1071
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C5	Min Value	0.0619	0.0125	0.0000	0.0000	0.0000	-0.0100
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0619	0.0125	0.0000	0.0000	0.0000	0.0336
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C6	Min Value	0.7620	0.0119	0.0000	0.0000	0.0000	-0.0096
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.7620	0.0119	0.0000	0.0000	0.0000	0.0322
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C7	Min Value	-0.6813	0.0045	0.0000	0.0000	0.0000	0.0059
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.6813	0.0045	0.0000	0.0000	0.0000	0.0217
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C8	Min Value	-0.0710	-0.0119	0.0000	0.0000	0.0000	0.0076
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0710	-0.0119	0.0000	0.0000	0.0000	0.0494
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C5	Min Value	0.0737	0.0064	0.0000	0.0000	0.0000	-0.0018
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0737	0.0064	0.0000	0.0000	0.0000	0.0205
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C6	Min Value	0.7486	0.0058	0.0000	0.0000	0.0000	-0.0006
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.7486	0.0058	0.0000	0.0000	0.0000	0.0197
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C7	Min Value	-0.7533	0.0052	0.0000	0.0000	0.0000	-0.0019
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.7533	0.0052	0.0000	0.0000	0.0000	0.0163
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C8	Min Value	-0.0792	0.0058	0.0000	0.0000	0.0000	-0.0143
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0792	0.0058	0.0000	0.0000	0.0000	0.0061
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C5	Min Value	0.0796	-0.0008	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0796	-0.0008	0.0000	0.0000	0.0000	0.0030
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C6	Min Value	0.7939	-0.0011	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.7939	-0.0011	0.0000	0.0000	0.0000	0.0038
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C7	Min Value	-0.8050	-0.0002	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.8050	-0.0002	0.0000	0.0000	0.0000	0.0007
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD

Lampiran 49: Coding Matlab Menghitung F_U Kasus Kerusakan 9

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5);
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n8);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15);
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);

k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];

id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];

id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

E=2e8; %kN/m2
Ks=assf(K1, id1, dof);

```

```

Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);

m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);
Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);

Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(M\r\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(14, i); mode(26, i); m
ode(38, i); mode(50, i); mode(62
, i)]
v=sqrt(m(mode'*Mr*mode))
wm=di ag(w(1:84));
Fu9=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```

Lampiran 50: Coding Matlab Menghitung F_D Kasus Kerusakan 9

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5); %//----
-damage member ----//
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15); %//--
---damage member ----//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
Adb=A2*0.5; %//----damage
member ----//
Adk=A1*0.5; %//----damage
member ----//
I1=5.536e-4; %m4
I2=2.176e-4;
Idb=I2*0.5; %//----damage
member ----//
Idk=I1*0.5; %//----damage
member ----//
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);

k16=kl fs(E, Adk, Idk, L16, f1, vs);
K16=kg(k16, T16); %//----
damage member ----//
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);

k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);

k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, Adb, Idb, L40, f2, vs);
K40=kg(k40, T40); %//----
damage member ----//
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];
id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];
id36=[0 0 65 11 12 68];

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id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

Ks=assf(K1, id1, dof);
Ks=Ks+assf(K2, id2, dof);
Ks=Ks+assf(K3, id3, dof);
Ks=Ks+assf(K4, id4, dof);
Ks=Ks+assf(K5, id5, dof);
Ks=Ks+assf(K6, id6, dof);
Ks=Ks+assf(K7, id7, dof);
Ks=Ks+assf(K8, id8, dof);
Ks=Ks+assf(K9, id9, dof);
Ks=Ks+assf(K10, id10, dof);
Ks=Ks+assf(K11, id11, dof);
Ks=Ks+assf(K12, id12, dof);
Ks=Ks+assf(K13, id13, dof);
Ks=Ks+assf(K14, id14, dof);
Ks=Ks+assf(K15, id15, dof);

Ks=Ks+assf(K16, id16, dof);
Ks=Ks+assf(K17, id17, dof);
Ks=Ks+assf(K18, id18, dof);
Ks=Ks+assf(K19, id19, dof);
Ks=Ks+assf(K20, id20, dof);
Ks=Ks+assf(K21, id21, dof);
Ks=Ks+assf(K22, id22, dof);
Ks=Ks+assf(K23, id23, dof);
Ks=Ks+assf(K24, id24, dof);
Ks=Ks+assf(K25, id25, dof);
Ks=Ks+assf(K26, id26, dof);
Ks=Ks+assf(K27, id27, dof);
Ks=Ks+assf(K28, id28, dof);
Ks=Ks+assf(K29, id29, dof);
Ks=Ks+assf(K30, id30, dof);
Ks=Ks+assf(K31, id31, dof);
Ks=Ks+assf(K32, id32, dof);
Ks=Ks+assf(K33, id33, dof);
Ks=Ks+assf(K34, id34, dof);
Ks=Ks+assf(K35, id35, dof);

Ks=Ks+assf(K36, id36, dof);
Ks=Ks+assf(K37, id37, dof);
Ks=Ks+assf(K38, id38, dof);
Ks=Ks+assf(K39, id39, dof);
Ks=Ks+assf(K40, id40, dof);
Ks=Ks+assf(K41, id41, dof);
Ks=Ks+assf(K42, id42, dof);
Ks=Ks+assf(K43, id43, dof);
Ks=Ks+assf(K44, id44, dof);
Ks=Ks+assf(K45, id45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*Adk, L16); %//-----
damage member -----//
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);
m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);
m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40); %//-----
damage member -----//
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);

M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, id1, dof);
Mr=Mr+assf(M2, id2, dof);
Mr=Mr+assf(M3, id3, dof);
Mr=Mr+assf(M4, id4, dof);
Mr=Mr+assf(M5, id5, dof);
Mr=Mr+assf(M6, id6, dof);
Mr=Mr+assf(M7, id7, dof);
Mr=Mr+assf(M8, id8, dof);
Mr=Mr+assf(M9, id9, dof);
Mr=Mr+assf(M10, id10, dof);
Mr=Mr+assf(M11, id11, dof);
Mr=Mr+assf(M12, id12, dof);
Mr=Mr+assf(M13, id13, dof);
Mr=Mr+assf(M14, id14, dof);
Mr=Mr+assf(M15, id15, dof);

Mr=Mr+assf(M16, id16, dof);
Mr=Mr+assf(M17, id17, dof);
Mr=Mr+assf(M18, id18, dof);
Mr=Mr+assf(M19, id19, dof);
Mr=Mr+assf(M20, id20, dof);
Mr=Mr+assf(M21, id21, dof);
Mr=Mr+assf(M22, id22, dof);
Mr=Mr+assf(M23, id23, dof);
Mr=Mr+assf(M24, id24, dof);
Mr=Mr+assf(M25, id25, dof);
Mr=Mr+assf(M26, id26, dof);
Mr=Mr+assf(M27, id27, dof);
Mr=Mr+assf(M28, id28, dof);
Mr=Mr+assf(M29, id29, dof);
Mr=Mr+assf(M30, id30, dof);
Mr=Mr+assf(M31, id31, dof);
Mr=Mr+assf(M32, id32, dof);
Mr=Mr+assf(M33, id33, dof);
Mr=Mr+assf(M34, id34, dof);
Mr=Mr+assf(M35, id35, dof);

Mr=Mr+assf(M36, id36, dof);
Mr=Mr+assf(M37, id37, dof);
Mr=Mr+assf(M38, id38, dof);
Mr=Mr+assf(M39, id39, dof);
Mr=Mr+assf(M40, id40, dof);
Mr=Mr+assf(M41, id41, dof);
Mr=Mr+assf(M42, id42, dof);
Mr=Mr+assf(M43, id43, dof);
Mr=Mr+assf(M44, id44, dof);
Mr=Mr+assf(M45, id45, dof);

[ei gv, ei gval]=ei g(Mr\Ks)
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder)

i=1:84;
pi m=[mode(14, i); mode(26, i); m
ode(38, i); mode(50, i); mode(62
, i)]
v=sqrtm(mode'*Mr*mode)
wm=di ag(w(1:84));
Fd9=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))'

```

Lampiran 51: *Coding* Matlab Menghitung SVD Kasus Kerusakan 9

```
Fu9 =1.0e-004 * [0.0469    0.0260    0.0279    0.0318    0.0349; 0.0260    0.0799  
0.0693    0.0801    0.0924; 0.0279    0.0693    0.1389    0.1434    0.1684; 0.0318  
0.0801    0.1434    0.2348    0.2575; 0.0349    0.0924    0.1684    0.2575    0.3768]
```

```
Fd9 =1.0e-004 * [0.0470    0.0260    0.0276    0.0316    0.0347; 0.0260    0.0801  
0.0706    0.0814    0.0937; 0.0276    0.0706    0.1463    0.1499    0.1748; 0.0316  
0.0814    0.1499    0.2406    0.2632; 0.0347    0.0937    0.1748    0.2632    0.3825]
```

```
Fdel =Fu9- Fd9  
[u, s, v]=svd(Fdel)
```



Lampiran 52: Coding Matlab Menghitung Gaya Batang Kasus Kerusakan 9

```

n1=coor(0, 0);
n2=coor(6, 0);
n3=coor(12, 0);
n4=coor(18, 0);

n5=coor(0, 3.5);
n6=coor(6, 3.5);
n7=coor(12, 3.5);
n8=coor(18, 3.5);

n9=coor(0, 7);
n10=coor(6, 7);
n11=coor(12, 7);
n12=coor(18, 7);

n13=coor(0, 10.5);
n14=coor(6, 10.5);
n15=coor(12, 10.5);
n16=coor(18, 10.5);

n17=coor(0, 14);
n18=coor(6, 14);
n19=coor(12, 14);
n20=coor(18, 14);

n21=coor(0, 17.5);
n22=coor(6, 17.5);
n23=coor(12, 17.5);
n24=coor(18, 17.5);

[L1, T1]=memf(n5, n6);
[L2, T2]=memf(n6, n7);
[L3, T3]=memf(n7, n8);
[L4, T4]=memf(n9, n10);
[L5, T5]=memf(n10, n11);
[L6, T6]=memf(n11, n12);
[L7, T7]=memf(n13, n14);
[L8, T8]=memf(n14, n15);
[L9, T9]=memf(n15, n16);
[L10, T10]=memf(n17, n18);
[L11, T11]=memf(n18, n19);
[L12, T12]=memf(n19, n20);
[L13, T13]=memf(n21, n22);
[L14, T14]=memf(n22, n23);
[L15, T15]=memf(n23, n24);
[L16, T16]=memf(n1, n5); %/--
-- damage member ----//
[L17, T17]=memf(n2, n6);
[L18, T18]=memf(n3, n7);
[L19, T19]=memf(n4, n8);
[L20, T20]=memf(n5, n9);
[L21, T21]=memf(n6, n10);
[L22, T22]=memf(n7, n11);
[L23, T23]=memf(n8, n12);
[L24, T24]=memf(n9, n13);
[L25, T25]=memf(n10, n14);
[L26, T26]=memf(n11, n15);
[L27, T27]=memf(n12, n16);
[L28, T28]=memf(n13, n17);
[L29, T29]=memf(n14, n18);
[L30, T30]=memf(n15, n19);
[L31, T31]=memf(n16, n20);
[L32, T32]=memf(n17, n21);
[L33, T33]=memf(n18, n22);
[L34, T34]=memf(n19, n23);
[L35, T35]=memf(n20, n24);
[L36, T36]=memf(n2, n7);
[L37, T37]=memf(n3, n6);
[L38, T38]=memf(n6, n11);
[L39, T39]=memf(n7, n10);
[L40, T40]=memf(n10, n15); %/--
--- damage member ----//
[L41, T41]=memf(n11, n14);
[L42, T42]=memf(n14, n19);
[L43, T43]=memf(n15, n18);
[L44, T44]=memf(n18, n23);
[L45, T45]=memf(n19, n22);

E=2e8; %kN/m2
A1=0.0144; %m2%Kolom
A2=0.0121; %Balok dan bracing
I1=5.536e-4; %m4
I2=2.176e-4;
r=78.5; %kN/m3
vs=0.3;
f1=2.884; %Kolom
f2=3.975; %Balok dan bracing

k1=kl fs(E, A2, I2, L1, f2, vs);
K1=kg(k1, T1);
k2=kl fs(E, A2, I2, L2, f2, vs);
K2=kg(k2, T2);
k3=kl fs(E, A2, I2, L3, f2, vs);
K3=kg(k3, T3);
k4=kl fs(E, A2, I2, L4, f2, vs);
K4=kg(k4, T4);
k5=kl fs(E, A2, I2, L5, f2, vs);
K5=kg(k5, T5);
k6=kl fs(E, A2, I2, L6, f2, vs);
K6=kg(k6, T6);
k7=kl fs(E, A2, I2, L7, f2, vs);
K7=kg(k7, T7);
k8=kl fs(E, A2, I2, L8, f2, vs);
K8=kg(k8, T8);
k9=kl fs(E, A2, I2, L9, f2, vs);
K9=kg(k9, T9);
k10=kl fs(E, A2, I2, L10, f2, vs);
K10=kg(k10, T10);
k11=kl fs(E, A2, I2, L11, f2, vs);
K11=kg(k11, T11);
k12=kl fs(E, A2, I2, L12, f2, vs);
K12=kg(k12, T12);
k13=kl fs(E, A2, I2, L13, f2, vs);
K13=kg(k13, T13);
k14=kl fs(E, A2, I2, L14, f2, vs);
K14=kg(k14, T14);
k15=kl fs(E, A2, I2, L15, f2, vs);
K15=kg(k15, T15);
k16=kl fs(E, A1, I1, L16, f1, vs);
K16=kg(k16, T16);
k17=kl fs(E, A1, I1, L17, f1, vs);
K17=kg(k17, T17);
k18=kl fs(E, A1, I1, L18, f1, vs);
K18=kg(k18, T18);
k19=kl fs(E, A1, I1, L19, f1, vs);
K19=kg(k19, T19);
k20=kl fs(E, A1, I1, L20, f1, vs);
K20=kg(k20, T20);
k21=kl fs(E, A1, I1, L21, f1, vs);
K21=kg(k21, T21);
k22=kl fs(E, A1, I1, L22, f1, vs);
K22=kg(k22, T22);
k23=kl fs(E, A1, I1, L23, f1, vs);
K23=kg(k23, T23);
k24=kl fs(E, A1, I1, L24, f1, vs);
K24=kg(k24, T24);
k25=kl fs(E, A1, I1, L25, f1, vs);
K25=kg(k25, T25);
k26=kl fs(E, A1, I1, L26, f1, vs);
K26=kg(k26, T26);
k27=kl fs(E, A1, I1, L27, f1, vs);
K27=kg(k27, T27);
k28=kl fs(E, A1, I1, L28, f1, vs);
K28=kg(k28, T28);
k29=kl fs(E, A1, I1, L29, f1, vs);
K29=kg(k29, T29);
k30=kl fs(E, A1, I1, L30, f1, vs);
K30=kg(k30, T30);
k31=kl fs(E, A1, I1, L31, f1, vs);
K31=kg(k31, T31);
k32=kl fs(E, A1, I1, L32, f1, vs);
K32=kg(k32, T32);
k33=kl fs(E, A1, I1, L33, f1, vs);
K33=kg(k33, T33);
k34=kl fs(E, A1, I1, L34, f1, vs);
K34=kg(k34, T34);
k35=kl fs(E, A1, I1, L35, f1, vs);
K35=kg(k35, T35);
k36=kl fs(E, A2, I2, L36, f2, vs);
K36=kg(k36, T36);
k37=kl fs(E, A2, I2, L37, f2, vs);
K37=kg(k37, T37);
k38=kl fs(E, A2, I2, L38, f2, vs);
K38=kg(k38, T38);
k39=kl fs(E, A2, I2, L39, f2, vs);
K39=kg(k39, T39);
k40=kl fs(E, A2, I2, L40, f2, vs);
K40=kg(k40, T40);
k41=kl fs(E, A2, I2, L41, f2, vs);
K41=kg(k41, T41);
k42=kl fs(E, A2, I2, L42, f2, vs);
K42=kg(k42, T42);
k43=kl fs(E, A2, I2, L43, f2, vs);
K43=kg(k43, T43);
k44=kl fs(E, A2, I2, L44, f2, vs);
K44=kg(k44, T44);
k45=kl fs(E, A2, I2, L45, f2, vs);
K45=kg(k45, T45);

dof=84;
id1=[5 6 7 8 9 10];
id2=[8 9 10 11 12 13];
id3=[11 12 13 14 15 16];
id4=[17 18 19 20 21 22];
id5=[20 21 22 23 24 25];
id6=[23 24 25 26 27 28];
id7=[29 30 31 32 33 34];
id8=[32 33 34 35 36 37];
id9=[35 36 37 38 39 40];
id10=[41 42 43 44 45 46];
id11=[44 45 46 47 48 49];
id12=[47 48 49 50 51 52];
id13=[53 54 55 56 57 58];
id14=[56 57 58 59 60 61];
id15=[59 60 61 62 63 64];
id16=[0 0 1 5 6 7];
id17=[0 0 2 8 9 10];
id18=[0 0 3 11 12 13];
id19=[0 0 4 14 15 16];
id20=[5 6 7 17 18 19];
id21=[8 9 10 20 21 22];
id22=[11 12 13 23 24 25];
id23=[14 15 16 26 27 28];
id24=[17 18 19 29 30 31];
id25=[20 21 22 32 33 34];
id26=[23 24 25 35 36 37];
id27=[26 27 28 38 39 40];
id28=[29 30 31 41 42 43];
id29=[32 33 34 44 45 46];
id30=[35 36 37 47 48 49];
id31=[38 39 40 50 51 52];
id32=[41 42 43 53 54 55];
id33=[44 45 46 56 57 58];
id34=[47 48 49 59 60 61];
id35=[50 51 52 62 63 64];
id36=[0 0 65 11 12 68];
id37=[0 0 66 8 9 67];
id38=[8 9 69 23 24 72];
id39=[11 12 70 20 21 71];
id40=[20 21 73 35 36 76];
id41=[23 24 74 32 33 75];
id42=[32 33 77 47 48 80];
id43=[35 36 78 44 45 79];
id44=[44 45 81 59 60 84];
id45=[47 48 82 56 57 83];

```



```

Ks=assf(K1, i d1, dof);
Ks=Ks+assf(K2, i d2, dof);
Ks=Ks+assf(K3, i d3, dof);
Ks=Ks+assf(K4, i d4, dof);
Ks=Ks+assf(K5, i d5, dof);
Ks=Ks+assf(K6, i d6, dof);
Ks=Ks+assf(K7, i d7, dof);
Ks=Ks+assf(K8, i d8, dof);
Ks=Ks+assf(K9, i d9, dof);
Ks=Ks+assf(K10, i d10, dof);
Ks=Ks+assf(K11, i d11, dof);
Ks=Ks+assf(K12, i d12, dof);
Ks=Ks+assf(K13, i d13, dof);
Ks=Ks+assf(K14, i d14, dof);
Ks=Ks+assf(K15, i d15, dof);

Ks=Ks+assf(K16, i d16, dof);
Ks=Ks+assf(K17, i d17, dof);
Ks=Ks+assf(K18, i d18, dof);
Ks=Ks+assf(K19, i d19, dof);
Ks=Ks+assf(K20, i d20, dof);
Ks=Ks+assf(K21, i d21, dof);
Ks=Ks+assf(K22, i d22, dof);
Ks=Ks+assf(K23, i d23, dof);
Ks=Ks+assf(K24, i d24, dof);
Ks=Ks+assf(K25, i d25, dof);
Ks=Ks+assf(K26, i d26, dof);
Ks=Ks+assf(K27, i d27, dof);
Ks=Ks+assf(K28, i d28, dof);
Ks=Ks+assf(K29, i d29, dof);
Ks=Ks+assf(K30, i d30, dof);
Ks=Ks+assf(K31, i d31, dof);
Ks=Ks+assf(K32, i d32, dof);
Ks=Ks+assf(K33, i d33, dof);
Ks=Ks+assf(K34, i d34, dof);
Ks=Ks+assf(K35, i d35, dof);

Ks=Ks+assf(K36, i d36, dof);
Ks=Ks+assf(K37, i d37, dof);
Ks=Ks+assf(K38, i d38, dof);
Ks=Ks+assf(K39, i d39, dof);
Ks=Ks+assf(K40, i d40, dof);
Ks=Ks+assf(K41, i d41, dof);
Ks=Ks+assf(K42, i d42, dof);
Ks=Ks+assf(K43, i d43, dof);
Ks=Ks+assf(K44, i d44, dof);
Ks=Ks+assf(K45, i d45, dof);

rho=8.002;

m1=ml f(rho*A2, L1);
m2=ml f(rho*A2, L2);
m3=ml f(rho*A2, L3);
m4=ml f(rho*A2, L4);
m5=ml f(rho*A2, L5);
m6=ml f(rho*A2, L6);
m7=ml f(rho*A2, L7);
m8=ml f(rho*A2, L8);
m9=ml f(rho*A2, L9);
m10=ml f(rho*A2, L10);
m11=ml f(rho*A2, L11);
m12=ml f(rho*A2, L12);
m13=ml f(rho*A2, L13);
m14=ml f(rho*A2, L14);
m15=ml f(rho*A2, L15);

m16=ml f(rho*A1, L16);
m17=ml f(rho*A1, L17);
m18=ml f(rho*A1, L18);
m19=ml f(rho*A1, L19);
m20=ml f(rho*A1, L20);
m21=ml f(rho*A1, L21);
m22=ml f(rho*A1, L22);
m23=ml f(rho*A1, L23);
m24=ml f(rho*A1, L24);
m25=ml f(rho*A1, L25);

m26=ml f(rho*A1, L26);
m27=ml f(rho*A1, L27);
m28=ml f(rho*A1, L28);
m29=ml f(rho*A1, L29);
m30=ml f(rho*A1, L30);
m31=ml f(rho*A1, L31);
m32=ml f(rho*A1, L32);
m33=ml f(rho*A1, L33);
m34=ml f(rho*A1, L34);
m35=ml f(rho*A1, L35);

m36=ml f(rho*A2, L36);
m37=ml f(rho*A2, L37);
m38=ml f(rho*A2, L38);
m39=ml f(rho*A2, L39);
m40=ml f(rho*A2, L40);
m41=ml f(rho*A2, L41);
m42=ml f(rho*A2, L42);
m43=ml f(rho*A2, L43);
m44=ml f(rho*A2, L44);
m45=ml f(rho*A2, L45);

M1=kg(m1, T1);
M2=kg(m2, T2);
M3=kg(m3, T3);
M4=kg(m4, T4);
M5=kg(m5, T5);
M6=kg(m6, T6);
M7=kg(m7, T7);
M8=kg(m8, T8);
M9=kg(m9, T9);
M10=kg(m10, T10);
M11=kg(m11, T11);
M12=kg(m12, T12);
M13=kg(m13, T13);
M14=kg(m14, T14);
M15=kg(m15, T15);

M16=kg(m16, T16);
M17=kg(m17, T17);
M18=kg(m18, T18);
M19=kg(m19, T19);
M20=kg(m20, T20);
M21=kg(m21, T21);
M22=kg(m22, T22);
M23=kg(m23, T23);
M24=kg(m24, T24);
M25=kg(m25, T25);
M26=kg(m26, T26);
M27=kg(m27, T27);
M28=kg(m28, T28);
M29=kg(m29, T29);
M30=kg(m30, T30);
M31=kg(m31, T31);
M32=kg(m32, T32);
M33=kg(m33, T33);
M34=kg(m34, T34);
M35=kg(m35, T35);

M36=kg(m36, T36);
M37=kg(m37, T37);
M38=kg(m38, T38);
M39=kg(m39, T39);
M40=kg(m40, T40);
M41=kg(m41, T41);
M42=kg(m42, T42);
M43=kg(m43, T43);
M44=kg(m44, T44);
M45=kg(m45, T45);

Mr=assf(M1, i d1, dof);
Mr=Mr+assf(M2, i d2, dof);
Mr=Mr+assf(M3, i d3, dof);
Mr=Mr+assf(M4, i d4, dof);
Mr=Mr+assf(M5, i d5, dof);
Mr=Mr+assf(M6, i d6, dof);
Mr=Mr+assf(M7, i d7, dof);

Mr=Mr+assf(M8, i d8, dof);
Mr=Mr+assf(M9, i d9, dof);
Mr=Mr+assf(M10, i d10, dof);
Mr=Mr+assf(M11, i d11, dof);
Mr=Mr+assf(M12, i d12, dof);
Mr=Mr+assf(M13, i d13, dof);
Mr=Mr+assf(M14, i d14, dof);
Mr=Mr+assf(M15, i d15, dof);

Mr=Mr+assf(M16, i d16, dof);
Mr=Mr+assf(M17, i d17, dof);
Mr=Mr+assf(M18, i d18, dof);
Mr=Mr+assf(M19, i d19, dof);
Mr=Mr+assf(M20, i d20, dof);
Mr=Mr+assf(M21, i d21, dof);
Mr=Mr+assf(M22, i d22, dof);
Mr=Mr+assf(M23, i d23, dof);
Mr=Mr+assf(M24, i d24, dof);
Mr=Mr+assf(M25, i d25, dof);
Mr=Mr+assf(M26, i d26, dof);
Mr=Mr+assf(M27, i d27, dof);
Mr=Mr+assf(M28, i d28, dof);
Mr=Mr+assf(M29, i d29, dof);
Mr=Mr+assf(M30, i d30, dof);
Mr=Mr+assf(M31, i d31, dof);
Mr=Mr+assf(M32, i d32, dof);
Mr=Mr+assf(M33, i d33, dof);
Mr=Mr+assf(M34, i d34, dof);
Mr=Mr+assf(M35, i d35, dof);

Mr=Mr+assf(M36, i d36, dof);
Mr=Mr+assf(M37, i d37, dof);
Mr=Mr+assf(M38, i d38, dof);
Mr=Mr+assf(M39, i d39, dof);
Mr=Mr+assf(M40, i d40, dof);
Mr=Mr+assf(M41, i d41, dof);
Mr=Mr+assf(M42, i d42, dof);
Mr=Mr+assf(M43, i d43, dof);
Mr=Mr+assf(M44, i d44, dof);
Mr=Mr+assf(M45, i d45, dof);

[ei gv, ei gval]=ei g(Mr\Ks);
[w, worder]=sort(sqrt(di ag(ei
gval)));
mode=ei gv(:, worder);

i=1:84;
pi m=[mode(14, i); mode(26, i); m
ode(38, i); mode(50, i); mode(62
, i)];
v=sqrtm(mode'*Mr*mode);
wm=di ag(w(1:84));
Fu9=(pi m*i nv(v))*i nv(wm^2)*(
pi m*i nv(v))';

R=zeros(84, 1);
R(14, 1)=-0.5730;
R(26, 1)=0.2071;
R(38, 1)=-0.3429;
R(50, 1)=0.6382;
R(62, 1)=-0.3222;

U=sol v(Ks, R);

u1=di ssf(U, i d1, T1);
u2=di ssf(U, i d2, T2);
u3=di ssf(U, i d3, T3);
u4=di ssf(U, i d4, T4);
u5=di ssf(U, i d5, T5);
u6=di ssf(U, i d6, T6);
u7=di ssf(U, i d7, T7);
u8=di ssf(U, i d8, T8);
u9=di ssf(U, i d9, T9);
u10=di ssf(U, i d10, T10);
u11=di ssf(U, i d11, T11);
u12=di ssf(U, i d12, T12);
u13=di ssf(U, i d13, T13);

```

```

u14=di ssf(U, i d14, T14);
u15=di ssf(U, i d15, T15);

u16=di ssf(U, i d16, T16);
u17=di ssf(U, i d17, T17);
u18=di ssf(U, i d18, T18);
u19=di ssf(U, i d19, T19);
u20=di ssf(U, i d20, T20);
u21=di ssf(U, i d21, T21);
u22=di ssf(U, i d22, T22);
u23=di ssf(U, i d23, T23);
u24=di ssf(U, i d24, T24);
u25=di ssf(U, i d25, T25);
u26=di ssf(U, i d26, T26);
u27=di ssf(U, i d27, T27);
u28=di ssf(U, i d28, T28);
u29=di ssf(U, i d29, T29);
u30=di ssf(U, i d30, T30);
u31=di ssf(U, i d31, T31);
u32=di ssf(U, i d32, T32);
u33=di ssf(U, i d33, T33);
u34=di ssf(U, i d34, T34);
u35=di ssf(U, i d35, T35);

u36=di ssf(U, i d36, T36);
u37=di ssf(U, i d37, T37);
u38=di ssf(U, i d38, T38);
u39=di ssf(U, i d39, T39);
u40=di ssf(U, i d40, T40);
u41=di ssf(U, i d41, T41);
u42=di ssf(U, i d42, T42);
u43=di ssf(U, i d43, T43);
u44=di ssf(U, i d44, T44);
u45=di ssf(U, i d45, T45);

So1=zeros(6, 1);
So2=zeros(6, 1);
So3=zeros(6, 1);
So4=zeros(6, 1);
So5=zeros(6, 1);
So6=zeros(6, 1);
So7=zeros(6, 1);
So8=zeros(6, 1);
So9=zeros(6, 1);
So10=zeros(6, 1);
So11=zeros(6, 1);
So12=zeros(6, 1);
So13=zeros(6, 1);
So14=zeros(6, 1);
So15=zeros(6, 1);
So16=zeros(6, 1);
So17=zeros(6, 1);
So18=zeros(6, 1);
So19=zeros(6, 1);
So20=zeros(6, 1);
So21=zeros(6, 1);
So22=zeros(6, 1);
So23=zeros(6, 1);
So24=zeros(6, 1);
So25=zeros(6, 1);
So26=zeros(6, 1);
So27=zeros(6, 1);
So28=zeros(6, 1);
So29=zeros(6, 1);
So30=zeros(6, 1);
So31=zeros(6, 1);
So32=zeros(6, 1);
So33=zeros(6, 1);
So34=zeros(6, 1);
So35=zeros(6, 1);
So36=zeros(6, 1);
So37=zeros(6, 1);
So38=zeros(6, 1);
So39=zeros(6, 1);
So40=zeros(6, 1);
So41=zeros(6, 1);
So42=zeros(6, 1);

So43=zeros(6, 1);
So44=zeros(6, 1);
So45=zeros(6, 1);

S1=stref(k1, u1, So1)
S2=stref(k2, u2, So2)
S3=stref(k3, u3, So3)
S4=stref(k4, u4, So4)
S5=stref(k5, u5, So5)
S6=stref(k6, u6, So6)
S7=stref(k7, u7, So7)
S8=stref(k8, u8, So8)
S9=stref(k9, u9, So9)
S10=stref(k10, u10, So10)
S11=stref(k11, u11, So11)
S12=stref(k12, u12, So12)
S13=stref(k13, u13, So13)
S14=stref(k14, u14, So14)
S15=stref(k15, u15, So15)

S16=stref(k16, u16, So16)
S17=stref(k17, u17, So17)
S18=stref(k18, u18, So18)
S19=stref(k19, u19, So19)
S20=stref(k20, u20, So20)
S21=stref(k21, u21, So21)
S22=stref(k22, u22, So22)
S23=stref(k23, u23, So23)
S24=stref(k24, u24, So24)
S25=stref(k25, u25, So25)
S26=stref(k26, u26, So26)
S27=stref(k27, u27, So27)
S28=stref(k28, u28, So28)
S29=stref(k29, u29, So29)
S30=stref(k30, u30, So30)
S31=stref(k31, u31, So31)
S32=stref(k32, u32, So32)
S33=stref(k33, u33, So33)
S34=stref(k34, u34, So34)
S35=stref(k35, u35, So35)

S36=stref(k36, u36, So36)
S37=stref(k37, u37, So37)
S38=stref(k38, u38, So38)
S39=stref(k39, u39, So39)
S40=stref(k40, u40, So40)
S41=stref(k41, u41, So41)
S42=stref(k42, u42, So42)
S43=stref(k43, u43, So43)
S44=stref(k44, u44, So44)
S45=stref(k45, u45, So45)

```

Lampiran 53: Output Gaya-gaya Batang dari software Matlab Kasus 9

```

S1 =          0. 2141          0. 0273          0. 0017          0. 0000
      0. 0014          -0. 0000          0. 0122          -0. 0027          0. 0000
      0. 0010          0. 0000          0. 0229          S33 =          -0. 1109
      0. 0030          S12 =          -0. 0273          0. 0870          -0. 0000
      -0. 0014          -0. 5470          -0. 0122          -0. 0022          0. 0000
      -0. 0010          -0. 0001          0. 0198          -0. 0039          S44 =
      0. 0029          0. 0004          S23 =          -0. 0870          0. 1330
S2 =          0. 5470          -0. 0053          0. 0022          0. 0000
      0. 1719          0. 0001          0. 0411          -0. 0038          0
      0. 0004          -0. 0010          0. 0710          S34 =          -0. 1330
      0. 0016          S13 =          0. 0053          -0. 0593          -0. 0000
      -0. 1719          0. 0017          -0. 0411          -0. 0169          0. 0000
      -0. 0004          0. 0009          0. 0730          -0. 0354          S45 =
      0. 0007          0. 0027          S24 =          0. 0593          -0. 1726
S3 =          -0. 0017          0. 0006          0. 0169          0. 0000
      0. 5125          -0. 0009          0. 0033          -0. 0239          0. 0000
      -0. 0007          0. 0025          0. 0060          S35 =          0. 0000
      -0. 0010          S14 =          -0. 0006          -0. 0086          -0. 0000
      -0. 5125          0. 1530          -0. 0033          -0. 0374          0. 0000
      0. 0007          0. 0009          0. 0054          -0. 0993          0. 0000
      -0. 0032          0. 0013          S25 =          0. 0086
S4 =          -0. 1530          -0. 0014          0. 0374
      0. 0036          -0. 0009          0. 0041          -0. 0315
      -0. 0006          0. 0038          0. 0074          S36 =
      -0. 0019          S15 =          0. 0014          0. 2685
      -0. 0036          0. 2848          -0. 0041          0. 0000
      0. 0006          0. 0086          0. 0069          0. 0000
      -0. 0019          0. 0200          S26 =          -0. 2685
S5 =          -0. 2848          -0. 0062          -0. 0000
      -0. 0837          -0. 0086          -0. 0101          0. 0000
      -0. 0004          0. 0315          -0. 0162          S37 =
      -0. 0013          S16 =          0. 0062          -0. 1521
      0. 0837          0. 0010          0. 0101          0. 0000
      0. 0004          -0. 0017          -0. 0193          0. 0000
      -0. 0013          0
S6 =          -0. 0010          S27 =          0. 1521
      -0. 1233          -0. 0062          -0. 0000
      -0. 0009          0. 0017          -0. 0427          0. 0000
      -0. 0023          -0. 0060          -0. 0697          S38 =
      0. 1233          S17 =          0. 0062          -0. 0437
      0. 0009          0. 0015          0. 0427          -0. 0000
      -0. 0033          -0. 0019          -0. 0797          -0. 0000
S7 =          0. 0000          S28 =          0. 0437
      -0. 0036          -0. 0015          0. 0014          0. 0000
      -0. 0008          0. 0019          -0. 0004          -0. 0000
      -0. 0023          -0. 0067          -0. 0031          S39 =
      0. 0036          S18 =          -0. 0014          0. 1042
      0. 0008          -0. 0566          0. 0004          -0. 0000
      -0. 0022          -0. 0065          0. 0018          -0. 0000
S8 =          0. 0000          S29 =          -0. 1042
      0. 1207          0. 0566          0. 0976          0. 0000
      -0. 0008          0. 0065          -0. 0001          -0. 0000
      -0. 0022          -0. 0226          -0. 0025          S40 =
      -0. 1207          S19 =          -0. 0976          0. 0022
      0. 0008          -0. 0045          0. 0001          -0. 0000
      -0. 0028          -0. 0194          0. 0021          -0. 0000
S9 =          -0. 0000          S30 =          -0. 0022
      0. 2464          0. 0045          -0. 0594          0. 0000
      -0. 0023          -0. 0194          0. 0179          -0. 0000
      -0. 0057          -0. 0679          0. 0277          S41 =
      -0. 2464          S20 =          0. 0594          0. 0237
      0. 0023          0. 0000          -0. 0179          -0. 0000
      -0. 0083          -0. 0003          0. 0349          -0. 0000
S10 =          0. 0030          S31 =          -0. 0237
      -0. 0000          -0. 0000          -0. 0085          0. 0000
      -0. 0014          0. 0003          0. 0538          -0. 0000
      0. 0005          -0. 0041          0. 0880          S42 =
      0. 0016          S21 =          0. 0085          -0. 1725
      0. 0014          -0. 0525          -0. 0538          -0. 0000
      -0. 0005          -0. 0006          0. 1003          0. 0000
      0. 0016          0. 0023          S32 =          0. 1725
S11 =          0. 0525          0. 0009          0. 0000
      -0. 2141          0. 0006          -0. 0017          0. 0000
      0. 0000          -0. 0043          -0. 0034          0. 0000
      0. 0001          S22 =          -0. 0009          S43 =          0. 1109

```

Lampiran 54: Output Gaya-gaya Batang dari software ETABS Kasus 9

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C O L U M N F O R C E E N V E L O P E S

STORY	COLUMN	ITEM	P	V2	V3	T	M2	M3
LT5	C5	Min Value	-0.0009	-0.0017	0.0000	0.0000	0.0000	-0.0034
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0009	-0.0017	0.0000	0.0000	0.0000	0.0027
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C6	Min Value	-0.0870	-0.0022	0.0000	0.0000	0.0000	-0.0038
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0870	-0.0022	0.0000	0.0000	0.0000	0.0038
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C7	Min Value	0.0593	-0.0169	0.0000	0.0000	0.0000	-0.0353
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0593	-0.0169	0.0000	0.0000	0.0000	0.0239
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT5	C8	Min Value	0.0086	-0.0373	0.0000	0.0000	0.0000	-0.0991
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0086	-0.0373	0.0000	0.0000	0.0000	0.0315
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C5	Min Value	-0.0014	-0.0004	0.0000	0.0000	0.0000	-0.0031
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0014	-0.0004	0.0000	0.0000	0.0000	-0.0018
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C6	Min Value	-0.0976	-0.0001	0.0000	0.0000	0.0000	-0.0025
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0976	-0.0001	0.0000	0.0000	0.0000	-0.0021
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C7	Min Value	0.0595	0.0179	0.0000	0.0000	0.0000	-0.0348
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0595	0.0179	0.0000	0.0000	0.0000	0.0277
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT4	C8	Min Value	0.0085	0.0537	0.0000	0.0000	0.0000	-0.1001
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0085	0.0537	0.0000	0.0000	0.0000	0.0878
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C5	Min Value	-0.0006	0.0033	0.0000	0.0000	0.0000	-0.0054
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0006	0.0033	0.0000	0.0000	0.0000	0.0060
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C6	Min Value	0.0014	0.0041	0.0000	0.0000	0.0000	-0.0069
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0014	0.0041	0.0000	0.0000	0.0000	0.0074
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C7	Min Value	0.0062	-0.0101	0.0000	0.0000	0.0000	-0.0162
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0062	-0.0101	0.0000	0.0000	0.0000	0.0192
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT3	C8	Min Value	0.0062	-0.0426	0.0000	0.0000	0.0000	-0.0696
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0062	-0.0426	0.0000	0.0000	0.0000	0.0796
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C5	Min Value	0.0000	-0.0003	0.0000	0.0000	0.0000	0.0030
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0000	-0.0003	0.0000	0.0000	0.0000	0.0041
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C6	Min Value	0.0525	-0.0006	0.0000	0.0000	0.0000	0.0022
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0525	-0.0006	0.0000	0.0000	0.0000	0.0043
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C7	Min Value	-0.0273	0.0122	0.0000	0.0000	0.0000	-0.0198
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0273	0.0122	0.0000	0.0000	0.0000	0.0228
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT2	C8	Min Value	0.0052	0.0411	0.0000	0.0000	0.0000	-0.0728
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0052	0.0411	0.0000	0.0000	0.0000	0.0709
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C5	Min Value	-0.0010	-0.0017	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0010	-0.0017	0.0000	0.0000	0.0000	0.0060
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C6	Min Value	-0.0015	-0.0019	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	-0.0015	-0.0019	0.0000	0.0000	0.0000	0.0067
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
LT1	C7	Min Value	0.0566	-0.0064	0.0000	0.0000	0.0000	0.0000
		Min Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD
		Max Value	0.0566	-0.0064	0.0000	0.0000	0.0000	0.0225
		Max Case	DEAD	DEAD	DEAD	DEAD	DEAD	DEAD

