

## BAB V

### KESIMPULAN DAN SARAN

#### 5.1 Kesimpulan

Penggunaan teknik kontrol getaran pasif khususnya untuk meredam getaran Indonesia jarang ditemukan. Padahal kalau dilihat lebih jauh Indonesia merupakan salah satu negara gempa yang sangat berbahaya karena dilalui oleh dua lempeng yang sangat aktif.

Pada tugas akhir ini perhitungan analisis struktur menggunakan perhitungan manual dengan menggunakan program MATLAB yang kemudian hasilnya dibandingkan dengan hasil perhitungan analisis struktur dengan menggunakan SAP 2000 versi 11. Gedung yang ditinjau adalah gedung dengan 12 lantai. Dalam perhitungan secara manual dengan menggunakan program MATLAB diperoleh hasil yang hampir sama dengan hasil yang diperoleh dari program SAP 2000 versi 11.

Peredam getaran *Tuned Mass Dampers* dipasang pada lantai 12. Kemudian nilai redaman dan kekakuan dioptimasi sehingga didapat nilai yang optimum. Setelah nilai redaman dan kekakuan didapat kemudian disimulasikan terhadap berbagai gempa yang tersedia yaitu gempa El Centro 1940 NS, gempa Kobe NS 1995, gempa Hachinohe 1968, dan gempa Northridge 1994. Hasil analisis menunjukkan bahwa peredam getaran yang direncanakan cukup efektif. Jika meninjau gempa Kobe perpindahan pada lantai 12 gedung dapat berkurang 17 % apabila dibandingkan tanpa *TMD*.

## **5.2 Saran**

Dalam penulisan tugas akhir ini ada beberapa saran dari penulis untuk pembaca khususnya untuk kalangan teknik sipil yaitu :

1. Dibutuhkan ketelitian yang ekstra dalam mengerjakan perhitungan analisis struktur dengan menggunakan program MATLAB.
2. Teknik-teknik perhitungan peredam getaran lainnya harus dikembangkan karena mengingat pentingnya peredam getaran untuk bangunan-bangunan bertingkat tinggi khususnya di Indonesia.
3. Perlu dicoba dengan menggunakan massa *TMD* yang berkisar 3-10 % dari massa seluruh gedung.
4. Perlu dicoba letak *TMD* pada lantai yang lainnya sehingga didapat nilai pengurangan perpindahan yang lebih optimum.

## DAFTAR PUSTAKA

- Ankireddi, S., and Yang, H. T. Y. (1997). "Multiple objective LQG control of wind-excited buildings." *J. Struct. Engrg.*, ASCE, 123(7), 943-951.
- Arfiadi, Y. (2000), Optimal passive and active control mechanisms for seismically excited buildings, PhD. Disertation University of Wolonggong.
- Arfiadi, Y. (2001), "Static and dynamics analysis of three dimensional buildings", *Jurnal Teknik Sipil*, Fakultas Teknik, Universitas Atma Jaya Yogyakarta (UAJY), vol. 1, pp 10-21.
- Arfiadi, Y. (2004), "Kontrol aktif pada struktur dengan menggunakan kontrol nonlinear untuk mengurangi getaran akibat gempa", Seminar Nasional Rekayasa Kegempaan, Yogyakarta, 20-21 Januari.
- Arfiadi, Y., and Hadi, M.N.S. (2000), "Passive and active control of three dimensional building", *Earthquake Engineering and Structural Dynamics*, vol. 29, 377-396.
- Arfiadi, Y., and Hadi, M.N.S. (2003), "Non linear controllers with bounded magnitude of control force", *The Ninth East Asia-Pasific Conference on Structural Engineering and Construction*, CPM107-CPM112, Bali, Indonesia.
- Arfiadi, Y., and Hadi, M.N.S. (2006), "Continous bounded controller for active control structures", *The International Journal of Computers and Structures*, 84, 798-807
- Chang, J. C. H., and Soong, T. T. (1980). "Structural control using active tuned mass dampers." *J. Engrg. Mech.*, ASCE, 106(6), 1091-1098.
- Clough, R. W., and Penzien, J. (1975). *Dynamics of structure*. McGraw-Hill, Kogkusha, Tokyo, Japan
- Den Hartog, J. P. (1947). *Mechanical Vibrations*. Mc Graw Hill, N.Y.
- Frahm, H. (1909). Device for damping of bodiees. U.S. Patent No. 989,958
- Gere., and Timoschenko. (1985). *Mechanic of material*, Wadsworth, Inc.

- Gluck, N., Reinhorn, A. M., Gluck, J., and Levy, R. (1996). "Design of supplemental damper for control of structures." *J. Struct. Engrg.*, ASCE, 122(12), 1394-1399.
- Golberg, D. E. (1989). *Genetic algorithms in search optimization and machine learning*. Addison-Wesley Publishing Co., Inc., Reading, Mass.
- Grefenstette, J. J. (1986). "Optimization of control parameters for genetic algorithms" *IEE Trans. On System, Man and Cybernetics*, SMC-16(1), 122-128
- Hadi, M. N. S., and Arfiadi, Y. (1998). "Optimum design absorber for MDOF structures." *Journal of Structural Engineering, American Society of Civil Engineers*, 124 (11), 1272-1280.
- Holland, J. H. (1992). *Adaptation in natural and artificial systems*, MIT Press, Cambridge, Mass
- Jabbari, F., Schmitendorf, W. E., and Yang, J. N. (1995). " $H_{\infty}$  control for seismic-excited buildings with acceleration feedback." *J. Engrg. Mech.*, ASCE, 121(9), 994-1002.
- Jenkins, W. M. (1991). "Towards structural optimization via the genetic algorithm." *Comp and Struct.*, 40(5), 1321-1327.
- Jenkins, W. M. (1997). "On the application of natural algorithms to structural design optimization." *Engrg. Struct.*, 19(4), 302-308
- Kareem, A. and Kline, S., (1995), "Performance of multiple mass dampers under random loading," *Journal of Structural Engineering, ASCE*, Vol.121, No.2, 348-361.
- Kaynia, A. M., Veneziano, D., and Biggs, J. M. (1981). "Seismic effectiveness of tuned mass dampers." *J. Struct. Engrg.*, ASCE, 121(2), 348-361
- Kobori, T., Koshika, N., Kazuhiko, Y., and Ikeda, Y. (1991). "Seismic response control structure with active mass driver system. Part 1 : design." *Earthquake Engrg and Struct. Dynamics*, 20, 135-149
- Lee, C. L., Chen, Y. T., Chung, L. L., Wang, Y. P (2006). "Optimal design theories and application of tuned mass dampers," *Engineering Structures*, 28, 43-53
- Lublin, L., Grocott, S., and Athans, M. (1996). " $H_2$  (LQG) dan  $H_{\infty}$  control." *The control handbook*, W. S. Levin, ed. CRC Press, Inc., Boca Raton, Fla.

- McNamara, R. J. (1977). "Tuned mass damper for buliding." *J. Struct. Div.*, ASCE, 103(9), 1785-1797
- Michalewicz (1996). *Genetic algorithms + data structures = evolution program*. Springer-Verlag, Berlin, Germany.
- Posbergh, T. A., Trimboli, M. S., and Duke, J. P. (1991). "A control formulation for vibration absorbers." *Proc., Am. Control Conf.*, American Automatic Control Council, 3, 2481-2482. Boston, Mass.
- Rajeev, S., and Krishnamoorthy, C. S. (1992). "Discrete optimization of structures using genetic algorithms." *J. Struct. Engrg.*, ASCE, 118(5), 1233-1250.
- Rana, R., Soong, T. T. (1998). "Parametric study and simplified design of tuned mass dampers." *Engrg. Struct.*, 20(3), 193-204.
- Rao, S. S., Pan, T. S., and Venkayya, V. B. (1991). "Optimal placement of actuators in actively controlled structured using genetic algorithms." *AIAA J.*, American Inst. Of Aeronautics and Astronautics, Washington, D. C., 29(6), 942-943.
- Sadek, F, Mohraz, B., Taylor A. W., Chung, R. M. (1997). "A method of estiamting the parameters of tuned mass dampers for seismic application." *Earthquake Engrg. And Struct. Dynamics*, 26, 617-635.
- Setareh, M., and Hanson, R. D (1992a). "Tuned mass damper for balcony vibration control." *Struct Engrg.*, ASCE, 118(3), 723-740.
- Setareh, M., and Hanson, R. D (1992b). "Tuned mass damper for control vibration from humans." *Struct Engrg.*, ASCE, 118(3), 741-761.
- Singh. M. P., Matheu, E. E, and Suarez, L. E. (1997). "Active and semiactive control of structures under seismic excitation." *Earthquake Engrg. And Struct. Dynamics*, 26, 193-213
- Spencer, B, F, Jr., Suhardjo, J., ans Sain, M, K. (1994) "Frequency domain optimal control strategies for aseismic excitation protection." *J. Engrg. Mech.*, ASCE, 120(1), 135-158.
- Stech, D. J (1994). "H<sub>2</sub> approach for optimally tuning passive vibration absorber to flexible structure." *J. Guidance, Contr. and Dynamics.*, 17(3), 636-638.

- Suhardjo, J., Spencer B, F, Jr., and Kareem, A. (1992), "Frequency domain optimal control of wind-excited buildings." *J. Engrg. Mech.*, ASCE, 118(12), 2463-2481.
- Tsai, H. C. (1993). "Green's function of support excited structures with tuned mass dampers derived by a perturbation method ." *Earthquake Engrg. Struct. Dynamics*, 22, 975-990.
- Tsai, H. C and Lin, G. C. (1993). "Optimum tuned mass dampers for minimizing steady state response of support excited and damped systems." *Earthquake Engrg. Struct. Dynamics*, 22, 957-973.
- Van de Vegte, J., and Hladun, A. R. (1973). "Design of optimal passive vibration controls by optimal techniques." *J. Dynamic Systems Measurement and Control*, 427-434.
- Villaverde, R. (1985). "Reduction in seismic response with heavily damped vibration absorbers." *Earthquake Engrg. Struct. Dynamics*, 13, 33-42.
- Warburton, G. B. (1982). "Optimum absorber parameters for various combinations of response and excitation." *Earthquake Engrg. Struct. Dynamics*, 10, 381-401
- Warburton, G. B., and Ayorinde, E. O. (1980). "Optimum absorber parameters for simple systems." *Earthquake Engrg. Struct. Dynamics*, 8, 197- 217.
- Webster, A. C., and Vaicaitis, R. (1992). "Application of tuned mass dampers to control vibration of composite floor systems." *Engrg. J.*, American Inst. of Steel Construction, 29(3), 116-124.
- Wiesner, K. B. (1986). "Taming lively buildings" *Civ. Emgrg.*, June 54-57.
- Xu, Y. L., Kwok, K. C. S., and Samali, B. (1992). "control of wind-induced tall building vibration by tuned mass dampers." *J. Wind Engrg. Ind. Aerodyn.*, 40, 1-32.
- Xu, Y. L., and Kwok, K. C. S. (1994), "Semianalytical method for parametric study of tuned mass dampers." *J. Struct. Engrg.*, 120(3), 747-764
- Xu, Y. L., and Igusa, T., (1992) "Dynamics characteristics of multiple sub structures under closely space frequencies." *Earthquake Engrg and Struct. Dynamics*, 21, 1059-1070.

Yamaguchi, H., and Harnpornchai, N. (1993). "Fundamental characteristics of multiple tuned mass dampers for suppressing harmonically forced oscillation." *Earthquake Engrg. and Struct. Dynamics*, 22, 51-62.



### Lampiran 1. Analisis struktur menggunakan MATLAB

```

%coordinate
%base
n1=coor3(0,0,0);
n2=coor3(6,0,0);
n3=coor3(12,0,0);
n4=coor3(18,0,0);
n5=coor3(24,0,0);

n6=coor3(0,0,6);
n7=coor3(6,0,6);
n8=coor3(12,0,6);
n9=coor3(18,0,6);
n10=coor3(24,0,6);

n11=coor3(0,0,12);
n12=coor3(6,0,12);
n13=coor3(12,0,12);
n14=coor3(18,0,12);
n15=coor3(24,0,12);

n16=coor3(0,0,18);
n17=coor3(6,0,18);
n18=coor3(12,0,18);
n19=coor3(18,0,18);
n20=coor3(24,0,18);

n21=coor3(0,0,24);
n22=coor3(6,0,24);
n23=coor3(12,0,24);
n24=coor3(18,0,24);
n25=coor3(24,0,24);

%lantai 1
n26=coor3(0,4,0);
n27=coor3(6,4,0);
n28=coor3(12,4,0);
n29=coor3(18,4,0);
n30=coor3(24,4,0);

n31=coor3(0,4,6);
n32=coor3(6,4,6);
n33=coor3(12,4,6);
n34=coor3(18,4,6);
n35=coor3(24,4,6);

n36=coor3(0,4,12);
n37=coor3(6,4,12);
n38=coor3(12,4,12);
n39=coor3(18,4,12);
n40=coor3(24,4,12);

n41=coor3(0,4,18);
n42=coor3(6,4,18);
n43=coor3(12,4,18);
n44=coor3(18,4,18);
n45=coor3(24,4,18);

n46=coor3(0,4,24);
n47=coor3(6,4,24);
n48=coor3(12,4,24);
n49=coor3(18,4,24);
n50=coor3(24,4,24);

%lantai 2
n51=coor3(0,7.6,0);
n52=coor3(6,7.6,0);
n53=coor3(12,7.6,0);

n54=coor3(18,7.6,0);
n55=coor3(24,7.6,0);

n56=coor3(0,7.6,6);
n57=coor3(6,7.6,6);
n58=coor3(12,7.6,6);
n59=coor3(18,7.6,6);
n60=coor3(24,7.6,6);

n61=coor3(0,7.6,12);
n62=coor3(6,7.6,12);
n63=coor3(12,7.6,12);
n64=coor3(18,7.6,12);
n65=coor3(24,7.6,12);

n66=coor3(0,7.6,18);
n67=coor3(6,7.6,18);
n68=coor3(12,7.6,18);
n69=coor3(18,7.6,18);
n70=coor3(24,7.6,18);

n71=coor3(0,7.6,24);
n72=coor3(6,7.6,24);
n73=coor3(12,7.6,24);
n74=coor3(18,7.6,24);
n75=coor3(24,7.6,24);

%lantai 3
n76=coor3(0,11.2,0);
n77=coor3(6,11.2,0);
n78=coor3(12,11.2,0);
n79=coor3(18,11.2,0);
n80=coor3(24,11.2,0);

n81=coor3(0,11.2,6);
n82=coor3(6,11.2,6);
n83=coor3(12,11.2,6);
n84=coor3(18,11.2,6);
n85=coor3(24,11.2,6);

n86=coor3(0,11.2,12);
n87=coor3(6,11.2,12);
n88=coor3(12,11.2,12);
n89=coor3(18,11.2,12);
n90=coor3(24,11.2,12);

n91=coor3(0,11.2,18);
n92=coor3(6,11.2,18);
n93=coor3(12,11.2,18);
n94=coor3(18,11.2,18);
n95=coor3(24,11.2,18);

n96=coor3(0,11.2,24);
n97=coor3(6,11.2,24);
n98=coor3(12,11.2,24);
n99=coor3(18,11.2,24);
n100=coor3(24,11.2,24);

%lantai 4
n101=coor3(0,14.8,0);
n102=coor3(6,14.8,0);
n103=coor3(12,14.8,0);
n104=coor3(18,14.8,0);
n105=coor3(24,14.8,0);

n106=coor3(0,14.8,6);
n107=coor3(6,14.8,6);

```



```

n108=coor3(12,14.8,6);
n109=coor3(18,14.8,6);
n110=coor3(24,14.8,6);

n111=coor3(0,14.8,12);
n112=coor3(6,14.8,12);
n113=coor3(12,14.8,12);
n114=coor3(18,14.8,12);
n115=coor3(24,14.8,12);

n116=coor3(0,14.8,18);
n117=coor3(6,14.8,18);
n118=coor3(12,14.8,18);
n119=coor3(18,14.8,18);
n120=coor3(24,14.8,18);

n121=coor3(0,14.8,24);
n122=coor3(6,14.8,24);
n123=coor3(12,14.8,24);
n124=coor3(18,14.8,24);
n125=coor3(24,14.8,24);

%lantai 5
n126=coor3(0,18.4,0);
n127=coor3(6,18.4,0);
n128=coor3(12,18.4,0);
n129=coor3(18,18.4,0);
n130=coor3(24,18.4,0);

n131=coor3(0,18.4,6);
n132=coor3(6,18.4,6);
n133=coor3(12,18.4,6);
n134=coor3(18,18.4,6);
n135=coor3(24,18.4,6);

n136=coor3(0,18.4,12);
n137=coor3(6,18.4,12);
n138=coor3(12,18.4,12);
n139=coor3(18,18.4,12);
n140=coor3(24,18.4,12);

n141=coor3(0,18.4,18);
n142=coor3(6,18.4,18);
n143=coor3(12,18.4,18);
n144=coor3(18,18.4,18);
n145=coor3(24,18.4,18);

n146=coor3(0,18.4,24);
n147=coor3(6,18.4,24);
n148=coor3(12,18.4,24);
n149=coor3(18,18.4,24);
n150=coor3(24,18.4,24);

%lantai 6
n151=coor3(0,22,0);
n152=coor3(6,22,0);
n153=coor3(12,22,0);
n154=coor3(18,22,0);
n155=coor3(24,22,0);

n156=coor3(0,22,6);
n157=coor3(6,22,6);
n158=coor3(12,22,6);
n159=coor3(18,22,6);
n160=coor3(24,22,6);

n161=coor3(0,22,12);
n162=coor3(6,22,12);
n163=coor3(12,22,12);
n164=coor3(18,22,12);
n165=coor3(24,22,12);

n166=coor3(0,22,18);
n167=coor3(6,22,18);
n168=coor3(12,22,18);

n169=coor3(0,22,24);
n170=coor3(6,22,24);
n171=coor3(12,22,24);

%lantai 7
n172=coor3(0,25.6,0);
n173=coor3(6,25.6,0);
n174=coor3(12,25.6,0);
n175=coor3(18,25.6,0);
n176=coor3(24,25.6,0);

n177=coor3(0,25.6,6);
n178=coor3(6,25.6,6);
n179=coor3(12,25.6,6);
n180=coor3(18,25.6,6);
n181=coor3(24,25.6,6);

n182=coor3(0,25.6,12);
n183=coor3(6,25.6,12);
n184=coor3(12,25.6,12);
n185=coor3(18,25.6,12);
n186=coor3(24,25.6,12);

n187=coor3(0,25.6,18);
n188=coor3(6,25.6,18);
n189=coor3(12,25.6,18);

n190=coor3(0,25.6,24);
n191=coor3(6,25.6,24);
n192=coor3(12,25.6,24);

%lantai 8
n193=coor3(0,29.2,0);
n194=coor3(6,29.2,0);
n195=coor3(12,29.2,0);
n196=coor3(18,29.2,0);
n197=coor3(24,29.2,0);

n198=coor3(0,29.2,6);
n199=coor3(6,29.2,6);
n200=coor3(12,29.2,6);
n201=coor3(18,29.2,6);
n202=coor3(24,29.2,6);

n203=coor3(0,29.2,12);
n204=coor3(6,29.2,12);
n205=coor3(12,29.2,12);
n206=coor3(18,29.2,12);
n207=coor3(24,29.2,12);

n208=coor3(0,29.2,18);
n209=coor3(6,29.2,18);
n210=coor3(12,29.2,18);

n211=coor3(0,29.2,24);
n212=coor3(6,29.2,24);
n213=coor3(12,29.2,24);

%lantai 9
n214=coor3(0,32.8,0);
n215=coor3(6,32.8,0);
n216=coor3(12,32.8,0);
n217=coor3(18,32.8,0);
n218=coor3(24,32.8,0);

n219=coor3(0,32.8,6);

```

```

n220=coor3(6,32.8,6);
n221=coor3(12,32.8,6);
n222=coor3(18,32.8,6);
n223=coor3(24,32.8,6);

n224=coor3(0,32.8,12);
n225=coor3(6,32.8,12);
n226=coor3(12,32.8,12);
n227=coor3(18,32.8,12);
n228=coor3(24,32.8,12);

n229=coor3(0,32.8,18);
n230=coor3(6,32.8,18);
n231=coor3(12,32.8,18);

n232=coor3(0,32.8,24);
n233=coor3(6,32.8,24);
n234=coor3(12,32.8,24);

%lantai 10
n235=coor3(0,36.4,0);
n236=coor3(6,36.4,0);
n237=coor3(12,36.4,0);
n238=coor3(18,36.4,0);
n239=coor3(24,36.4,0);

n240=coor3(0,36.4,6);
n241=coor3(6,36.4,6);
n242=coor3(12,36.4,6);
n243=coor3(18,36.4,6);
n244=coor3(24,36.4,6);

n245=coor3(0,36.4,12);
n246=coor3(6,36.4,12);
n247=coor3(12,36.4,12);
n248=coor3(18,36.4,12);
n249=coor3(24,36.4,12);

n250=coor3(0,36.4,18);
n251=coor3(6,36.4,18);
n252=coor3(12,36.4,18);

n253=coor3(0,36.4,24);
n254=coor3(6,36.4,24);
n255=coor3(12,36.4,24);

%lantai 11
n256=coor3(0,40,0);
n257=coor3(6,40,0);
n258=coor3(12,40,0);
n259=coor3(18,40,0);
n260=coor3(24,40,0);

n261=coor3(0,40,6);
n262=coor3(6,40,6);
n263=coor3(12,40,6);
n264=coor3(18,40,6);
n265=coor3(24,40,6);

n266=coor3(0,40,12);
n267=coor3(6,40,12);
n268=coor3(12,40,12);
n269=coor3(18,40,12);
n270=coor3(24,40,12);

n271=coor3(0,40,18);
n272=coor3(6,40,18);
n273=coor3(12,40,18);

n274=coor3(0,40,24);
n275=coor3(6,40,24);

n276=coor3(12,40,24);

%lantai 12
n277=coor3(0,43.6,0);
n278=coor3(6,43.6,0);
n279=coor3(12,43.6,0);
n280=coor3(18,43.6,0);
n281=coor3(24,43.6,0);

n282=coor3(0,43.6,6);
n283=coor3(6,43.6,6);
n284=coor3(12,43.6,6);
n285=coor3(18,43.6,6);
n286=coor3(24,43.6,6);

n287=coor3(0,43.6,12);
n288=coor3(6,43.6,12);
n289=coor3(12,43.6,12);
n290=coor3(18,43.6,12);
n291=coor3(24,43.6,12);

n292=coor3(0,43.6,18);
n293=coor3(6,43.6,18);
n294=coor3(12,43.6,18);

n295=coor3(0,43.6,24);
n296=coor3(6,43.6,24);
n297=coor3(12,43.6,24);

%Column
[L1,T1]=mem3f(n1,n26,n2);
[L2,T2]=mem3f(n26,n51,n2);
[L3,T3]=mem3f(n51,n76,n2);
[L4,T4]=mem3f(n76,n101,n2);
[L5,T5]=mem3f(n101,n126,n2);
[L6,T6]=mem3f(n126,n151,n2);
[L7,T7]=mem3f(n151,n172,n2);
[L8,T8]=mem3f(n172,n193,n2);
[L9,T9]=mem3f(n193,n214,n2);
[L10,T10]=mem3f(n214,n235,n2);
[L11,T11]=mem3f(n235,n256,n2);
[L12,T12]=mem3f(n256,n277,n2);

[L13,T13]=mem3f(n2,n27,n3);
[L14,T14]=mem3f(n27,n52,n3);
[L15,T15]=mem3f(n52,n77,n3);
[L16,T16]=mem3f(n77,n102,n3);
[L17,T17]=mem3f(n102,n127,n3);
[L18,T18]=mem3f(n127,n152,n3);
[L19,T19]=mem3f(n152,n173,n3);
[L20,T20]=mem3f(n173,n194,n3);
[L21,T21]=mem3f(n194,n215,n3);
[L22,T22]=mem3f(n215,n236,n3);
[L23,T23]=mem3f(n236,n257,n3);
[L24,T24]=mem3f(n257,n278,n3);

[L25,T25]=mem3f(n3,n28,n4);
[L26,T26]=mem3f(n28,n53,n4);
[L27,T27]=mem3f(n53,n78,n4);
[L28,T28]=mem3f(n78,n103,n4);
[L29,T29]=mem3f(n103,n128,n4);
[L30,T30]=mem3f(n128,n153,n4);
[L31,T31]=mem3f(n153,n174,n4);
[L32,T32]=mem3f(n174,n195,n4);
[L33,T33]=mem3f(n195,n216,n4);
[L34,T34]=mem3f(n216,n237,n4);
[L35,T35]=mem3f(n237,n258,n4);
[L36,T36]=mem3f(n258,n279,n4);

[L37,T37]=mem3f(n4,n29,n5);
[L38,T38]=mem3f(n29,n54,n5);

```

[L39, T39]=mem3f(n54, n79, n5);  
 [L40, T40]=mem3f(n79, n104, n5);  
 [L41, T41]=mem3f(n104, n129, n5);  
 [L42, T42]=mem3f(n129, n154, n5);  
 [L43, T43]=mem3f(n154, n175, n5);  
 [L44, T44]=mem3f(n175, n196, n5);  
 [L45, T45]=mem3f(n196, n217, n5);  
 [L46, T46]=mem3f(n217, n238, n5);  
 [L47, T47]=mem3f(n238, n259, n5);  
 [L48, T48]=mem3f(n259, n280, n5);  
  
 [L49, T49]=mem3f(n5, n30, n4);  
 [L50, T50]=mem3f(n30, n55, n4);  
 [L51, T51]=mem3f(n55, n80, n4);  
 [L52, T52]=mem3f(n80, n105, n4);  
 [L53, T53]=mem3f(n105, n130, n4);  
 [L54, T54]=mem3f(n130, n155, n4);  
 [L55, T55]=mem3f(n155, n176, n4);  
 [L56, T56]=mem3f(n176, n197, n4);  
 [L57, T57]=mem3f(n197, n218, n4);  
 [L58, T58]=mem3f(n218, n239, n4);  
 [L59, T59]=mem3f(n239, n260, n4);  
 [L60, T60]=mem3f(n260, n281, n4);  
  
 [L61, T61]=mem3f(n6, n31, n7);  
 [L62, T62]=mem3f(n31, n56, n7);  
 [L63, T63]=mem3f(n56, n81, n7);  
 [L64, T64]=mem3f(n81, n106, n7);  
 [L65, T65]=mem3f(n106, n131, n7);  
 [L66, T66]=mem3f(n131, n156, n7);  
 [L67, T67]=mem3f(n156, n177, n7);  
 [L68, T68]=mem3f(n177, n198, n7);  
 [L69, T69]=mem3f(n198, n219, n7);  
 [L70, T70]=mem3f(n219, n240, n7);  
 [L71, T71]=mem3f(n240, n251, n7);  
 [L72, T72]=mem3f(n251, n282, n7);  
  
 [L73, T73]=mem3f(n7, n32, n8);  
 [L74, T74]=mem3f(n32, n57, n8);  
 [L75, T75]=mem3f(n57, n82, n8);  
 [L76, T76]=mem3f(n82, n107, n8);  
 [L77, T77]=mem3f(n107, n132, n8);  
 [L78, T78]=mem3f(n132, n157, n8);  
 [L79, T79]=mem3f(n157, n178, n8);  
 [L80, T80]=mem3f(n178, n199, n8);  
 [L81, T81]=mem3f(n199, n220, n8);  
 [L82, T82]=mem3f(n220, n241, n8);  
 [L83, T83]=mem3f(n241, n262, n8);  
 [L84, T84]=mem3f(n262, n283, n8);  
  
 [L85, T85]=mem3f(n8, n33, n9);  
 [L86, T86]=mem3f(n33, n58, n9);  
 [L87, T87]=mem3f(n58, n83, n9);  
 [L88, T88]=mem3f(n83, n108, n9);  
 [L89, T89]=mem3f(n108, n133, n9);  
 [L90, T90]=mem3f(n133, n158, n9);  
 [L91, T91]=mem3f(n158, n179, n9);  
 [L92, T92]=mem3f(n179, n200, n9);  
 [L93, T93]=mem3f(n200, n221, n9);  
 [L94, T94]=mem3f(n221, n242, n9);  
 [L95, T95]=mem3f(n242, n263, n9);  
 [L96, T96]=mem3f(n263, n284, n9);  
  
 [L97, T97]=mem3f(n9, n34, n10);  
 [L98, T98]=mem3f(n34, n59, n10);  
 [L99, T99]=mem3f(n59, n84, n10);  
 [L100, T100]=mem3f(n84, n109, n10);  
 [L101, T101]=mem3f(n109, n134, n10);  
 [L102, T102]=mem3f(n134, n159, n10);  
 [L103, T103]=mem3f(n159, n180, n10);  
 [L104, T104]=mem3f(n180, n201, n10);  
  
 [L105, T105]=mem3f(n201, n222, n10);  
 [L106, T106]=mem3f(n222, n243, n10);  
 [L107, T107]=mem3f(n243, n264, n10);  
 [L108, T108]=mem3f(n264, n285, n10);  
  
 [L109, T109]=mem3f(n10, n35, n9);  
 [L110, T110]=mem3f(n35, n60, n9);  
 [L111, T111]=mem3f(n60, n85, n9);  
 [L112, T112]=mem3f(n85, n110, n9);  
 [L113, T113]=mem3f(n110, n135, n9);  
 [L114, T114]=mem3f(n135, n160, n9);  
 [L115, T115]=mem3f(n160, n181, n9);  
 [L116, T116]=mem3f(n181, n202, n9);  
 [L117, T117]=mem3f(n202, n223, n9);  
 [L118, T118]=mem3f(n223, n244, n9);  
 [L119, T119]=mem3f(n244, n265, n9);  
 [L120, T120]=mem3f(n265, n286, n9);  
  
 [L121, T121]=mem3f(n11, n36, n12);  
 [L122, T122]=mem3f(n36, n61, n12);  
 [L123, T123]=mem3f(n61, n86, n12);  
 [L124, T124]=mem3f(n86, n111, n12);  
 [L125, T125]=mem3f(n111, n136, n12);  
 [L126, T126]=mem3f(n136, n161, n12);  
 [L127, T127]=mem3f(n161, n182, n12);  
 [L128, T128]=mem3f(n182, n203, n12);  
 [L129, T129]=mem3f(n203, n224, n12);  
 [L130, T130]=mem3f(n224, n245, n12);  
 [L131, T131]=mem3f(n245, n266, n12);  
 [L132, T132]=mem3f(n266, n287, n12);  
  
 [L133, T133]=mem3f(n12, n37, n13);  
 [L134, T134]=mem3f(n37, n62, n13);  
 [L135, T135]=mem3f(n62, n87, n13);  
 [L136, T136]=mem3f(n87, n112, n13);  
 [L137, T137]=mem3f(n112, n137, n13);  
 [L138, T138]=mem3f(n137, n162, n13);  
 [L139, T139]=mem3f(n162, n183, n13);  
 [L140, T140]=mem3f(n183, n204, n13);  
 [L141, T141]=mem3f(n204, n225, n13);  
 [L142, T142]=mem3f(n225, n246, n13);  
 [L143, T143]=mem3f(n246, n267, n13);  
 [L144, T144]=mem3f(n267, n288, n13);  
  
 [L145, T145]=mem3f(n13, n38, n14);  
 [L146, T146]=mem3f(n38, n63, n14);  
 [L147, T147]=mem3f(n63, n88, n14);  
 [L148, T148]=mem3f(n88, n113, n14);  
 [L149, T149]=mem3f(n113, n138, n14);  
 [L150, T150]=mem3f(n138, n163, n14);  
 [L151, T151]=mem3f(n163, n184, n14);  
 [L152, T152]=mem3f(n184, n205, n14);  
 [L153, T153]=mem3f(n205, n226, n14);  
 [L154, T154]=mem3f(n226, n247, n14);  
 [L155, T155]=mem3f(n247, n268, n14);  
 [L156, T156]=mem3f(n268, n289, n14);  
  
 [L157, T157]=mem3f(n14, n39, n15);  
 [L158, T158]=mem3f(n39, n64, n15);  
 [L159, T159]=mem3f(n64, n89, n15);  
 [L160, T160]=mem3f(n89, n114, n15);  
 [L161, T161]=mem3f(n114, n139, n15);  
 [L162, T162]=mem3f(n139, n164, n15);  
 [L163, T163]=mem3f(n164, n185, n15);  
 [L164, T164]=mem3f(n185, n206, n15);  
 [L165, T165]=mem3f(n206, n227, n15);  
 [L166, T166]=mem3f(n227, n248, n15);  
 [L167, T167]=mem3f(n248, n269, n15);  
 [L168, T168]=mem3f(n269, n290, n15);  
  
 [L169, T169]=mem3f(n15, n40, n14);

```

[L170,T170]=mem3f(n40,n65,n14);
[L171,T171]=mem3f(n65,n90,n14);
[L172,T172]=mem3f(n90,n115,n14);
[L173,T173]=mem3f(n115,n140,n14);
[L174,T174]=mem3f(n140,n165,n14);
[L175,T175]=mem3f(n165,n186,n14);
[L176,T176]=mem3f(n186,n207,n14);
[L177,T177]=mem3f(n207,n228,n14);
[L178,T178]=mem3f(n228,n249,n14);
[L179,T179]=mem3f(n249,n270,n14);
[L180,T180]=mem3f(n270,n291,n14);

[L181,T181]=mem3f(n16,n41,n17);
[L182,T182]=mem3f(n41,n66,n17);
[L183,T183]=mem3f(n66,n91,n17);
[L184,T184]=mem3f(n91,n116,n17);
[L185,T185]=mem3f(n116,n141,n17);
[L186,T186]=mem3f(n141,n166,n17);
[L187,T187]=mem3f(n166,n187,n17);
[L188,T188]=mem3f(n187,n208,n17);
[L189,T189]=mem3f(n208,n229,n17);
[L190,T190]=mem3f(n229,n250,n17);
[L191,T191]=mem3f(n250,n271,n17);
[L192,T192]=mem3f(n271,n292,n17);

[L193,T193]=mem3f(n17,n42,n18);
[L194,T194]=mem3f(n42,n67,n18);
[L195,T195]=mem3f(n67,n92,n18);
[L196,T196]=mem3f(n92,n117,n18);
[L197,T197]=mem3f(n117,n142,n18);
[L198,T198]=mem3f(n142,n167,n18);
[L199,T199]=mem3f(n167,n188,n18);
[L200,T200]=mem3f(n188,n209,n18);
[L201,T201]=mem3f(n209,n230,n18);
[L202,T202]=mem3f(n230,n251,n18);
[L203,T203]=mem3f(n251,n272,n18);
[L204,T204]=mem3f(n272,n293,n18);

[L205,T205]=mem3f(n18,n43,n19);
[L206,T206]=mem3f(n43,n68,n19);
[L207,T207]=mem3f(n68,n93,n19);
[L208,T208]=mem3f(n93,n118,n19);
[L209,T209]=mem3f(n118,n143,n19);
[L210,T210]=mem3f(n143,n168,n19);
[L211,T211]=mem3f(n168,n189,n19);
[L212,T212]=mem3f(n189,n210,n19);
[L213,T213]=mem3f(n210,n231,n19);
[L214,T214]=mem3f(n231,n252,n19);
[L215,T215]=mem3f(n252,n273,n19);
[L216,T216]=mem3f(n273,n294,n19);

[L217,T217]=mem3f(n19,n44,n20);
[L218,T218]=mem3f(n44,n69,n20);
[L219,T219]=mem3f(n69,n94,n20);
[L220,T220]=mem3f(n94,n119,n20);
[L221,T221]=mem3f(n119,n144,n20);

[L222,T222]=mem3f(n20,n45,n19);
[L223,T223]=mem3f(n45,n70,n19);
[L224,T224]=mem3f(n70,n95,n19);
[L225,T225]=mem3f(n95,n120,n19);
[L226,T226]=mem3f(n120,n145,n19);

[L227,T227]=mem3f(n21,n46,n22);
[L228,T228]=mem3f(n46,n71,n22);
[L229,T229]=mem3f(n71,n96,n22);
[L230,T230]=mem3f(n96,n121,n22);
[L231,T231]=mem3f(n121,n146,n22);
[L232,T232]=mem3f(n146,n169,n22);
[L233,T233]=mem3f(n169,n190,n22);
[L234,T234]=mem3f(n190,n211,n22);

[L235,T235]=mem3f(n211,n232,n22);
[L236,T236]=mem3f(n232,n253,n22);
[L237,T237]=mem3f(n253,n274,n22);
[L238,T238]=mem3f(n274,n295,n22);

[L239,T239]=mem3f(n22,n47,n23);
[L240,T240]=mem3f(n47,n72,n23);
[L241,T241]=mem3f(n72,n97,n23);
[L242,T242]=mem3f(n97,n122,n23);
[L243,T243]=mem3f(n122,n147,n23);
[L244,T244]=mem3f(n147,n170,n23);
[L245,T245]=mem3f(n170,n191,n23);
[L246,T246]=mem3f(n191,n212,n23);
[L247,T247]=mem3f(n212,n233,n23);
[L248,T248]=mem3f(n233,n254,n23);
[L249,T249]=mem3f(n254,n275,n23);
[L250,T250]=mem3f(n275,n296,n23);

[L251,T251]=mem3f(n23,n48,n24);
[L252,T252]=mem3f(n48,n73,n24);
[L253,T253]=mem3f(n73,n98,n24);
[L254,T254]=mem3f(n98,n123,n24);
[L255,T255]=mem3f(n123,n148,n24);
[L256,T256]=mem3f(n148,n171,n24);
[L257,T257]=mem3f(n171,n192,n24);
[L258,T258]=mem3f(n192,n213,n24);
[L259,T259]=mem3f(n213,n234,n24);
[L260,T260]=mem3f(n234,n255,n24);
[L261,T261]=mem3f(n255,n276,n24);
[L262,T262]=mem3f(n276,n291,n24);

[L263,T263]=mem3f(n24,n49,n25);
[L264,T264]=mem3f(n49,n74,n25);
[L265,T265]=mem3f(n74,n99,n25);
[L266,T266]=mem3f(n99,n124,n25);
[L267,T267]=mem3f(n124,n149,n25);

[L268,T268]=mem3f(n25,n50,n24);
[L269,T269]=mem3f(n50,n75,n24);
[L270,T270]=mem3f(n75,n100,n24);
[L271,T271]=mem3f(n100,n125,n24);
[L272,T272]=mem3f(n125,n150,n24);

%Beam
%Arah x
[L273,T273]=mem3f(n26,n27,n51); %
lantai 1
[L274,T274]=mem3f(n27,n28,n51);
[L275,T275]=mem3f(n28,n29,n51);
[L276,T276]=mem3f(n29,n30,n51);
[L277,T277]=mem3f(n31,n32,n56);
[L278,T278]=mem3f(n32,n33,n56);
[L279,T279]=mem3f(n33,n34,n56);
[L280,T280]=mem3f(n34,n35,n56);
[L281,T281]=mem3f(n36,n37,n61);
[L282,T282]=mem3f(n37,n38,n61);
[L283,T283]=mem3f(n38,n39,n61);
[L284,T284]=mem3f(n39,n40,n61);
[L285,T285]=mem3f(n41,n42,n66);
[L286,T286]=mem3f(n42,n43,n66);
[L287,T287]=mem3f(n43,n44,n66);
[L288,T288]=mem3f(n44,n45,n66);
[L289,T289]=mem3f(n46,n47,n71);
[L290,T290]=mem3f(n47,n48,n71);
[L291,T291]=mem3f(n48,n49,n71);
[L292,T292]=mem3f(n49,n50,n71);

[L293,T293]=mem3f(n51,n52,n76); %
lantai 2
[L294,T294]=mem3f(n52,n53,n76);
[L295,T295]=mem3f(n53,n54,n76);

```

```

[L296, T296]=mem3f(n54, n55, n76);
[L297, T297]=mem3f(n56, n57, n81);
[L298, T298]=mem3f(n57, n58, n81);
[L299, T299]=mem3f(n58, n59, n81);
[L300, T300]=mem3f(n59, n60, n81);
[L301, T301]=mem3f(n61, n62, n86);
[L302, T302]=mem3f(n62, n63, n86);
[L303, T303]=mem3f(n63, n64, n86);
[L304, T304]=mem3f(n64, n65, n86);
[L305, T305]=mem3f(n66, n67, n91);
[L306, T306]=mem3f(n67, n68, n91);
[L307, T307]=mem3f(n68, n69, n91);
[L308, T308]=mem3f(n69, n70, n91);
[L309, T309]=mem3f(n71, n72, n96);
[L310, T310]=mem3f(n72, n73, n96);
[L311, T311]=mem3f(n73, n74, n96);
[L312, T312]=mem3f(n74, n75, n96);

[L313, T313]=mem3f(n76, n77, n101); %
lantai 3
[L314, T314]=mem3f(n77, n78, n101);
[L315, T315]=mem3f(n78, n79, n101);
[L316, T316]=mem3f(n79, n80, n101);
[L317, T317]=mem3f(n81, n82, n106);
[L318, T318]=mem3f(n82, n83, n106);
[L319, T319]=mem3f(n83, n84, n106);
[L320, T320]=mem3f(n84, n85, n106);
[L321, T321]=mem3f(n86, n87, n111);
[L322, T322]=mem3f(n87, n88, n111);
[L323, T323]=mem3f(n88, n89, n111);
[L324, T324]=mem3f(n89, n90, n111);
[L325, T325]=mem3f(n91, n92, n116);
[L326, T326]=mem3f(n92, n93, n116);
[L327, T327]=mem3f(n93, n94, n116);
[L328, T328]=mem3f(n94, n95, n116);
[L329, T329]=mem3f(n96, n97, n121);
[L330, T330]=mem3f(n97, n98, n121);
[L331, T331]=mem3f(n98, n99, n121);
[L332, T332]=mem3f(n99, n100, n121);

[L333, T333]=mem3f(n101, n102, n126); %
lantai 4
[L334, T334]=mem3f(n102, n103, n126);
[L335, T335]=mem3f(n103, n104, n126);
[L336, T336]=mem3f(n104, n105, n126);
[L337, T337]=mem3f(n106, n107, n131);
[L338, T338]=mem3f(n107, n108, n131);
[L339, T339]=mem3f(n108, n109, n131);
[L340, T340]=mem3f(n109, n110, n131);
[L341, T341]=mem3f(n111, n112, n136);
[L342, T342]=mem3f(n112, n113, n136);
[L343, T343]=mem3f(n113, n114, n136);
[L344, T344]=mem3f(n114, n115, n136);
[L345, T345]=mem3f(n116, n117, n141);
[L346, T346]=mem3f(n117, n118, n141);
[L347, T347]=mem3f(n118, n119, n141);
[L348, T348]=mem3f(n119, n120, n141);
[L349, T349]=mem3f(n121, n122, n146);
[L350, T350]=mem3f(n122, n123, n146);
[L351, T351]=mem3f(n123, n124, n146);
[L352, T352]=mem3f(n124, n125, n146);

[L353, T353]=mem3f(n126, n127, n151); %
lantai 5
[L354, T354]=mem3f(n127, n128, n151);
[L355, T355]=mem3f(n128, n129, n151);
[L356, T356]=mem3f(n129, n130, n151);
[L357, T357]=mem3f(n131, n132, n156);
[L358, T358]=mem3f(n132, n133, n156);
[L359, T359]=mem3f(n133, n134, n156);
[L360, T360]=mem3f(n134, n135, n156);

[L361, T361]=mem3f(n136, n137, n161);
[L362, T362]=mem3f(n137, n138, n161);
[L363, T363]=mem3f(n138, n139, n161);
[L364, T364]=mem3f(n139, n140, n161);
[L365, T365]=mem3f(n141, n142, n166);
[L366, T366]=mem3f(n142, n143, n166);
[L367, T367]=mem3f(n143, n144, n166);
[L368, T368]=mem3f(n144, n145, n166);
[L369, T369]=mem3f(n146, n147, n169);
[L370, T370]=mem3f(n147, n148, n169);
[L371, T371]=mem3f(n148, n149, n169);
[L372, T372]=mem3f(n149, n150, n169);

[L373, T373]=mem3f(n151, n152, n172); %
lantai 6
[L374, T374]=mem3f(n152, n153, n172);
[L375, T375]=mem3f(n153, n154, n172);
[L376, T376]=mem3f(n154, n155, n172);
[L377, T377]=mem3f(n156, n157, n177);
[L378, T378]=mem3f(n157, n158, n177);
[L379, T379]=mem3f(n158, n159, n177);
[L380, T380]=mem3f(n159, n160, n177);
[L381, T381]=mem3f(n161, n162, n182);
[L382, T382]=mem3f(n162, n163, n182);
[L383, T383]=mem3f(n163, n164, n182);
[L384, T384]=mem3f(n164, n165, n182);
[L385, T385]=mem3f(n166, n167, n187);
[L386, T386]=mem3f(n167, n168, n187);
[L387, T387]=mem3f(n169, n170, n190);
[L388, T388]=mem3f(n170, n171, n190);

[L389, T389]=mem3f(n172, n173, n193); %
lantai 7
[L390, T390]=mem3f(n173, n174, n193);
[L391, T391]=mem3f(n174, n175, n193);
[L392, T392]=mem3f(n175, n176, n193);
[L393, T393]=mem3f(n177, n178, n198);
[L394, T394]=mem3f(n178, n179, n198);
[L395, T395]=mem3f(n179, n180, n198);
[L396, T396]=mem3f(n180, n181, n198);
[L397, T397]=mem3f(n182, n183, n203);
[L398, T398]=mem3f(n183, n184, n203);
[L399, T399]=mem3f(n184, n185, n203);
[L400, T400]=mem3f(n185, n186, n203);
[L401, T401]=mem3f(n187, n188, n208);
[L402, T402]=mem3f(n188, n189, n208);
[L403, T403]=mem3f(n190, n191, n211);
[L404, T404]=mem3f(n191, n192, n211);

[L405, T405]=mem3f(n193, n194, n214); %
lantai 8
[L406, T406]=mem3f(n194, n195, n214);
[L407, T407]=mem3f(n195, n196, n214);
[L408, T408]=mem3f(n196, n197, n214);
[L409, T409]=mem3f(n198, n199, n219);
[L410, T410]=mem3f(n199, n200, n219);
[L411, T411]=mem3f(n200, n201, n219);
[L412, T412]=mem3f(n201, n202, n219);
[L413, T413]=mem3f(n203, n204, n224);
[L414, T414]=mem3f(n204, n205, n224);
[L415, T415]=mem3f(n205, n206, n224);
[L416, T416]=mem3f(n206, n207, n224);
[L417, T417]=mem3f(n208, n209, n229);
[L418, T418]=mem3f(n209, n210, n229);
[L419, T419]=mem3f(n211, n212, n232);
[L420, T420]=mem3f(n212, n213, n232);

[L421, T421]=mem3f(n214, n215, n235); %
lantai 9
[L422, T422]=mem3f(n215, n216, n235);
[L423, T423]=mem3f(n216, n217, n235);

```

```

[L424, T424]=mem3f (n217, n218, n235);
[L425, T425]=mem3f (n219, n220, n240);
[L426, T426]=mem3f (n220, n221, n240);
[L427, T427]=mem3f (n221, n222, n240);
[L428, T428]=mem3f (n222, n223, n240);
[L429, T429]=mem3f (n224, n225, n245);
[L430, T430]=mem3f (n225, n226, n245);
[L431, T431]=mem3f (n226, n227, n245);
[L432, T432]=mem3f (n227, n228, n245);
[L433, T433]=mem3f (n229, n230, n250);
[L434, T434]=mem3f (n230, n231, n250);
[L435, T435]=mem3f (n232, n233, n253);
[L436, T436]=mem3f (n233, n234, n253);

[L437, T437]=mem3f (n235, n236, n256); %1a
antai 10
[L438, T438]=mem3f (n236, n237, n256);
[L439, T439]=mem3f (n237, n238, n256);
[L440, T440]=mem3f (n238, n239, n256);
[L441, T441]=mem3f (n240, n241, n261);
[L442, T442]=mem3f (n241, n242, n261);
[L443, T443]=mem3f (n242, n243, n261);
[L444, T444]=mem3f (n243, n244, n261);
[L445, T445]=mem3f (n245, n246, n266);
[L446, T446]=mem3f (n246, n247, n266);
[L447, T447]=mem3f (n247, n248, n266);
[L448, T448]=mem3f (n248, n249, n266);
[L449, T449]=mem3f (n250, n251, n271);
[L450, T450]=mem3f (n251, n252, n271);
[L451, T451]=mem3f (n253, n254, n274);
[L452, T452]=mem3f (n254, n255, n274);

[L453, T453]=mem3f (n256, n257, n277); %
lantai 11
[L454, T454]=mem3f (n257, n258, n277);
[L455, T455]=mem3f (n258, n259, n277);
[L456, T456]=mem3f (n259, n260, n277);
[L457, T457]=mem3f (n261, n262, n282);
[L458, T458]=mem3f (n262, n263, n282);
[L459, T459]=mem3f (n263, n264, n282);
[L460, T460]=mem3f (n264, n265, n282);
[L461, T461]=mem3f (n266, n267, n287);
[L462, T462]=mem3f (n267, n268, n287);
[L463, T463]=mem3f (n268, n269, n287);
[L464, T464]=mem3f (n269, n270, n287);
[L465, T465]=mem3f (n271, n272, n292);
[L466, T466]=mem3f (n272, n273, n292);
[L467, T467]=mem3f (n274, n275, n295);
[L468, T468]=mem3f (n275, n276, n295);

[L469, T469]=mem3f (n277, n278, n256); %
lantai 12
[L470, T470]=mem3f (n278, n279, n256);
[L471, T471]=mem3f (n279, n280, n256);
[L472, T472]=mem3f (n280, n281, n256);
[L473, T473]=mem3f (n282, n283, n261);
[L474, T474]=mem3f (n283, n284, n261);
[L475, T475]=mem3f (n284, n285, n261);
[L476, T476]=mem3f (n285, n286, n261);
[L477, T477]=mem3f (n287, n288, n266);
[L478, T478]=mem3f (n288, n289, n266);
[L479, T479]=mem3f (n289, n290, n266);
[L480, T480]=mem3f (n290, n291, n266);
[L481, T481]=mem3f (n292, n293, n271);
[L482, T482]=mem3f (n293, n294, n271);
[L483, T483]=mem3f (n295, n296, n274);
[L484, T484]=mem3f (n296, n297, n274);

%Arah z
[L485, T485]=mem3f (n26, n31, n51); %
lantai 1

[L486, T486]=mem3f (n31, n36, n51);
[L487, T487]=mem3f (n36, n41, n51);
[L488, T488]=mem3f (n41, n46, n51);
[L489, T489]=mem3f (n27, n32, n52);
[L490, T490]=mem3f (n32, n37, n52);
[L491, T491]=mem3f (n37, n42, n52);
[L492, T492]=mem3f (n42, n47, n52);
[L493, T493]=mem3f (n28, n33, n53);
[L494, T494]=mem3f (n33, n38, n53);
[L495, T495]=mem3f (n38, n43, n53);
[L496, T496]=mem3f (n43, n48, n53);
[L497, T497]=mem3f (n29, n34, n54);
[L498, T498]=mem3f (n34, n39, n54);
[L499, T499]=mem3f (n39, n44, n54);
[L500, T500]=mem3f (n44, n49, n54);
[L501, T501]=mem3f (n30, n35, n55);
[L502, T502]=mem3f (n35, n40, n55);
[L503, T503]=mem3f (n40, n45, n55);
[L504, T504]=mem3f (n45, n50, n55);

[L505, T505]=mem3f (n51, n56, n76); %
lantai 2
[L506, T506]=mem3f (n56, n61, n76);
[L507, T507]=mem3f (n61, n66, n76);
[L508, T508]=mem3f (n66, n71, n76);
[L509, T509]=mem3f (n52, n57, n77);
[L510, T510]=mem3f (n57, n62, n77);
[L511, T511]=mem3f (n62, n67, n77);
[L512, T512]=mem3f (n67, n72, n77);
[L513, T513]=mem3f (n53, n58, n78);
[L514, T514]=mem3f (n58, n63, n78);
[L515, T515]=mem3f (n63, n68, n78);
[L516, T516]=mem3f (n68, n73, n78);
[L517, T517]=mem3f (n54, n59, n79);
[L518, T518]=mem3f (n59, n64, n79);
[L519, T519]=mem3f (n64, n69, n79);
[L520, T520]=mem3f (n69, n74, n79);
[L521, T521]=mem3f (n55, n60, n80);
[L522, T522]=mem3f (n60, n65, n80);
[L523, T523]=mem3f (n65, n70, n80);
[L524, T524]=mem3f (n70, n75, n80);

[L525, T525]=mem3f (n76, n81, n101); %
lantai 3
[L526, T526]=mem3f (n81, n86, n101);
[L527, T527]=mem3f (n86, n91, n101);
[L528, T528]=mem3f (n91, n96, n101);
[L529, T529]=mem3f (n77, n82, n102);
[L530, T530]=mem3f (n82, n87, n102);
[L531, T531]=mem3f (n87, n92, n102);
[L532, T532]=mem3f (n92, n97, n102);
[L533, T533]=mem3f (n78, n83, n103);
[L534, T534]=mem3f (n83, n88, n103);
[L535, T535]=mem3f (n88, n93, n103);
[L536, T536]=mem3f (n93, n98, n103);
[L537, T537]=mem3f (n79, n84, n104);
[L538, T538]=mem3f (n84, n89, n104);
[L539, T539]=mem3f (n89, n94, n104);
[L540, T540]=mem3f (n94, n99, n104);
[L541, T541]=mem3f (n80, n85, n105);
[L542, T542]=mem3f (n85, n90, n105);
[L543, T543]=mem3f (n90, n95, n105);
[L544, T544]=mem3f (n95, n100, n105);

[L545, T545]=mem3f (n101, n106, n126); %
lantai 4
[L546, T546]=mem3f (n106, n111, n126);
[L547, T547]=mem3f (n111, n116, n126);
[L548, T548]=mem3f (n116, n121, n126);
[L549, T549]=mem3f (n102, n107, n127);
[L550, T550]=mem3f (n107, n112, n127);

```

[L551, T551]=mem3f (n112, n117, n127);  
[L552, T552]=mem3f (n117, n122, n127);  
[L553, T553]=mem3f (n103, n108, n128);  
[L554, T554]=mem3f (n108, n113, n128);  
[L555, T555]=mem3f (n113, n118, n128);  
[L556, T556]=mem3f (n118, n123, n128);  
[L557, T557]=mem3f (n104, n109, n129);  
[L558, T558]=mem3f (n109, n114, n129);  
[L559, T559]=mem3f (n114, n119, n129);  
[L560, T560]=mem3f (n119, n124, n129);  
[L561, T561]=mem3f (n105, n110, n129);  
[L562, T562]=mem3f (n110, n115, n129);  
[L563, T563]=mem3f (n115, n120, n129);  
[L564, T564]=mem3f (n120, n125, n129);

[L565, T565]=mem3f (n126, n131, n151); %  
lantai 5  
[L566, T566]=mem3f (n131, n136, n151);  
[L567, T567]=mem3f (n136, n141, n151);  
[L568, T568]=mem3f (n141, n146, n151);  
[L569, T569]=mem3f (n127, n132, n152);  
[L570, T570]=mem3f (n132, n137, n152);  
[L571, T571]=mem3f (n137, n142, n152);  
[L572, T572]=mem3f (n142, n147, n152);  
[L573, T573]=mem3f (n128, n133, n153);  
[L574, T574]=mem3f (n133, n138, n153);  
[L575, T575]=mem3f (n138, n143, n153);  
[L576, T576]=mem3f (n143, n148, n153);  
[L577, T577]=mem3f (n129, n134, n154);  
[L578, T578]=mem3f (n134, n139, n154);  
[L579, T579]=mem3f (n139, n144, n154);  
[L580, T580]=mem3f (n144, n149, n154);  
[L581, T581]=mem3f (n130, n135, n155);  
[L582, T582]=mem3f (n135, n140, n155);  
[L583, T583]=mem3f (n140, n145, n155);  
[L584, T584]=mem3f (n145, n150, n155);

[L585, T585]=mem3f (n151, n156, n172); %  
lantai 6  
[L586, T586]=mem3f (n156, n161, n172);  
[L587, T587]=mem3f (n161, n166, n172);  
[L588, T588]=mem3f (n166, n169, n172);  
[L589, T589]=mem3f (n152, n157, n173);  
[L590, T590]=mem3f (n157, n162, n173);  
[L591, T591]=mem3f (n162, n167, n173);  
[L592, T592]=mem3f (n167, n170, n173);  
[L593, T593]=mem3f (n153, n158, n174);  
[L594, T594]=mem3f (n158, n163, n174);  
[L595, T595]=mem3f (n163, n168, n174);  
[L596, T596]=mem3f (n168, n171, n174);  
[L597, T597]=mem3f (n154, n159, n175);  
[L598, T598]=mem3f (n159, n164, n175);  
[L599, T599]=mem3f (n155, n160, n176);  
[L600, T600]=mem3f (n160, n165, n176);

[L601, T601]=mem3f (n172, n177, n240); %  
lantai 7  
[L602, T602]=mem3f (n177, n182, n193);  
[L603, T603]=mem3f (n182, n187, n193);  
[L604, T604]=mem3f (n187, n190, n193);  
[L605, T605]=mem3f (n173, n178, n194);  
[L606, T606]=mem3f (n178, n183, n194);  
[L607, T607]=mem3f (n183, n188, n194);  
[L608, T608]=mem3f (n188, n191, n194);  
[L609, T609]=mem3f (n174, n179, n195);  
[L610, T610]=mem3f (n179, n184, n195);  
[L611, T611]=mem3f (n184, n189, n195);  
[L612, T612]=mem3f (n189, n192, n195);  
[L613, T613]=mem3f (n175, n180, n196);  
[L614, T614]=mem3f (n180, n185, n196);  
[L615, T615]=mem3f (n176, n181, n197);

[L616, T616]=mem3f (n181, n186, n197);

[L617, T617]=mem3f (n193, n198, n214); %  
lantai 8  
[L618, T618]=mem3f (n198, n203, n214);  
[L619, T619]=mem3f (n203, n208, n214);  
[L620, T620]=mem3f (n208, n211, n214);  
[L621, T621]=mem3f (n194, n199, n215);  
[L622, T622]=mem3f (n199, n204, n215);  
[L623, T623]=mem3f (n204, n209, n215);  
[L624, T624]=mem3f (n209, n212, n215);  
[L625, T625]=mem3f (n195, n200, n216);  
[L626, T626]=mem3f (n200, n205, n216);  
[L627, T627]=mem3f (n205, n210, n216);  
[L628, T628]=mem3f (n210, n213, n216);  
[L629, T629]=mem3f (n196, n201, n217);  
[L630, T630]=mem3f (n201, n206, n217);  
[L631, T631]=mem3f (n197, n202, n218);  
[L632, T632]=mem3f (n202, n207, n218);

[L633, T633]=mem3f (n214, n219, n235); %  
lantai 9  
[L634, T634]=mem3f (n219, n224, n235);  
[L635, T635]=mem3f (n224, n229, n235);  
[L636, T636]=mem3f (n229, n232, n235);  
[L637, T637]=mem3f (n215, n220, n236);  
[L638, T638]=mem3f (n220, n225, n236);  
[L639, T639]=mem3f (n225, n230, n236);  
[L640, T640]=mem3f (n230, n233, n236);  
[L641, T641]=mem3f (n216, n221, n237);  
[L642, T642]=mem3f (n221, n226, n237);  
[L643, T643]=mem3f (n226, n231, n237);  
[L644, T644]=mem3f (n231, n234, n237);  
[L645, T645]=mem3f (n217, n222, n238);  
[L646, T646]=mem3f (n222, n227, n238);  
[L647, T647]=mem3f (n218, n223, n239);  
[L648, T648]=mem3f (n223, n228, n239);

[L649, T649]=mem3f (n235, n240, n256); %  
lantai 10  
[L650, T650]=mem3f (n240, n245, n256);  
[L651, T651]=mem3f (n245, n250, n256);  
[L652, T652]=mem3f (n250, n253, n256);  
[L653, T653]=mem3f (n236, n241, n257);  
[L654, T654]=mem3f (n241, n246, n257);  
[L655, T655]=mem3f (n246, n251, n257);  
[L656, T656]=mem3f (n251, n254, n257);  
[L657, T657]=mem3f (n237, n242, n258);  
[L658, T658]=mem3f (n242, n247, n258);  
[L659, T659]=mem3f (n247, n252, n258);  
[L660, T660]=mem3f (n252, n255, n258);  
[L661, T661]=mem3f (n238, n243, n259);  
[L662, T662]=mem3f (n243, n248, n259);  
[L663, T663]=mem3f (n239, n244, n260);  
[L664, T664]=mem3f (n244, n249, n260);

[L665, T665]=mem3f (n256, n261, n277); %  
lantai 11  
[L666, T666]=mem3f (n261, n266, n277);  
[L667, T667]=mem3f (n266, n271, n277);  
[L668, T668]=mem3f (n271, n274, n277);  
[L669, T669]=mem3f (n257, n262, n278);  
[L670, T670]=mem3f (n262, n267, n278);  
[L671, T671]=mem3f (n267, n272, n278);  
[L672, T672]=mem3f (n272, n275, n278);  
[L673, T673]=mem3f (n258, n263, n279);  
[L674, T674]=mem3f (n263, n268, n279);  
[L675, T675]=mem3f (n268, n273, n279);  
[L676, T676]=mem3f (n273, n276, n279);  
[L677, T677]=mem3f (n259, n264, n280);  
[L678, T678]=mem3f (n264, n269, n280);



```

[L679, T679]=mem3f(n260, n265, n281);
[L680, T680]=mem3f(n265, n270, n281);

[L681, T681]=mem3f(n277, n282, n256); %
lantai 12
[L682, T682]=mem3f(n282, n287, n256);
[L683, T683]=mem3f(n287, n292, n256);
[L684, T684]=mem3f(n292, n295, n256);
[L685, T685]=mem3f(n278, n283, n257);
[L686, T686]=mem3f(n283, n288, n257);
[L687, T687]=mem3f(n288, n293, n257);
[L688, T688]=mem3f(n293, n296, n257);
[L689, T689]=mem3f(n279, n284, n258);
[L690, T690]=mem3f(n284, n289, n258);
[L691, T691]=mem3f(n289, n294, n258);
[L692, T692]=mem3f(n294, n297, n258);
[L693, T693]=mem3f(n280, n285, n259);
[L694, T694]=mem3f(n285, n290, n259);
[L695, T695]=mem3f(n281, n286, n260);
[L696, T696]=mem3f(n286, n291, n260);

E=2.5e7;
v=0.3;
G=E/(2*(1+v));

Ab1=0.15;           % balok 0.3 *0.5
Iy1=1.125e-3;
Iz1=3.125e-3;
Jx1=2.817e-3;

Ab2=0.12;           % balok 0.3 *0.4
Iy2=0.9e-3;
Iz2=1.6e-3;
Jx2=1.944e-3;

Ac1=0.5625;         % kolom ltdasar-lt2
%0.75*0.75
Izc1=26.37e-3;
Iyc1=26.27e-3;
Jxc1=44.6e-3;

Ac2=0.4225;         % kolom lt3-5
%0.65*0.65
Izc2=14.87e-3;
Iyc2=14.87e-3;
Jxc2=25.1e-3;

Ac3=0.25;           % kolom lt6-lt8 0.5
*0.5
Izc3=5.208e-3;
Iyc3=5.208e-3;
Jxc3=8.802e-3;

Ac4=0.16;           % kolom lt9-lt11
0.4 * 0.4
Izc4=2.133e-3;
Iyc4=2.133e-3;
Jxc4=3.605e-3;

% Column
k1=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L1);
k2=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L2);
k3=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L2);
k4=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L4);
k5=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L5);
k6=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L6);
k7=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L7);
k8=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L8);
k9=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L9);
k10=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L10);
k11=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L11);

k12=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L12);

k13=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L13);
k14=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L14);
k15=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L15);
k16=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L16);
k17=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L17);
k18=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L18);
k19=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L19);
k20=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L20);
k21=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L21);
k22=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L22);
k23=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L23);
k24=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L24);

k25=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L25);
k26=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L26);
k27=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L27);
k28=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L28);
k29=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L29);
k30=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L30);
k31=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L31);
k32=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L32);
k33=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L33);
k34=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L34);
k35=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L35);
k36=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L36);

k37=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L37);
k38=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L38);
k39=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L39);
k40=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L40);
k41=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L41);
k42=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L42);
k43=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L43);
k44=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L44);
k45=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L45);
k46=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L46);
k47=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L47);
k48=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L48);

k49=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L37);
k50=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L38);
k51=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L39);
k52=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L40);
k53=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L41);
k54=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L42);
k55=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L43);
k56=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L44);
k57=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L45);
k58=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L58);
k59=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L59);
k60=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L60);

k61=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L61);
k62=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L62);
k63=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L63);
k64=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L64);
k65=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L65);
k66=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L66);
k67=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L67);
k68=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L68);
k69=k13f(E, G, Ac3, Iyc3, Izc3, Jxc3, L69);
k70=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L70);
k71=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L71);
k72=k13f(E, G, Ac4, Iyc4, Izc4, Jxc4, L72);

k73=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L73);
k74=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L74);
k75=k13f(E, G, Ac1, Iyc1, Izc1, Jxc1, L75);
k76=k13f(E, G, Ac2, Iyc2, Izc2, Jxc2, L76);

```



k77=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L77);  
 k78=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L78);  
 k79=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L79);  
 k80=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L80);  
 k81=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L81);  
 k82=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L82);  
 k83=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L83);  
 k84=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L84);  
  
 k85=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L85);  
 k86=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L86);  
 k87=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L87);  
 k88=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L88);  
 k89=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L89);  
 k90=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L90);  
 k91=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L91);  
 k92=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L92);  
 k93=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L93);  
 k94=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L94);  
 k95=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L95);  
 k96=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L96);  
  
 k97=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L97);  
 k98=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L98);  
 k99=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L99);  
 k100=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L100);  
 k101=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L101);  
 k102=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L102);  
 k103=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L103);  
 k104=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L104);  
 k105=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L105);  
 k106=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L106);  
 k107=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L107);  
 k108=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L108);  
  
 k109=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L109);  
 k110=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L110);  
 k111=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L111);  
 k112=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L112);  
 k113=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L113);  
 k114=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L114);  
 k115=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L115);  
 k116=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L116);  
 k117=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L117);  
 k118=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L118);  
 k119=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L119);  
 k120=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L120);  
  
 k121=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L121);  
  
 k122=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L122);  
 k123=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L123);  
 k124=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L124);  
 k125=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L125);  
 k126=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L126);  
 k127=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L127);  
 k128=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L128);  
 k129=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L129);  
 k130=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L130);  
 k131=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L131);  
 k132=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L132);  
  
 k133=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L133);  
 k134=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L134);  
 k135=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L135);  
 k136=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L136);  
 k137=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L137);  
 k138=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L138);  
 k139=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L139);  
 k140=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L140);  
 k141=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L141);  
 k142=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L142);  
 k143=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L143);  
 k144=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L144);  
  
 k145=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L145);  
 k146=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L146);  
 k147=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L147);  
 k148=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L148);  
 k149=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L149);  
 k150=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L150);  
 k151=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L151);  
 k152=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L152);  
 k153=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L153);  
 k154=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L154);  
 k155=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L155);

```

k156=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L156
);
k157=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L157
);
k158=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L158
);
k159=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L159
);
k160=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L160
);
k161=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L161
);
k162=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L162
);
k163=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L163
);
k164=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L164
);
k165=k13f(E,G,Ac3,Iyc3,Izc3,Jxc2,L165
);
k166=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L166
);
k167=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L167
);
k168=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L168
);
k169=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L169
);
k170=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L170
);
k171=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L171
);
k172=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L172
);
k173=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L173
);
k174=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L174
);
k175=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L175
);
k176=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L176
);
k177=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L177
);
k178=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L178
);
k179=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L179
);
k180=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L180
);
k181=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L181
);
k182=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L182
);
k183=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L183
);
k184=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L184
);
k185=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L185
);
k186=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L186
);
k187=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L187
);
k188=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L188
);
k189=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L189
);
k190=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L190
);
k191=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L191
);
k192=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L192
);
k193=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L193
);
k194=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L194
);
k195=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L195
);
k196=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L196
);
k197=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L197
);
k198=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L198
);
k199=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L199
);
k200=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L200
);
k201=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L201
);
k202=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L202
);
k203=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L203
);
k204=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L204
);
k205=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L205
);
k206=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L206
);
k207=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L207
);
k208=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L208
);
k209=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L209
);
k210=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L210
);
k211=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L211
);
k212=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L212
);
k213=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L213
);
k214=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L214
);
k215=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L215
);
k216=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L216
);
k217=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L217
);
k218=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L218
);
k219=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L219
);
k220=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L220
);
k221=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L221
);
k222=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L222
);

```

```

k223=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L223
);
k224=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L224
);
k225=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L225
);
k226=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L226
);

k227=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L227
);
k228=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L228
);
k229=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L229
);
k230=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L230
);
k231=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L231
);
k232=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L232
);
k233=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L233
);
k234=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L234
);
k235=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L235
);
k236=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L236
);
k237=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L237
);
k238=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L238
);

k239=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L239
);
k240=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L240
);
k241=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L241
);
k242=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L242
);
k243=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L243
);
k244=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L244
);
k245=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L245
);
k246=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L246
);
k247=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L247
);
k248=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L248
);
k249=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L249
);
k250=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L250
);

k251=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L251
);
k252=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L252
);
k253=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L253
);
k254=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L254
);
k255=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L255
);
k256=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L256
);

k257=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L257
);
k258=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L258
);
k259=k13f(E,G,Ac3,Iyc3,Izc3,Jxc3,L259
);
k260=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L260
);
k261=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L261
);
k262=k13f(E,G,Ac4,Iyc4,Izc4,Jxc4,L262
);

k263=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L263
);
k264=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L264
);
k265=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L265
);
k266=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L266
);
k267=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L267
);

k268=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L268
);
k269=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L269
);
k270=k13f(E,G,Ac1,Iyc1,Izc1,Jxc1,L270
);
k271=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L271
);
k272=k13f(E,G,Ac2,Iyc2,Izc2,Jxc2,L272
);

%Beam
%Arah x
k273=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L273
);% lantai 1
k274=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L274
);
k275=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L275
);
k276=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L276
);
k277=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L277
);
k278=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L278
);
k279=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L279
);
k280=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L280
);
k281=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L281
);
k282=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L282
);
k283=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L283
);
k284=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L284
);
k285=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L285
);
k286=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L286
);
k287=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L287
);
k288=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L288
);
k289=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L289
);

```

```
k290=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L290
);
k291=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L291
);
k292=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L292
);
k293=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L293
);% lantai 2
k294=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L294
);
k295=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L295
);
k296=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L296
);
k297=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L297
);
k298=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L298
);
k299=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L299
);
k300=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L300
);
k301=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L301
);
k302=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L302
);
k303=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L303
);
k304=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L304
);
k305=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L305
);
k306=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L306
);
k307=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L307
);
k308=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L308
);
k309=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L309
);
k310=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L310
);
k311=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L311
);
k312=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L312
);
k313=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L313
);% lantai 3
k314=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L314
);
k315=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L315
);
k316=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L316
);
k317=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L317
);
k318=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L318
);
k319=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L319
);
k320=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L320
);
k321=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L321
);
k322=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L322
);
k323=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L323
);
k324=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L324
);
k325=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L325
);
k326=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L326
);
k327=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L327
);
k328=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L328
);
k329=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L329
);
k330=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L330
);
k331=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L331
);
k332=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L332
);
k333=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L333
);% lantai 4
k334=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L334
);
k335=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L335
);
k336=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L336
);
k337=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L337
);
k338=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L338
);
k339=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L339
);
k340=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L340
);
k341=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L341
);
k342=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L342
);
k343=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L343
);
k344=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L344
);
k345=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L345
);
k346=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L346
);
k347=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L347
);
k348=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L348
);
k349=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L349
);
k350=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L350
);
k351=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L351
);
k352=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L352
);
k353=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L353
);% lantai 5
k354=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L354
);
k355=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L355
);
k356=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L356
);
k357=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L357
);
```

```

k358=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L358
);
k359=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L359
);
k360=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L360
);
k361=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L361
);
k362=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L362
);
k363=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L363
);
k364=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L364
);
k365=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L365
);
k366=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L366
);
k367=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L367
);
k368=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L368
);
k369=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L369
);
k370=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L370
);
k371=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L371
);
k372=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L372
);

k373=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L373
);% lantai 6
k374=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L374
);
k375=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L375
);
k376=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L376
);
k377=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L377
);
k378=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L378
);
k379=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L379
);
k380=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L380
);
k381=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L381
);
k382=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L382
);
k383=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L383
);
k384=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L384
);
k385=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L385
);
k386=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L386
);
k387=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L387
);
k388=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L388
);

k389=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L389
);% lantai 7
k390=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L390
);
k391=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L391
);

k392=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L392
);
k393=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L393
);
k394=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L394
);
k395=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L395
);
k396=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L396
);
k397=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L397
);
k398=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L398
);
k399=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L399
);
k400=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L400
);
k401=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L401
);
k402=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L402
);
k403=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L403
);
k404=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L404
);

k405=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L405
);% lantai 8
k406=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L406
);
k407=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L407
);
k408=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L408
);
k409=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L409
);
k410=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L410
);
k411=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L411
);
k412=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L412
);
k413=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L413
);
k414=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L414
);
k415=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L415
);
k416=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L416
);
k417=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L417
);
k418=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L418
);
k419=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L419
);
k420=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L420
);

k421=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L421
);% lantai 9
k422=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L422
);
k423=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L423
);
k424=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L424
);
k425=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L425
);

```

```

k426=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L426
);
k427=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L427
);
k428=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L428
);
k429=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L429
);
k430=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L430
);
k431=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L431
);
k432=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L432
);
k433=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L433
);
k434=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L434
);
k435=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L435
);
k436=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L436
);
k437=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L437
);% lantai 10
k438=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L438
);
k439=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L439
);
k440=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L440
);
k441=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L441
);
k442=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L442
);
k443=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L443
);
k444=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L444
);
k445=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L445
);
k446=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L446
);
k447=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L447
);
k448=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L448
);
k449=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L449
);
k450=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L450
);
k451=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L451
);
k452=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L452
);
k453=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L453
);% lantai 11
k454=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L454
);
k455=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L455
);
k456=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L456
);
k457=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L457
);
k458=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L458
);
k459=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L459
);
k460=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L460
);
k461=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L461
);
k462=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L462
);
k463=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L463
);
k464=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L464
);
k465=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L465
);
k466=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L466
);
k467=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L467
);
k468=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L468
);
k469=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L469
);% lantai 12
k470=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L470
);
k471=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L471
);
k472=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L472
);
k473=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L473
);
k474=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L474
);
k475=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L475
);
k476=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L476
);
k477=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L477
);
k478=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L478
);
k479=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L479
);
k480=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L480
);
k481=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L481
);
k482=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L482
);
k483=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L483
);
k484=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L484
);
%Aras z
k485=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L485
);% lantai 1
k486=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L486
);
k487=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L487
);
k488=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L488
);
k489=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L489
);
k490=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L490
);
k491=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L491
);
k492=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L492
);
k493=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L493
);

```



```

k563=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L563
);
k564=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L564
);
k565=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L565
);% lantai 5
k566=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L566
);
k567=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L567
);
k568=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L568
);
k569=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L569
);
k570=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L570
);
k571=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L571
);
k572=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L572
);
k573=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L573
);
k574=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L574
);
k575=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L575
);
k576=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L576
);
k577=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L577
);
k578=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L578
);
k579=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L579
);
k580=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L580
);
k581=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L581
);
k582=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L582
);
k583=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L583
);
k584=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L584
);
k585=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L585
);% lantai 6
k586=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L586
);
k587=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L587
);
k588=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L588
);
k589=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L589
);
k590=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L590
);
k591=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L591
);
k592=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L592
);
k593=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L593
);
k594=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L594
);
k595=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L595
);
k596=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L596
);
k597=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L597
);
k598=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L598
);
k599=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L599
);
k600=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L600
);
k601=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L601
);% lantai 7
k602=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L602
);
k603=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L603
);
k604=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L604
);
k605=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L605
);
k606=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L606
);
k607=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L607
);
k608=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L608
);
k609=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L609
);
k610=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L610
);
k611=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L611
);
k612=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L612
);
k613=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L613
);
k614=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L614
);
k615=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L615
);
k616=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L616
);
k617=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L617
);% lantai 8
k618=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L618
);
k619=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L619
);
k620=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L620
);
k621=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L621
);
k622=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L622
);
k623=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L623
);
k624=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L624
);
k625=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L625
);
k626=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L626
);
k627=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L627
);
k628=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L628
);
k629=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L629
);
k630=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L630
);

```



```

k631=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L631
);
k632=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L632
);
k633=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L633
);% lantai 9
k634=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L634
);
k635=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L635
);
k636=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L636
);
k637=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L637
);
k638=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L638
);
k639=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L639
);
k640=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L640
);
k641=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L641
);
k642=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L642
);
k643=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L643
);
k644=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L644
);
k645=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L645
);
k646=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L646
);
k647=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L647
);
k648=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L648
);
k649=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L649
);% lantai 10
k650=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L650
);
k651=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L651
);
k652=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L652
);
k653=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L653
);
k654=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L654
);
k655=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L655
);
k656=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L656
);
k657=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L657
);
k658=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L658
);
k659=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L659
);
k660=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L660
);
k661=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L661
);
k662=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L662
);
k663=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L663
);
k664=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L664
);
k665=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L665
);% lantai 11
k666=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L666
);
k667=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L667
);
k668=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L668
);
k669=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L669
);
k670=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L670
);
k671=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L671
);
k672=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L672
);
k673=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L673
);
k674=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L674
);
k675=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L675
);
k676=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L676
);
k677=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L677
);
k678=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L678
);
k679=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L679
);
k680=k13f(E,G,Ab1,Iyb1,Izb1,Jxb1,L680
);
k681=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L681
);% lantai 12
k682=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L682
);
k683=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L683
);
k684=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L684
);
k685=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L685
);
k686=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L686
);
k687=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L687
);
k688=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L688
);
k689=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L689
);
k690=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L690
);
k691=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L691
);
k692=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L692
);
k693=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L693
);
k694=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L694
);
k695=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L695
);
k696=k13f(E,G,Ab2,Iyb2,Izb2,Jxb2,L696
);
%Column
K1=kg(k1,T1);
K2=kg(k2,T2);
K3=kg(k3,T3);
K4=kg(k4,T4);

```

K5=kg (k5, T5);  
 K6=kg (k6, T6);  
 K7=kg (k7, T7);  
 K8=kg (k8, T8);  
 K9=kg (k9, T9);  
 K10=kg (k10, T10);  
 K11=kg (k11, T11);  
 K12=kg (k12, T12);  
 K13=kg (k13, T13);  
 K14=kg (k14, T14);  
 K15=kg (k15, T15);  
 K16=kg (k16, T16);  
 K17=kg (k17, T17);  
 K18=kg (k18, T18);  
 K19=kg (k19, T19);  
 K20=kg (k20, T20);  
 K21=kg (k21, T21);  
 K22=kg (k22, T22);  
 K23=kg (k23, T23);  
 K24=kg (k24, T24);  
 K25=kg (k25, T25);  
 K26=kg (k26, T26);  
 K27=kg (k27, T27);  
 K28=kg (k28, T28);  
 K29=kg (k29, T29);  
 K30=kg (k30, T30);  
 K31=kg (k31, T31);  
 K32=kg (k32, T32);  
 K33=kg (k33, T33);  
 K34=kg (k34, T34);  
 K35=kg (k35, T35);  
 K36=kg (k36, T36);  
 K37=kg (k37, T37);  
 K38=kg (k38, T38);  
 K39=kg (k39, T39);  
 K40=kg (k40, T40);  
 K41=kg (k41, T41);  
 K42=kg (k42, T42);  
 K43=kg (k43, T43);  
 K44=kg (k44, T44);  
 K45=kg (k45, T45);  
 K46=kg (k46, T46);  
 K47=kg (k47, T47);  
 K48=kg (k48, T48);  
 K49=kg (k49, T49);  
 K50=kg (k50, T50);  
 K51=kg (k51, T51);  
 K52=kg (k52, T52);  
 K53=kg (k53, T53);  
 K54=kg (k54, T54);  
 K55=kg (k55, T55);  
 K56=kg (k56, T56);  
 K57=kg (k57, T57);  
 K58=kg (k58, T58);  
 K59=kg (k59, T59);  
 K60=kg (k60, T60);  
 K61=kg (k61, T61);  
 K62=kg (k62, T62);  
 K63=kg (k63, T63);  
 K64=kg (k64, T64);  
 K65=kg (k65, T65);  
 K66=kg (k66, T66);  
 K67=kg (k67, T67);  
 K68=kg (k68, T68);  
 K69=kg (k69, T69);  
 K70=kg (k70, T70);  
 K71=kg (k71, T71);  
 K72=kg (k72, T72);  
 K73=kg (k73, T73);  
 K74=kg (k74, T74);  
 K75=kg (k75, T75);  
 K76=kg (k76, T76);  
 K77=kg (k77, T77);  
 K78=kg (k78, T78);  
 K79=kg (k79, T79);  
 K80=kg (k80, T80);  
 K81=kg (k81, T81);  
 K82=kg (k82, T82);  
 K83=kg (k83, T83);  
 K84=kg (k84, T84);  
 K85=kg (k85, T85);  
 K86=kg (k86, T86);  
 K87=kg (k87, T87);  
 K88=kg (k88, T88);  
 K89=kg (k89, T89);  
 K90=kg (k90, T90);  
 K91=kg (k91, T91);  
 K92=kg (k92, T92);  
 K93=kg (k93, T93);  
 K94=kg (k94, T94);  
 K95=kg (k95, T95);  
 K96=kg (k96, T96);  
 K97=kg (k97, T97);  
 K98=kg (k98, T98);  
 K99=kg (k99, T99);  
 K100=kg (k100, T100);  
 K101=kg (k101, T101);  
 K102=kg (k102, T102);  
 K103=kg (k103, T103);  
 K104=kg (k104, T104);  
 K105=kg (k105, T105);  
 K106=kg (k106, T106);  
 K107=kg (k107, T107);  
 K108=kg (k108, T108);  
 K109=kg (k109, T109);  
 K110=kg (k110, T110);  
 K111=kg (k111, T111);  
 K112=kg (k112, T112);  
 K113=kg (k113, T113);  
 K114=kg (k114, T114);  
 K115=kg (k115, T115);  
 K116=kg (k116, T116);  
 K117=kg (k117, T117);  
 K118=kg (k118, T118);  
 K119=kg (k119, T119);  
 K120=kg (k120, T120);  
 K121=kg (k121, T121);  
 K122=kg (k122, T122);  
 K123=kg (k123, T123);  
 K124=kg (k124, T124);  
 K125=kg (k125, T125);  
 K126=kg (k126, T126);  
 K127=kg (k127, T127);  
 K128=kg (k128, T128);  
 K129=kg (k129, T129);  
 K130=kg (k130, T130);  
 K131=kg (k131, T131);  
 K132=kg (k132, T132);  
 K133=kg (k133, T133);  
 K134=kg (k134, T134);  
 K135=kg (k135, T135);  
 K136=kg (k136, T136);  
 K137=kg (k137, T137);  
 K138=kg (k138, T138);  
 K139=kg (k139, T139);  
 K140=kg (k140, T140);  
 K141=kg (k141, T141);  
 K142=kg (k142, T142);  
 K143=kg (k143, T143);  
 K144=kg (k144, T144);  
 K145=kg (k145, T145);  
 K146=kg (k146, T146);

K147=kg (k147, T147) ;  
 K148=kg (k148, T148) ;  
 K149=kg (k149, T149) ;  
 K150=kg (k150, T150) ;  
 K151=kg (k151, T151) ;  
 K152=kg (k152, T152) ;  
 K153=kg (k153, T153) ;  
 K154=kg (k154, T154) ;  
 K155=kg (k155, T155) ;  
 K156=kg (k156, T156) ;  
 K157=kg (k157, T157) ;  
 K158=kg (k158, T158) ;  
 K159=kg (k159, T159) ;  
 K160=kg (k160, T160) ;  
 K161=kg (k161, T161) ;  
 K162=kg (k162, T162) ;  
 K163=kg (k163, T163) ;  
 K164=kg (k164, T164) ;  
 K165=kg (k165, T165) ;  
 K166=kg (k166, T166) ;  
 K167=kg (k167, T167) ;  
 K168=kg (k168, T168) ;  
 K169=kg (k169, T169) ;  
 K170=kg (k170, T170) ;  
 K171=kg (k171, T171) ;  
 K172=kg (k172, T172) ;  
 K173=kg (k173, T173) ;  
 K174=kg (k174, T174) ;  
 K175=kg (k175, T175) ;  
 K176=kg (k176, T176) ;  
 K177=kg (k177, T177) ;  
 K178=kg (k178, T178) ;  
 K179=kg (k179, T179) ;  
 K180=kg (k180, T180) ;  
 K181=kg (k181, T181) ;  
 K182=kg (k182, T182) ;  
 K183=kg (k183, T183) ;  
 K184=kg (k184, T184) ;  
 K185=kg (k185, T185) ;  
 K186=kg (k186, T186) ;  
 K187=kg (k187, T187) ;  
 K188=kg (k188, T188) ;  
 K189=kg (k189, T189) ;  
 K190=kg (k190, T190) ;  
 K191=kg (k191, T191) ;  
 K192=kg (k192, T192) ;  
 K193=kg (k193, T193) ;  
 K194=kg (k194, T194) ;  
 K195=kg (k195, T195) ;  
 K196=kg (k196, T196) ;  
 K197=kg (k197, T197) ;  
 K198=kg (k198, T198) ;  
 K199=kg (k199, T199) ;  
 K200=kg (k200, T200) ;  
 K201=kg (k201, T201) ;  
 K202=kg (k202, T202) ;  
 K203=kg (k203, T203) ;  
 K204=kg (k204, T204) ;  
 K205=kg (k205, T205) ;  
 K206=kg (k206, T206) ;  
 K207=kg (k207, T207) ;  
 K208=kg (k208, T208) ;  
 K209=kg (k209, T209) ;  
 K210=kg (k210, T210) ;  
 K211=kg (k211, T211) ;  
 K212=kg (k212, T212) ;  
 K213=kg (k213, T213) ;  
 K214=kg (k214, T214) ;  
 K215=kg (k215, T215) ;  
 K216=kg (k216, T216) ;  
 K217=kg (k217, T217) ;

K218=kg (k218, T218) ;  
 K219=kg (k219, T219) ;  
 K220=kg (k220, T220) ;  
 K221=kg (k221, T221) ;  
 K222=kg (k222, T222) ;  
 K223=kg (k223, T223) ;  
 K224=kg (k224, T224) ;  
 K225=kg (k225, T225) ;  
 K226=kg (k226, T226) ;  
 K227=kg (k227, T227) ;  
 K228=kg (k228, T228) ;  
 K229=kg (k229, T229) ;  
 K230=kg (k230, T230) ;  
 K231=kg (k231, T231) ;  
 K232=kg (k232, T232) ;  
 K233=kg (k233, T233) ;  
 K234=kg (k234, T234) ;  
 K235=kg (k235, T235) ;  
 K236=kg (k236, T236) ;  
 K237=kg (k237, T237) ;  
 K238=kg (k238, T238) ;  
 K239=kg (k239, T239) ;  
 K240=kg (k240, T240) ;  
 K241=kg (k241, T241) ;  
 K242=kg (k242, T242) ;  
 K243=kg (k243, T243) ;  
 K244=kg (k244, T244) ;  
 K245=kg (k245, T245) ;  
 K246=kg (k246, T246) ;  
 K247=kg (k247, T247) ;  
 K248=kg (k248, T248) ;  
 K249=kg (k249, T249) ;  
 K250=kg (k250, T250) ;  
 K251=kg (k251, T251) ;  
 K252=kg (k252, T252) ;  
 K253=kg (k253, T253) ;  
 K254=kg (k254, T254) ;  
 K255=kg (k255, T255) ;  
 K256=kg (k256, T256) ;  
 K257=kg (k257, T257) ;  
 K258=kg (k258, T258) ;  
 K259=kg (k259, T259) ;  
 K260=kg (k260, T260) ;  
 K261=kg (k261, T261) ;  
 K262=kg (k262, T262) ;  
 K263=kg (k263, T263) ;  
 K264=kg (k264, T264) ;  
 K265=kg (k265, T265) ;  
 K266=kg (k266, T266) ;  
 K267=kg (k267, T267) ;  
 K268=kg (k268, T268) ;  
 K269=kg (k269, T269) ;  
 K270=kg (k270, T270) ;  
 K271=kg (k271, T271) ;  
 K272=kg (k272, T272) ;

%Beam

K273=kg (k273, T273) ;  
 K274=kg (k274, T274) ;  
 K275=kg (k275, T275) ;  
 K276=kg (k276, T276) ;  
 K277=kg (k277, T277) ;  
 K278=kg (k278, T278) ;  
 K279=kg (k279, T279) ;  
 K280=kg (k280, T280) ;  
 K281=kg (k281, T281) ;  
 K282=kg (k282, T282) ;  
 K283=kg (k283, T283) ;  
 K284=kg (k284, T284) ;  
 K285=kg (k285, T285) ;  
 K286=kg (k286, T286) ;

K287=kg (k287, T287);  
K288=kg (k288, T288);  
K289=kg (k289, T289);  
K290=kg (k290, T290);  
K291=kg (k291, T291);  
K292=kg (k292, T292);  
K293=kg (k293, T293);  
K294=kg (k294, T294);  
K295=kg (k295, T295);  
K296=kg (k296, T296);  
K297=kg (k297, T297);  
K298=kg (k298, T298);  
K299=kg (k299, T299);  
K300=kg (k300, T300);  
K301=kg (k301, T301);  
K302=kg (k302, T302);  
K303=kg (k303, T303);  
K304=kg (k304, T304);  
K305=kg (k305, T305);  
K306=kg (k306, T306);  
K307=kg (k307, T307);  
K308=kg (k308, T308);  
K309=kg (k309, T309);  
K310=kg (k310, T310);  
K311=kg (k311, T311);  
K312=kg (k312, T312);  
K313=kg (k313, T313);  
K314=kg (k314, T314);  
K315=kg (k315, T315);  
K316=kg (k316, T316);  
K317=kg (k317, T317);  
K318=kg (k318, T318);  
K319=kg (k319, T319);  
K320=kg (k320, T320);  
K321=kg (k321, T321);  
K322=kg (k322, T322);  
K323=kg (k323, T323);  
K324=kg (k324, T324);  
K325=kg (k325, T325);  
K326=kg (k326, T326);  
K327=kg (k327, T327);  
K328=kg (k328, T328);  
K329=kg (k329, T329);  
K330=kg (k330, T330);  
K331=kg (k331, T331);  
K332=kg (k332, T332);  
K333=kg (k333, T333);  
K334=kg (k334, T334);  
K335=kg (k335, T335);  
K336=kg (k336, T336);  
K337=kg (k337, T337);  
K338=kg (k338, T338);  
K339=kg (k339, T339);  
K340=kg (k340, T340);  
K341=kg (k341, T341);  
K342=kg (k342, T342);  
K343=kg (k343, T343);  
K344=kg (k344, T344);  
K345=kg (k345, T345);  
K346=kg (k346, T346);  
K347=kg (k347, T347);  
K348=kg (k348, T348);  
K349=kg (k349, T349);  
K350=kg (k350, T350);  
K351=kg (k351, T351);  
K352=kg (k352, T352);  
K353=kg (k353, T353);  
K354=kg (k354, T354);  
K355=kg (k355, T355);  
K356=kg (k356, T356);  
K357=kg (k357, T357);

K358=kg (k358, T358);  
K359=kg (k359, T359);  
K360=kg (k360, T360);  
K361=kg (k361, T361);  
K362=kg (k362, T362);  
K363=kg (k363, T363);  
K364=kg (k364, T364);  
K365=kg (k365, T365);  
K366=kg (k366, T366);  
K367=kg (k367, T367);  
K368=kg (k368, T368);  
K369=kg (k369, T369);  
K370=kg (k370, T370);  
K371=kg (k371, T371);  
K372=kg (k372, T372);  
K373=kg (k373, T373);  
K374=kg (k374, T374);  
K375=kg (k375, T375);  
K376=kg (k376, T376);  
K377=kg (k377, T377);  
K378=kg (k378, T378);  
K379=kg (k379, T379);  
K380=kg (k380, T380);  
K381=kg (k381, T381);  
K382=kg (k382, T382);  
K383=kg (k383, T383);  
K384=kg (k384, T384);  
K385=kg (k385, T385);  
K386=kg (k386, T386);  
K387=kg (k387, T387);  
K388=kg (k388, T388);  
K389=kg (k389, T389);  
K390=kg (k390, T390);  
K391=kg (k391, T391);  
K392=kg (k392, T392);  
K393=kg (k393, T393);  
K394=kg (k394, T394);  
K395=kg (k395, T395);  
K396=kg (k396, T396);  
K397=kg (k397, T397);  
K398=kg (k398, T398);  
K399=kg (k399, T399);  
K400=kg (k400, T400);  
K401=kg (k401, T401);  
K402=kg (k402, T402);  
K403=kg (k403, T403);  
K404=kg (k404, T404);  
K405=kg (k405, T405);  
K406=kg (k406, T406);  
K407=kg (k407, T407);  
K408=kg (k408, T408);  
K409=kg (k409, T409);  
K410=kg (k410, T410);  
K411=kg (k411, T411);  
K412=kg (k412, T412);  
K413=kg (k413, T413);  
K414=kg (k414, T414);  
K415=kg (k415, T415);  
K416=kg (k416, T416);  
K417=kg (k417, T417);  
K418=kg (k418, T418);  
K419=kg (k419, T419);  
K420=kg (k420, T420);  
K421=kg (k421, T421);  
K422=kg (k422, T422);  
K423=kg (k423, T423);  
K424=kg (k424, T424);  
K425=kg (k425, T425);  
K426=kg (k426, T426);  
K427=kg (k427, T427);  
K428=kg (k428, T428);

K429=kg (k429, T429) ;  
 K430=kg (k430, T430) ;  
 K431=kg (k431, T431) ;  
 K432=kg (k432, T432) ;  
 K433=kg (k433, T433) ;  
 K434=kg (k434, T434) ;  
 K435=kg (k435, T435) ;  
 K436=kg (k436, T436) ;  
 K437=kg (k437, T437) ;  
 K438=kg (k438, T438) ;  
 K439=kg (k439, T439) ;  
 K440=kg (k440, T440) ;  
 K441=kg (k441, T441) ;  
 K442=kg (k442, T442) ;  
 K443=kg (k443, T443) ;  
 K444=kg (k444, T444) ;  
 K445=kg (k445, T445) ;  
 K446=kg (k446, T446) ;  
 K447=kg (k447, T447) ;  
 K448=kg (k448, T448) ;  
 K449=kg (k449, T449) ;  
 K450=kg (k450, T450) ;  
 K451=kg (k451, T451) ;  
 K452=kg (k452, T452) ;  
 K453=kg (k453, T453) ;  
 K454=kg (k454, T454) ;  
 K455=kg (k455, T455) ;  
 K456=kg (k456, T456) ;  
 K457=kg (k457, T457) ;  
 K458=kg (k458, T458) ;  
 K459=kg (k459, T459) ;  
 K460=kg (k460, T460) ;  
 K461=kg (k461, T461) ;  
 K462=kg (k462, T462) ;  
 K463=kg (k463, T463) ;  
 K464=kg (k464, T464) ;  
 K465=kg (k465, T465) ;  
 K466=kg (k466, T466) ;  
 K467=kg (k467, T467) ;  
 K468=kg (k468, T468) ;  
 K469=kg (k469, T469) ;  
 K470=kg (k470, T470) ;  
 K471=kg (k471, T471) ;  
 K472=kg (k472, T472) ;  
 K473=kg (k473, T473) ;  
 K474=kg (k474, T474) ;  
 K475=kg (k475, T475) ;  
 K476=kg (k476, T476) ;  
 K477=kg (k477, T477) ;  
 K478=kg (k478, T478) ;  
 K479=kg (k479, T479) ;  
 K480=kg (k480, T480) ;  
 K481=kg (k481, T481) ;  
 K482=kg (k482, T482) ;  
 K483=kg (k483, T483) ;  
 K484=kg (k484, T484) ;  
 K485=kg (k485, T485) ;  
 K486=kg (k486, T486) ;  
 K487=kg (k487, T487) ;  
 K488=kg (k488, T488) ;  
 K489=kg (k489, T489) ;  
 K490=kg (k490, T490) ;  
 K491=kg (k491, T491) ;  
 K492=kg (k492, T492) ;  
 K493=kg (k493, T493) ;  
 K494=kg (k494, T494) ;  
 K495=kg (k495, T495) ;  
 K496=kg (k496, T496) ;  
 K497=kg (k497, T497) ;  
 K498=kg (k498, T498) ;  
 K499=kg (k499, T499) ;  
 K500=kg (k500, T500) ;  
 K501=kg (k501, T501) ;  
 K502=kg (k502, T502) ;  
 K503=kg (k503, T503) ;  
 K504=kg (k504, T504) ;  
 K505=kg (k505, T505) ;  
 K506=kg (k506, T506) ;  
 K507=kg (k507, T507) ;  
 K508=kg (k508, T508) ;  
 K509=kg (k509, T509) ;  
 K510=kg (k510, T510) ;  
 K511=kg (k511, T511) ;  
 K512=kg (k512, T512) ;  
 K513=kg (k513, T513) ;  
 K514=kg (k514, T514) ;  
 K515=kg (k515, T515) ;  
 K516=kg (k516, T516) ;  
 K517=kg (k517, T517) ;  
 K518=kg (k518, T518) ;  
 K519=kg (k519, T519) ;  
 K520=kg (k520, T520) ;  
 K521=kg (k521, T521) ;  
 K522=kg (k522, T522) ;  
 K523=kg (k523, T523) ;  
 K524=kg (k524, T524) ;  
 K525=kg (k525, T525) ;  
 K526=kg (k526, T526) ;  
 K527=kg (k527, T527) ;  
 K528=kg (k528, T528) ;  
 K529=kg (k529, T529) ;  
 K530=kg (k530, T530) ;  
 K531=kg (k531, T531) ;  
 K532=kg (k532, T532) ;  
 K533=kg (k533, T533) ;  
 K534=kg (k534, T534) ;  
 K535=kg (k535, T535) ;  
 K536=kg (k536, T536) ;  
 K537=kg (k537, T537) ;  
 K538=kg (k538, T538) ;  
 K539=kg (k539, T539) ;  
 K540=kg (k540, T540) ;  
 K541=kg (k541, T541) ;  
 K542=kg (k542, T542) ;  
 K543=kg (k543, T543) ;  
 K544=kg (k544, T544) ;  
 K545=kg (k545, T545) ;  
 K546=kg (k546, T546) ;  
 K547=kg (k547, T547) ;  
 K548=kg (k548, T548) ;  
 K549=kg (k549, T549) ;  
 K550=kg (k550, T550) ;  
 K551=kg (k551, T551) ;  
 K552=kg (k552, T552) ;  
 K553=kg (k553, T553) ;  
 K554=kg (k554, T554) ;  
 K555=kg (k555, T555) ;  
 K556=kg (k556, T556) ;  
 K557=kg (k557, T557) ;  
 K558=kg (k558, T558) ;  
 K559=kg (k559, T559) ;  
 K560=kg (k560, T560) ;  
 K561=kg (k561, T561) ;  
 K562=kg (k562, T562) ;  
 K563=kg (k563, T563) ;  
 K564=kg (k564, T564) ;  
 K565=kg (k565, T565) ;  
 K566=kg (k566, T566) ;  
 K567=kg (k567, T567) ;  
 K568=kg (k568, T568) ;  
 K569=kg (k569, T569) ;  
 K570=kg (k570, T570) ;

K571=kg (k571, T571) ;  
 K572=kg (k572, T572) ;  
 K573=kg (k573, T573) ;  
 K574=kg (k574, T574) ;  
 K575=kg (k575, T575) ;  
 K576=kg (k576, T576) ;  
 K577=kg (k577, T577) ;  
 K578=kg (k578, T578) ;  
 K579=kg (k579, T579) ;  
 K580=kg (k580, T580) ;  
 K581=kg (k581, T581) ;  
 K582=kg (k582, T582) ;  
 K583=kg (k583, T583) ;  
 K584=kg (k584, T584) ;  
 K585=kg (k585, T585) ;  
 K586=kg (k586, T586) ;  
 K587=kg (k587, T587) ;  
 K588=kg (k588, T588) ;  
 K589=kg (k589, T589) ;  
 K590=kg (k590, T590) ;  
 K591=kg (k591, T591) ;  
 K592=kg (k592, T592) ;  
 K593=kg (k593, T593) ;  
 K594=kg (k594, T594) ;  
 K595=kg (k595, T595) ;  
 K596=kg (k596, T596) ;  
 K597=kg (k597, T597) ;  
 K598=kg (k598, T598) ;  
 K599=kg (k599, T599) ;  
 K600=kg (k600, T600) ;  
 K601=kg (k601, T601) ;  
 K602=kg (k602, T602) ;  
 K603=kg (k603, T603) ;  
 K604=kg (k604, T604) ;  
 K605=kg (k605, T605) ;  
 K606=kg (k606, T606) ;  
 K607=kg (k607, T607) ;  
 K608=kg (k608, T608) ;  
 K609=kg (k609, T609) ;  
 K610=kg (k610, T610) ;  
 K611=kg (k611, T611) ;  
 K612=kg (k612, T612) ;  
 K613=kg (k613, T613) ;  
 K614=kg (k614, T614) ;  
 K615=kg (k615, T615) ;  
 K616=kg (k616, T616) ;  
 K617=kg (k617, T617) ;  
 K618=kg (k618, T618) ;  
 K619=kg (k619, T619) ;  
 K620=kg (k620, T620) ;  
 K621=kg (k621, T621) ;  
 K622=kg (k622, T622) ;  
 K623=kg (k623, T623) ;  
 K624=kg (k624, T624) ;  
 K625=kg (k625, T625) ;  
 K626=kg (k626, T626) ;  
 K627=kg (k627, T627) ;  
 K628=kg (k628, T628) ;  
 K629=kg (k629, T629) ;  
 K630=kg (k630, T630) ;  
 K631=kg (k631, T631) ;  
 K632=kg (k632, T632) ;  
 K633=kg (k633, T633) ;  
 K634=kg (k634, T634) ;  
 K635=kg (k635, T635) ;  
 K636=kg (k636, T636) ;  
 K637=kg (k637, T637) ;  
 K638=kg (k638, T638) ;  
 K639=kg (k639, T639) ;  
 K640=kg (k640, T640) ;  
 K641=kg (k641, T641) ;

K642=kg (k642, T642) ;  
 K643=kg (k643, T643) ;  
 K644=kg (k644, T644) ;  
 K645=kg (k645, T645) ;  
 K646=kg (k646, T646) ;  
 K647=kg (k647, T647) ;  
 K648=kg (k648, T648) ;  
 K649=kg (k649, T649) ;  
 K650=kg (k650, T650) ;  
 K651=kg (k651, T651) ;  
 K652=kg (k652, T652) ;  
 K653=kg (k653, T653) ;  
 K654=kg (k654, T654) ;  
 K655=kg (k655, T655) ;  
 K656=kg (k656, T656) ;  
 K657=kg (k657, T657) ;  
 K658=kg (k658, T658) ;  
 K659=kg (k659, T659) ;  
 K660=kg (k660, T660) ;  
 K661=kg (k661, T661) ;  
 K662=kg (k662, T662) ;  
 K663=kg (k663, T663) ;  
 K664=kg (k664, T664) ;  
 K665=kg (k665, T665) ;  
 K666=kg (k666, T666) ;  
 K667=kg (k667, T667) ;  
 K668=kg (k668, T668) ;  
 K669=kg (k669, T669) ;  
 K670=kg (k670, T670) ;  
 K671=kg (k671, T671) ;  
 K672=kg (k672, T672) ;  
 K673=kg (k673, T673) ;  
 K674=kg (k674, T674) ;  
 K675=kg (k675, T675) ;  
 K676=kg (k676, T676) ;  
 K677=kg (k677, T677) ;  
 K678=kg (k678, T678) ;  
 K679=kg (k679, T679) ;  
 K680=kg (k680, T680) ;  
 K681=kg (k681, T681) ;  
 K682=kg (k682, T682) ;  
 K683=kg (k683, T683) ;  
 K684=kg (k684, T684) ;  
 K685=kg (k685, T685) ;  
 K686=kg (k686, T686) ;  
 K687=kg (k687, T687) ;  
 K688=kg (k688, T688) ;  
 K689=kg (k689, T689) ;  
 K690=kg (k690, T690) ;  
 K691=kg (k691, T691) ;  
 K692=kg (k692, T692) ;  
 K693=kg (k693, T693) ;  
 K694=kg (k694, T694) ;  
 K695=kg (k695, T695) ;  
 K696=kg (k696, T696) ;

% Column

id1=id3fs (1, 26, 297, 25, 1) ;  
 id2=id3fs (26, 51, 297, 25, 0) ;  
 id3=id3fs (51, 76, 297, 25, 0) ;  
 id4=id3fs (76, 101, 297, 25, 0) ;  
 id5=id3fs (101, 126, 297, 25, 0) ;  
 id6=id3fs (126, 151, 297, 25, 0) ;  
 id7=id3fs (151, 172, 297, 25, 0) ;  
 id8=id3fs (172, 193, 297, 25, 0) ;  
 id9=id3fs (193, 214, 297, 25, 0) ;  
 id10=id3fs (214, 235, 297, 25, 0) ;  
 id11=id3fs (235, 256, 297, 25, 0) ;  
 id12=id3fs (256, 282, 297, 25, 0) ;  
  
 id13=id3fs (2, 27, 297, 25, 1) ;

id14=id3fs(27,52,297,25,0);  
id15=id3fs(52,77,297,25,0);  
id16=id3fs(77,102,297,25,0);  
id17=id3fs(102,127,297,25,0);  
id18=id3fs(127,152,297,25,0);  
id19=id3fs(152,173,297,25,0);  
id20=id3fs(173,194,297,25,0);  
id21=id3fs(194,215,297,25,0);  
id22=id3fs(215,236,297,25,0);  
id23=id3fs(236,257,297,25,0);  
id24=id3fs(257,278,297,25,0);

id25=id3fs(3,28,297,25,1);  
id26=id3fs(28,53,297,25,0);  
id27=id3fs(53,78,297,25,0);  
id28=id3fs(78,103,297,25,0);  
id29=id3fs(103,128,297,25,0);  
id30=id3fs(128,153,297,25,0);  
id31=id3fs(153,174,297,25,0);  
id32=id3fs(174,195,297,25,0);  
id33=id3fs(195,216,297,25,0);  
id34=id3fs(216,237,297,25,0);  
id35=id3fs(237,258,297,25,0);  
id36=id3fs(258,279,297,25,0);

id37=id3fs(4,29,297,25,1);  
id38=id3fs(29,54,297,25,0);  
id39=id3fs(54,79,297,25,0);  
id40=id3fs(79,104,297,25,0);  
id41=id3fs(104,129,297,25,0);  
id42=id3fs(129,154,297,25,0);  
id43=id3fs(154,175,297,25,0);  
id44=id3fs(175,196,297,25,0);  
id45=id3fs(196,217,297,25,0);  
id46=id3fs(217,238,297,25,0);  
id47=id3fs(238,259,297,25,0);  
id48=id3fs(259,280,297,25,0);

id49=id3fs(5,30,297,25,1);  
id50=id3fs(30,55,297,25,0);  
id51=id3fs(55,80,297,25,0);  
id52=id3fs(80,105,297,25,0);  
id53=id3fs(105,130,297,25,0);  
id54=id3fs(130,155,297,25,0);  
id55=id3fs(155,176,297,25,0);  
id56=id3fs(176,197,297,25,0);  
id57=id3fs(197,218,297,25,0);  
id58=id3fs(218,239,297,25,0);  
id59=id3fs(239,260,297,25,0);  
id60=id3fs(260,281,297,25,0);

id61=id3fs(6,31,297,25,1);  
id62=id3fs(31,56,297,25,0);  
id63=id3fs(56,81,297,25,0);  
id64=id3fs(81,106,297,25,0);  
id65=id3fs(106,131,297,25,0);  
id66=id3fs(131,156,297,25,0);  
id67=id3fs(156,177,297,25,0);  
id68=id3fs(177,198,297,25,0);  
id69=id3fs(198,219,297,25,0);  
id70=id3fs(219,240,297,25,0);  
id71=id3fs(240,261,297,25,0);  
id72=id3fs(261,282,297,25,0);

id73=id3fs(7,32,297,25,1);  
id74=id3fs(32,57,297,25,0);  
id75=id3fs(57,82,297,25,0);  
id76=id3fs(82,107,297,25,0);  
id77=id3fs(107,132,297,25,0);  
id78=id3fs(132,157,297,25,0);  
id79=id3fs(157,178,297,25,0);

id80=id3fs(178,199,297,25,0);  
id81=id3fs(199,220,297,25,0);  
id82=id3fs(220,241,297,25,0);  
id83=id3fs(241,262,297,25,0);  
id84=id3fs(262,283,297,25,0);

id85=id3fs(8,33,297,25,1);  
id86=id3fs(33,58,297,25,0);  
id87=id3fs(58,83,297,25,0);  
id88=id3fs(83,108,297,25,0);  
id89=id3fs(108,133,297,25,0);  
id90=id3fs(133,158,297,25,0);  
id91=id3fs(158,179,297,25,0);  
id92=id3fs(179,200,297,25,0);  
id93=id3fs(200,221,297,25,0);  
id94=id3fs(221,242,297,25,0);  
id95=id3fs(242,263,297,25,0);  
id96=id3fs(263,284,297,25,0);

id97=id3fs(9,34,297,25,1);  
id98=id3fs(34,59,297,25,0);  
id99=id3fs(59,84,297,25,0);  
id100=id3fs(84,109,297,25,0);  
id101=id3fs(109,134,297,25,0);  
id102=id3fs(134,159,297,25,0);  
id103=id3fs(159,180,297,25,0);  
id104=id3fs(180,201,297,25,0);  
id105=id3fs(201,222,297,25,0);  
id106=id3fs(222,243,297,25,0);  
id107=id3fs(243,264,297,25,0);  
id108=id3fs(264,285,297,25,0);

id109=id3fs(10,35,297,25,1);  
id110=id3fs(35,60,297,25,0);  
id111=id3fs(60,85,297,25,0);  
id112=id3fs(85,110,297,25,0);  
id113=id3fs(110,135,297,25,0);  
id114=id3fs(135,160,297,25,0);  
id115=id3fs(160,181,297,25,0);  
id116=id3fs(181,202,297,25,0);  
id117=id3fs(202,223,297,25,0);  
id118=id3fs(223,244,297,25,0);  
id119=id3fs(244,265,297,25,0);  
id120=id3fs(265,286,297,25,0);

id121=id3fs(11,36,297,25,1);  
id122=id3fs(36,61,297,25,0);  
id123=id3fs(61,86,297,25,0);  
id124=id3fs(86,111,297,25,0);  
id125=id3fs(111,136,297,25,0);  
id126=id3fs(136,161,297,25,0);  
id127=id3fs(161,182,297,25,0);  
id128=id3fs(182,203,297,25,0);  
id129=id3fs(203,224,297,25,0);  
id130=id3fs(224,245,297,25,0);  
id131=id3fs(245,266,297,25,0);  
id132=id3fs(266,287,297,25,0);

id133=id3fs(12,37,297,25,1);  
id134=id3fs(37,62,297,25,0);  
id135=id3fs(62,87,297,25,0);  
id136=id3fs(87,112,297,25,0);  
id137=id3fs(112,137,297,25,0);  
id138=id3fs(137,162,297,25,0);  
id139=id3fs(162,183,297,25,0);  
id140=id3fs(183,204,297,25,0);  
id141=id3fs(204,225,297,25,0);  
id142=id3fs(225,246,297,25,0);  
id143=id3fs(246,267,297,25,0);  
id144=id3fs(267,288,297,25,0);

id145=id3fs(13,38,297,25,1);  
 id146=id3fs(38,63,297,25,0);  
 id147=id3fs(63,88,297,25,0);  
 id148=id3fs(88,113,297,25,0);  
 id149=id3fs(113,138,297,25,0);  
 id150=id3fs(138,163,297,25,0);  
 id151=id3fs(163,184,297,25,0);  
 id152=id3fs(184,205,297,25,0);  
 id153=id3fs(205,226,297,25,0);  
 id154=id3fs(226,247,297,25,0);  
 id155=id3fs(247,268,297,25,0);  
 id156=id3fs(268,289,297,25,0);  
  
 id157=id3fs(14,39,297,25,1);  
 id158=id3fs(39,64,297,25,0);  
 id159=id3fs(64,89,297,25,0);  
 id160=id3fs(89,114,297,25,0);  
 id161=id3fs(114,139,297,25,0);  
 id162=id3fs(139,164,297,25,0);  
 id163=id3fs(164,185,297,25,0);  
 id164=id3fs(185,206,297,25,0);  
 id165=id3fs(206,227,297,25,0);  
 id166=id3fs(227,248,297,25,0);  
 id167=id3fs(248,269,297,25,0);  
 id168=id3fs(269,290,297,25,0);  
  
 id169=id3fs(15,40,297,25,1);  
 id170=id3fs(40,65,297,25,0);  
 id171=id3fs(65,90,297,25,0);  
 id172=id3fs(90,115,297,25,0);  
 id173=id3fs(115,140,297,25,0);  
 id174=id3fs(140,165,297,25,0);  
 id175=id3fs(165,186,297,25,0);  
 id176=id3fs(186,207,297,25,0);  
 id177=id3fs(207,228,297,25,0);  
 id178=id3fs(228,249,297,25,0);  
 id179=id3fs(249,270,297,25,0);  
 id180=id3fs(270,291,297,25,0);  
  
 id181=id3fs(16,41,297,25,1);  
 id182=id3fs(41,66,297,25,0);  
 id183=id3fs(66,91,297,25,0);  
 id184=id3fs(91,116,297,25,0);  
 id185=id3fs(116,141,297,25,0);  
 id186=id3fs(141,166,297,25,0);  
 id187=id3fs(166,187,297,25,0);  
 id188=id3fs(187,208,297,25,0);  
 id189=id3fs(208,229,297,25,0);  
 id190=id3fs(229,250,297,25,0);  
 id191=id3fs(250,271,297,25,0);  
 id192=id3fs(271,292,297,25,0);  
  
 id193=id3fs(17,42,297,25,1);  
 id194=id3fs(42,67,297,25,0);  
 id195=id3fs(67,92,297,25,0);  
 id196=id3fs(92,117,297,25,0);  
 id197=id3fs(117,142,297,25,0);  
 id198=id3fs(142,167,297,25,0);  
 id199=id3fs(167,188,297,25,0);  
 id200=id3fs(188,209,297,25,0);  
 id201=id3fs(209,230,297,25,0);  
 id202=id3fs(230,251,297,25,0);  
 id203=id3fs(251,272,297,25,0);  
 id204=id3fs(272,293,297,25,0);  
  
 id205=id3fs(18,43,297,25,1);  
 id206=id3fs(43,68,297,25,0);  
 id207=id3fs(68,93,297,25,0);  
 id208=id3fs(93,118,297,25,0);  
 id209=id3fs(118,143,297,25,0);  
 id210=id3fs(143,168,297,25,0);  
  
 id211=id3fs(168,189,297,25,0);  
 id212=id3fs(189,210,297,25,0);  
 id213=id3fs(210,231,297,25,0);  
 id214=id3fs(231,252,297,25,0);  
 id215=id3fs(252,273,297,25,0);  
 id216=id3fs(273,294,297,25,0);  
  
 id217=id3fs(19,44,297,25,1);  
 id218=id3fs(44,69,297,25,0);  
 id219=id3fs(69,94,297,25,0);  
 id220=id3fs(94,119,297,25,0);  
 id221=id3fs(119,144,297,25,0);  
  
 id222=id3fs(20,45,297,25,1);  
 id223=id3fs(45,70,297,25,0);  
 id224=id3fs(70,95,297,25,0);  
 id225=id3fs(95,120,297,25,0);  
 id226=id3fs(120,145,297,25,0);  
  
 id227=id3fs(21,46,297,25,1);  
 id228=id3fs(46,71,297,25,0);  
 id229=id3fs(71,96,297,25,0);  
 id230=id3fs(96,121,297,25,0);  
 id231=id3fs(121,146,297,25,0);  
 id232=id3fs(146,169,297,25,0);  
 id233=id3fs(169,190,297,25,0);  
 id234=id3fs(190,211,297,25,0);  
 id235=id3fs(211,232,297,25,0);  
 id236=id3fs(232,245,297,25,0);  
 id237=id3fs(245,266,297,25,0);  
 id238=id3fs(266,287,297,25,0);  
  
 id239=id3fs(22,47,297,25,1);  
 id240=id3fs(47,72,297,25,0);  
 id241=id3fs(72,97,297,25,0);  
 id242=id3fs(97,122,297,25,0);  
 id243=id3fs(122,147,297,25,0);  
 id244=id3fs(147,170,297,25,0);  
 id245=id3fs(170,191,297,25,0);  
 id246=id3fs(191,212,297,25,0);  
 id247=id3fs(212,233,297,25,0);  
 id248=id3fs(233,246,297,25,0);  
 id249=id3fs(246,267,297,25,0);  
 id250=id3fs(267,288,297,25,0);  
  
 id251=id3fs(23,48,297,25,1);  
 id252=id3fs(48,73,297,25,0);  
 id253=id3fs(73,98,297,25,0);  
 id254=id3fs(98,123,297,25,0);  
 id255=id3fs(123,148,297,25,0);  
 id256=id3fs(148,171,297,25,0);  
 id257=id3fs(171,192,297,25,0);  
 id258=id3fs(192,213,297,25,0);  
 id259=id3fs(213,234,297,25,0);  
 id260=id3fs(234,247,297,25,0);  
 id261=id3fs(247,268,297,25,0);  
 id262=id3fs(268,289,297,25,0);  
  
 id263=id3fs(24,49,297,25,1);  
 id264=id3fs(49,74,297,25,0);  
 id265=id3fs(74,99,297,25,0);  
 id266=id3fs(99,124,297,25,0);  
 id267=id3fs(124,149,297,25,0);  
  
 id268=id3fs(25,50,297,25,1);  
 id269=id3fs(50,75,297,25,0);  
 id270=id3fs(75,100,297,25,0);  
 id271=id3fs(100,125,297,25,0);  
 id272=id3fs(125,150,297,25,0);  
  
 \* Beam



```

% Arah x
id273=id3fs(26,27,297,25,0);% lantai
1
id274=id3fs(27,28,297,25,0);
id275=id3fs(28,29,297,25,0);
id276=id3fs(29,30,297,25,0);
id277=id3fs(31,32,297,25,0);
id278=id3fs(32,33,297,25,0);
id279=id3fs(33,34,297,25,0);
id280=id3fs(34,35,297,25,0);
id281=id3fs(36,37,297,25,0);
id282=id3fs(37,38,297,25,0);
id283=id3fs(38,39,297,25,0);
id284=id3fs(39,40,297,25,0);
id285=id3fs(41,42,297,25,0);
id286=id3fs(42,43,297,25,0);
id287=id3fs(43,44,297,25,0);
id288=id3fs(44,45,297,25,0);
id289=id3fs(46,47,297,25,0);
id290=id3fs(47,48,297,25,0);
id291=id3fs(48,49,297,25,0);
id292=id3fs(49,50,297,25,0);

id293=id3fs(51,52,297,25,0);% lantai
2
id294=id3fs(52,53,297,25,0);
id295=id3fs(53,54,297,25,0);
id296=id3fs(54,55,297,25,0);
id297=id3fs(56,57,297,25,0);
id298=id3fs(57,58,297,25,0);
id299=id3fs(31,32,297,25,0);
id300=id3fs(32,33,297,25,0);
id301=id3fs(33,34,297,25,0);
id302=id3fs(62,63,297,25,0);
id303=id3fs(63,64,297,25,0);
id304=id3fs(64,65,297,25,0);
id305=id3fs(66,67,297,25,0);
id306=id3fs(67,68,297,25,0);
id307=id3fs(68,69,297,25,0);
id308=id3fs(69,70,297,25,0);
id309=id3fs(71,72,297,25,0);
id310=id3fs(72,73,297,25,0);
id311=id3fs(73,74,297,25,0);
id312=id3fs(74,75,297,25,0);

id313=id3fs(76,77,297,25,0);% lantai
3
id314=id3fs(77,78,297,25,0);
id315=id3fs(78,79,297,25,0);
id316=id3fs(79,80,297,25,0);
id317=id3fs(81,82,297,25,0);
id318=id3fs(82,83,297,25,0);
id319=id3fs(83,84,297,25,0);
id320=id3fs(84,85,297,25,0);
id321=id3fs(86,87,297,25,0);
id322=id3fs(87,88,297,25,0);
id323=id3fs(88,89,297,25,0);
id324=id3fs(89,90,297,25,0);
id325=id3fs(91,92,297,25,0);
id326=id3fs(92,93,297,25,0);
id327=id3fs(93,94,297,25,0);
id328=id3fs(94,95,297,25,0);
id329=id3fs(96,97,297,25,0);
id330=id3fs(97,98,297,25,0);
id331=id3fs(98,99,297,25,0);
id332=id3fs(99,100,297,25,0);

id333=id3fs(101,102,297,25,0);%
lantai 4
id334=id3fs(102,103,297,25,0);
id335=id3fs(103,104,297,25,0);

id336=id3fs(104,105,297,25,0);
id337=id3fs(106,107,297,25,0);
id338=id3fs(107,108,297,25,0);
id339=id3fs(108,109,297,25,0);
id340=id3fs(109,110,297,25,0);
id341=id3fs(111,112,297,25,0);
id342=id3fs(112,113,297,25,0);
id343=id3fs(113,114,297,25,0);
id344=id3fs(114,115,297,25,0);
id345=id3fs(116,117,297,25,0);
id346=id3fs(117,118,297,25,0);
id347=id3fs(118,119,297,25,0);
id348=id3fs(119,120,297,25,0);
id349=id3fs(121,122,297,25,0);
id350=id3fs(122,123,297,25,0);
id351=id3fs(123,124,297,25,0);
id352=id3fs(124,125,297,25,0);

id353=id3fs(126,127,297,25,0);%
lantai 5
id354=id3fs(127,128,297,25,0);
id355=id3fs(128,129,297,25,0);
id356=id3fs(129,130,297,25,0);
id357=id3fs(131,132,297,25,0);
id358=id3fs(132,133,297,25,0);
id359=id3fs(133,134,297,25,0);
id360=id3fs(134,135,297,25,0);
id361=id3fs(136,137,297,25,0);
id362=id3fs(137,138,297,25,0);
id363=id3fs(138,139,297,25,0);
id364=id3fs(139,140,297,25,0);
id365=id3fs(141,142,297,25,0);
id366=id3fs(142,143,297,25,0);
id367=id3fs(143,144,297,25,0);
id368=id3fs(144,145,297,25,0);
id369=id3fs(146,147,297,25,0);
id370=id3fs(147,148,297,25,0);
id371=id3fs(148,149,297,25,0);
id372=id3fs(149,150,297,25,0);

id373=id3fs(151,152,297,25,0);%
lantai 6
id374=id3fs(152,153,297,25,0);
id375=id3fs(153,154,297,25,0);
id376=id3fs(154,155,297,25,0);
id377=id3fs(156,157,297,25,0);
id378=id3fs(157,158,297,25,0);
id379=id3fs(158,159,297,25,0);
id380=id3fs(159,160,297,25,0);
id381=id3fs(161,162,297,25,0);
id382=id3fs(162,163,297,25,0);
id383=id3fs(163,164,297,25,0);
id384=id3fs(164,165,297,25,0);
id385=id3fs(166,167,297,25,0);
id386=id3fs(167,168,297,25,0);
id387=id3fs(169,170,297,25,0);
id388=id3fs(170,171,297,25,0);

id389=id3fs(172,173,297,25,0);%
lantai 7
id390=id3fs(173,174,297,25,0);
id391=id3fs(174,175,297,25,0);
id392=id3fs(175,176,297,25,0);
id393=id3fs(177,178,297,25,0);
id394=id3fs(178,179,297,25,0);
id395=id3fs(179,180,297,25,0);
id396=id3fs(180,181,297,25,0);
id397=id3fs(182,183,297,25,0);
id398=id3fs(183,184,297,25,0);
id399=id3fs(184,185,297,25,0);
id400=id3fs(185,186,297,25,0);

```

```

id401=id3fs (187, 188, 297, 25, 0);
id402=id3fs (188, 189, 297, 25, 0);
id403=id3fs (190, 191, 297, 25, 0);
id404=id3fs (191, 192, 297, 25, 0);

id405=id3fs (193, 194, 297, 25, 0);%
lantai 8
id406=id3fs (194, 195, 297, 25, 0);
id407=id3fs (195, 196, 297, 25, 0);
id408=id3fs (196, 197, 297, 25, 0);
id409=id3fs (198, 199, 297, 25, 0);
id410=id3fs (199, 200, 297, 25, 0);
id411=id3fs (200, 201, 297, 25, 0);
id412=id3fs (201, 202, 297, 25, 0);
id413=id3fs (203, 204, 297, 25, 0);
id414=id3fs (204, 205, 297, 25, 0);
id415=id3fs (205, 206, 297, 25, 0);
id416=id3fs (206, 207, 297, 25, 0);
id417=id3fs (208, 209, 297, 25, 0);
id418=id3fs (209, 210, 297, 25, 0);
id419=id3fs (211, 212, 297, 25, 0);
id420=id3fs (212, 213, 297, 25, 0);

id421=id3fs (214, 215, 297, 25, 0);%
lantai 9
id422=id3fs (215, 216, 297, 25, 0);
id423=id3fs (216, 217, 297, 25, 0);
id424=id3fs (217, 218, 297, 25, 0);
id425=id3fs (219, 220, 297, 25, 0);
id426=id3fs (220, 221, 297, 25, 0);
id427=id3fs (221, 222, 297, 25, 0);
id428=id3fs (222, 223, 297, 25, 0);
id429=id3fs (224, 225, 297, 25, 0);
id430=id3fs (225, 226, 297, 25, 0);
id431=id3fs (226, 227, 297, 25, 0);
id432=id3fs (227, 228, 297, 25, 0);
id433=id3fs (229, 230, 297, 25, 0);
id434=id3fs (230, 231, 297, 25, 0);
id435=id3fs (232, 233, 297, 25, 0);
id436=id3fs (233, 234, 297, 25, 0);

id437=id3fs (235, 236, 297, 25, 0);%
lantai 10
id438=id3fs (236, 237, 297, 25, 0);
id439=id3fs (237, 238, 297, 25, 0);
id440=id3fs (238, 239, 297, 25, 0);
id441=id3fs (240, 241, 297, 25, 0);
id442=id3fs (241, 242, 297, 25, 0);
id443=id3fs (242, 243, 297, 25, 0);
id444=id3fs (243, 244, 297, 25, 0);
id445=id3fs (245, 246, 297, 25, 0);
id446=id3fs (246, 247, 297, 25, 0);
id447=id3fs (247, 248, 297, 25, 0);
id448=id3fs (248, 249, 297, 25, 0);
id449=id3fs (250, 251, 297, 25, 0);
id450=id3fs (251, 252, 297, 25, 0);
id451=id3fs (253, 254, 297, 25, 0);
id452=id3fs (254, 255, 297, 25, 0);

id453=id3fs (256, 257, 297, 25, 0);%
lantai 11
id454=id3fs (257, 258, 297, 25, 0);
id455=id3fs (258, 259, 297, 25, 0);
id456=id3fs (259, 260, 297, 25, 0);
id457=id3fs (261, 262, 297, 25, 0);
id458=id3fs (262, 263, 297, 25, 0);
id459=id3fs (263, 264, 297, 25, 0);
id460=id3fs (264, 265, 297, 25, 0);
id461=id3fs (266, 267, 297, 25, 0);
id462=id3fs (267, 268, 297, 25, 0);
id463=id3fs (268, 269, 297, 25, 0);

id464=id3fs (269, 270, 297, 25, 0);
id465=id3fs (271, 272, 297, 25, 0);
id466=id3fs (272, 273, 297, 25, 0);
id467=id3fs (274, 275, 297, 25, 0);
id468=id3fs (275, 276, 297, 25, 0);

id469=id3fs (277, 278, 297, 25, 0);%
lantai 12
id470=id3fs (278, 279, 297, 25, 0);
id471=id3fs (279, 280, 297, 25, 0);
id472=id3fs (280, 281, 297, 25, 0);
id473=id3fs (282, 283, 297, 25, 0);
id474=id3fs (283, 284, 297, 25, 0);
id475=id3fs (284, 285, 297, 25, 0);
id476=id3fs (285, 286, 297, 25, 0);
id477=id3fs (287, 288, 297, 25, 0);
id478=id3fs (288, 289, 297, 25, 0);
id479=id3fs (289, 290, 297, 25, 0);
id480=id3fs (290, 291, 297, 25, 0);
id481=id3fs (292, 293, 297, 25, 0);
id482=id3fs (293, 294, 297, 25, 0);
id483=id3fs (295, 296, 297, 25, 0);
id484=id3fs (296, 297, 297, 25, 0);

%Arah z
id485=id3fs (26, 31, 297, 25, 0);% lantai
1
id486=id3fs (31, 36, 297, 25, 0);
id487=id3fs (36, 41, 297, 25, 0);
id488=id3fs (41, 46, 297, 25, 0);
id489=id3fs (27, 32, 297, 25, 0);
id490=id3fs (32, 37, 297, 25, 0);
id491=id3fs (37, 42, 297, 25, 0);
id492=id3fs (42, 47, 297, 25, 0);
id493=id3fs (28, 33, 297, 25, 0);
id494=id3fs (33, 38, 297, 25, 0);
id495=id3fs (38, 43, 297, 25, 0);
id496=id3fs (43, 48, 297, 25, 0);
id497=id3fs (29, 34, 297, 25, 0);
id498=id3fs (34, 39, 297, 25, 0);
id499=id3fs (39, 44, 297, 25, 0);
id500=id3fs (44, 49, 297, 25, 0);
id501=id3fs (30, 35, 297, 25, 0);
id502=id3fs (35, 40, 297, 25, 0);
id503=id3fs (40, 45, 297, 25, 0);
id504=id3fs (45, 50, 297, 25, 0);

id505=id3fs (51, 56, 297, 25, 0);% lantai
2
id506=id3fs (56, 61, 297, 25, 0);
id507=id3fs (61, 66, 297, 25, 0);
id508=id3fs (66, 71, 297, 25, 0);
id509=id3fs (52, 57, 297, 25, 0);
id510=id3fs (57, 62, 297, 25, 0);
id511=id3fs (62, 67, 297, 25, 0);
id512=id3fs (67, 72, 297, 25, 0);
id513=id3fs (53, 58, 297, 25, 0);
id514=id3fs (58, 63, 297, 25, 0);
id515=id3fs (63, 68, 297, 25, 0);
id516=id3fs (68, 73, 297, 25, 0);
id517=id3fs (54, 59, 297, 25, 0);
id518=id3fs (59, 64, 297, 25, 0);
id519=id3fs (64, 69, 297, 25, 0);
id520=id3fs (69, 74, 297, 25, 0);
id521=id3fs (55, 60, 297, 25, 0);
id522=id3fs (60, 65, 297, 25, 0);
id523=id3fs (65, 70, 297, 25, 0);
id524=id3fs (70, 75, 297, 25, 0);

id525=id3fs (76, 81, 297, 25, 0);% lantai
3

```

id526=id3fs(81,86,297,25,0);  
id527=id3fs(86,91,297,25,0);  
id528=id3fs(91,96,297,25,0);  
id529=id3fs(77,82,297,25,0);  
id530=id3fs(82,87,297,25,0);  
id531=id3fs(87,92,297,25,0);  
id532=id3fs(92,97,297,25,0);  
id533=id3fs(78,83,297,25,0);  
id534=id3fs(83,88,297,25,0);  
id535=id3fs(88,93,297,25,0);  
id536=id3fs(93,98,297,25,0);  
id537=id3fs(79,84,297,25,0);  
id538=id3fs(84,89,297,25,0);  
id539=id3fs(89,94,297,25,0);  
id540=id3fs(94,99,297,25,0);  
id541=id3fs(80,85,297,25,0);  
id542=id3fs(85,90,297,25,0);  
id543=id3fs(90,95,297,25,0);  
id544=id3fs(95,100,297,25,0);  
  
id545=id3fs(101,106,297,25,0);%  
lantai 4  
id546=id3fs(106,111,297,25,0);  
id547=id3fs(111,116,297,25,0);  
id548=id3fs(116,121,297,25,0);  
id549=id3fs(102,107,297,25,0);  
id550=id3fs(107,112,297,25,0);  
id551=id3fs(112,117,297,25,0);  
id552=id3fs(117,122,297,25,0);  
id553=id3fs(103,108,297,25,0);  
id554=id3fs(108,113,297,25,0);  
id555=id3fs(113,118,297,25,0);  
id556=id3fs(118,123,297,25,0);  
id557=id3fs(104,109,297,25,0);  
id558=id3fs(109,114,297,25,0);  
id559=id3fs(114,119,297,25,0);  
id560=id3fs(119,124,297,25,0);  
id561=id3fs(105,110,297,25,0);  
id562=id3fs(110,115,297,25,0);  
id563=id3fs(115,120,297,25,0);  
id564=id3fs(120,125,297,25,0);  
  
id565=id3fs(126,131,297,25,0);%  
lantai 5  
id566=id3fs(131,136,297,25,0);  
id567=id3fs(136,141,297,25,0);  
id568=id3fs(141,146,297,25,0);  
id569=id3fs(127,132,297,25,0);  
id570=id3fs(132,137,297,25,0);  
id571=id3fs(137,142,297,25,0);  
id572=id3fs(142,147,297,25,0);  
id573=id3fs(128,133,297,25,0);  
id574=id3fs(133,138,297,25,0);  
id575=id3fs(138,143,297,25,0);  
id576=id3fs(143,148,297,25,0);  
id577=id3fs(129,134,297,25,0);  
id578=id3fs(134,139,297,25,0);  
id579=id3fs(139,144,297,25,0);  
id580=id3fs(144,149,297,25,0);  
id581=id3fs(130,135,297,25,0);  
id582=id3fs(135,140,297,25,0);  
id583=id3fs(140,145,297,25,0);  
id584=id3fs(145,150,297,25,0);  
  
id585=id3fs(151,156,297,25,0);%  
lantai 6  
id586=id3fs(156,161,297,25,0);  
id587=id3fs(161,166,297,25,0);  
id588=id3fs(166,169,297,25,0);  
id589=id3fs(152,157,297,25,0);  
id590=id3fs(157,162,297,25,0);  
  
id591=id3fs(162,167,297,25,0);  
id592=id3fs(167,170,297,25,0);  
id593=id3fs(153,158,297,25,0);  
id594=id3fs(158,163,297,25,0);  
id595=id3fs(163,168,297,25,0);  
id596=id3fs(168,171,297,25,0);  
id597=id3fs(154,159,297,25,0);  
id598=id3fs(159,164,297,25,0);  
id599=id3fs(155,160,297,25,0);  
id600=id3fs(160,165,297,25,0);  
  
id601=id3fs(172,177,297,25,0);%  
lantai 7  
id602=id3fs(177,182,297,25,0);  
id603=id3fs(182,187,297,25,0);  
id604=id3fs(187,190,297,25,0);  
id605=id3fs(173,178,297,25,0);  
id606=id3fs(178,183,297,25,0);  
id607=id3fs(183,188,297,25,0);  
id608=id3fs(188,191,297,25,0);  
id609=id3fs(174,179,297,25,0);  
id610=id3fs(179,184,297,25,0);  
id611=id3fs(184,189,297,25,0);  
id612=id3fs(189,192,297,25,0);  
id613=id3fs(175,180,297,25,0);  
id614=id3fs(180,185,297,25,0);  
id615=id3fs(176,181,297,25,0);  
id616=id3fs(181,186,297,25,0);  
  
id617=id3fs(193,198,297,25,0);%  
lantai 8  
id618=id3fs(198,203,297,25,0);  
id619=id3fs(203,208,297,25,0);  
id620=id3fs(208,211,297,25,0);  
id621=id3fs(194,198,297,25,0);  
id622=id3fs(198,204,297,25,0);  
id623=id3fs(204,209,297,25,0);  
id624=id3fs(209,212,297,25,0);  
id625=id3fs(195,200,297,25,0);  
id626=id3fs(200,205,297,25,0);  
id627=id3fs(205,210,297,25,0);  
id628=id3fs(210,213,297,25,0);  
id629=id3fs(196,201,297,25,0);  
id630=id3fs(201,206,297,25,0);  
id631=id3fs(197,202,297,25,0);  
id632=id3fs(202,207,297,25,0);  
  
id633=id3fs(214,219,297,25,0);%  
lantai 9  
id634=id3fs(219,224,297,25,0);  
id635=id3fs(224,229,297,25,0);  
id636=id3fs(229,231,297,25,0);  
id637=id3fs(215,220,297,25,0);  
id638=id3fs(220,225,297,25,0);  
id639=id3fs(225,230,297,25,0);  
id640=id3fs(230,233,297,25,0);  
id641=id3fs(216,221,297,25,0);  
id642=id3fs(221,226,297,25,0);  
id643=id3fs(226,231,297,25,0);  
id644=id3fs(231,234,297,25,0);  
id645=id3fs(217,222,297,25,0);  
id646=id3fs(222,227,297,25,0);  
id647=id3fs(218,223,297,25,0);  
id648=id3fs(223,228,297,25,0);  
  
id649=id3fs(235,240,297,25,0);%  
lantai 10  
id650=id3fs(240,245,297,25,0);  
id651=id3fs(245,250,297,25,0);  
id652=id3fs(250,253,297,25,0);  
id653=id3fs(236,241,297,25,0);

```

id654=id3fs (241,246,297,25,0);
id655=id3fs (246,251,297,25,0);
id656=id3fs (251,254,297,25,0);
id657=id3fs (237,242,297,25,0);
id658=id3fs (242,247,297,25,0);
id659=id3fs (247,252,297,25,0);
id660=id3fs (252,255,297,25,0);
id661=id3fs (238,243,297,25,0);
id662=id3fs (243,248,297,25,0);
id663=id3fs (239,244,297,25,0);
id664=id3fs (244,249,297,25,0);

id665=id3fs (256,261,297,25,0);%
lantai 11
id666=id3fs (261,266,297,25,0);
id667=id3fs (266,271,297,25,0);
id668=id3fs (271,274,297,25,0);
id669=id3fs (257,262,297,25,0);
id670=id3fs (262,267,297,25,0);
id671=id3fs (267,272,297,25,0);
id672=id3fs (272,275,297,25,0);
id673=id3fs (258,263,297,25,0);
id674=id3fs (263,268,297,25,0);
id675=id3fs (268,273,297,25,0);
id676=id3fs (273,276,297,25,0);
id677=id3fs (259,264,297,25,0);
id678=id3fs (264,269,297,25,0);
id679=id3fs (260,265,297,25,0);
id680=id3fs (265,270,297,25,0);

id681=id3fs (277,282,297,25,0);%
lantai 12
id682=id3fs (282,287,297,25,0);
id683=id3fs (287,292,297,25,0);
id684=id3fs (292,295,297,25,0);
id685=id3fs (278,283,297,25,0);
id686=id3fs (283,288,297,25,0);
id687=id3fs (288,293,297,25,0);
id688=id3fs (293,296,297,25,0);
id689=id3fs (279,284,297,25,0);
id690=id3fs (284,289,297,25,0);
id691=id3fs (289,294,297,25,0);
id692=id3fs (294,297,297,25,0);
id693=id3fs (280,285,297,25,0);
id694=id3fs (285,290,297,25,0);
id695=id3fs (281,286,297,25,0);
id696=id3fs (286,291,297,25,0);

tdf=1632;
Ks=ass3f (K1, id1, tdf);
Ks=Ks+ass3f (K2, id2, tdf);
Ks=Ks+ass3f (K3, id3, tdf);
Ks=Ks+ass3f (K4, id4, tdf);
Ks=Ks+ass3f (K5, id5, tdf);
Ks=Ks+ass3f (K6, id6, tdf);
Ks=Ks+ass3f (K7, id7, tdf);
Ks=Ks+ass3f (K8, id8, tdf);
Ks=Ks+ass3f (K9, id9, tdf);
Ks=Ks+ass3f (K10, id10, tdf);
Ks=Ks+ass3f (K11, id11, tdf);
Ks=Ks+ass3f (K12, id12, tdf);
Ks=Ks+ass3f (K13, id13, tdf);
Ks=Ks+ass3f (K14, id14, tdf);
Ks=Ks+ass3f (K15, id15, tdf);
Ks=Ks+ass3f (K16, id16, tdf);
Ks=Ks+ass3f (K17, id17, tdf);
Ks=Ks+ass3f (K18, id18, tdf);
Ks=Ks+ass3f (K19, id19, tdf);
Ks=Ks+ass3f (K20, id20, tdf);
Ks=Ks+ass3f (K21, id21, tdf);
Ks=Ks+ass3f (K22, id22, tdf);

Ks=Ks+ass3f (K23, id23, tdf);
Ks=Ks+ass3f (K24, id24, tdf);
Ks=Ks+ass3f (K25, id25, tdf);
Ks=Ks+ass3f (K26, id26, tdf);
Ks=Ks+ass3f (K27, id27, tdf);
Ks=Ks+ass3f (K28, id28, tdf);
Ks=Ks+ass3f (K29, id29, tdf);
Ks=Ks+ass3f (K30, id30, tdf);
Ks=Ks+ass3f (K31, id31, tdf);
Ks=Ks+ass3f (K32, id32, tdf);
Ks=Ks+ass3f (K33, id33, tdf);
Ks=Ks+ass3f (K34, id34, tdf);
Ks=Ks+ass3f (K35, id35, tdf);
Ks=Ks+ass3f (K36, id36, tdf);
Ks=Ks+ass3f (K37, id37, tdf);
Ks=Ks+ass3f (K38, id38, tdf);
Ks=Ks+ass3f (K39, id39, tdf);
Ks=Ks+ass3f (K40, id40, tdf);
Ks=Ks+ass3f (K41, id41, tdf);
Ks=Ks+ass3f (K42, id42, tdf);
Ks=Ks+ass3f (K43, id43, tdf);
Ks=Ks+ass3f (K44, id44, tdf);
Ks=Ks+ass3f (K45, id45, tdf);
Ks=Ks+ass3f (K46, id46, tdf);
Ks=Ks+ass3f (K47, id47, tdf);
Ks=Ks+ass3f (K48, id48, tdf);
Ks=Ks+ass3f (K49, id49, tdf);
Ks=Ks+ass3f (K50, id50, tdf);
Ks=Ks+ass3f (K51, id51, tdf);
Ks=Ks+ass3f (K52, id52, tdf);
Ks=Ks+ass3f (K53, id53, tdf);
Ks=Ks+ass3f (K54, id54, tdf);
Ks=Ks+ass3f (K55, id55, tdf);
Ks=Ks+ass3f (K56, id56, tdf);
Ks=Ks+ass3f (K57, id57, tdf);
Ks=Ks+ass3f (K58, id58, tdf);
Ks=Ks+ass3f (K59, id59, tdf);
Ks=Ks+ass3f (K60, id60, tdf);
Ks=Ks+ass3f (K61, id61, tdf);
Ks=Ks+ass3f (K62, id62, tdf);
Ks=Ks+ass3f (K63, id63, tdf);
Ks=Ks+ass3f (K64, id64, tdf);
Ks=Ks+ass3f (K65, id65, tdf);
Ks=Ks+ass3f (K66, id66, tdf);
Ks=Ks+ass3f (K67, id67, tdf);
Ks=Ks+ass3f (K68, id68, tdf);
Ks=Ks+ass3f (K69, id69, tdf);
Ks=Ks+ass3f (K70, id70, tdf);
Ks=Ks+ass3f (K71, id71, tdf);
Ks=Ks+ass3f (K72, id72, tdf);
Ks=Ks+ass3f (K73, id73, tdf);
Ks=Ks+ass3f (K74, id74, tdf);
Ks=Ks+ass3f (K75, id75, tdf);
Ks=Ks+ass3f (K76, id76, tdf);
Ks=Ks+ass3f (K77, id77, tdf);
Ks=Ks+ass3f (K78, id78, tdf);
Ks=Ks+ass3f (K79, id79, tdf);
Ks=Ks+ass3f (K80, id80, tdf);
Ks=Ks+ass3f (K81, id81, tdf);
Ks=Ks+ass3f (K82, id82, tdf);
Ks=Ks+ass3f (K83, id83, tdf);
Ks=Ks+ass3f (K84, id84, tdf);
Ks=Ks+ass3f (K85, id85, tdf);
Ks=Ks+ass3f (K86, id86, tdf);
Ks=Ks+ass3f (K87, id87, tdf);
Ks=Ks+ass3f (K88, id88, tdf);
Ks=Ks+ass3f (K89, id89, tdf);
Ks=Ks+ass3f (K90, id90, tdf);
Ks=Ks+ass3f (K91, id91, tdf);
Ks=Ks+ass3f (K92, id92, tdf);
Ks=Ks+ass3f (K93, id93, tdf);

```



Ks=Ks+ass3f(K236,id236,tdf);  
 Ks=Ks+ass3f(K237,id237,tdf);  
 Ks=Ks+ass3f(K238,id238,tdf);  
 Ks=Ks+ass3f(K239,id239,tdf);  
 Ks=Ks+ass3f(K240,id240,tdf);  
 Ks=Ks+ass3f(K241,id241,tdf);  
 Ks=Ks+ass3f(K242,id242,tdf);  
 Ks=Ks+ass3f(K243,id243,tdf);  
 Ks=Ks+ass3f(K244,id244,tdf);  
 Ks=Ks+ass3f(K245,id245,tdf);  
 Ks=Ks+ass3f(K246,id246,tdf);  
 Ks=Ks+ass3f(K247,id247,tdf);  
 Ks=Ks+ass3f(K248,id248,tdf);  
 Ks=Ks+ass3f(K249,id249,tdf);  
 Ks=Ks+ass3f(K250,id250,tdf);  
 Ks=Ks+ass3f(K251,id251,tdf);  
 Ks=Ks+ass3f(K252,id252,tdf);  
 Ks=Ks+ass3f(K253,id253,tdf);  
 Ks=Ks+ass3f(K254,id254,tdf);  
 Ks=Ks+ass3f(K255,id255,tdf);  
 Ks=Ks+ass3f(K256,id256,tdf);  
 Ks=Ks+ass3f(K257,id257,tdf);  
 Ks=Ks+ass3f(K258,id258,tdf);  
 Ks=Ks+ass3f(K259,id259,tdf);  
 Ks=Ks+ass3f(K260,id260,tdf);  
 Ks=Ks+ass3f(K261,id261,tdf);  
 Ks=Ks+ass3f(K262,id262,tdf);  
 Ks=Ks+ass3f(K263,id263,tdf);  
 Ks=Ks+ass3f(K264,id264,tdf);  
 Ks=Ks+ass3f(K265,id265,tdf);  
 Ks=Ks+ass3f(K266,id266,tdf);  
 Ks=Ks+ass3f(K267,id267,tdf);  
 Ks=Ks+ass3f(K268,id268,tdf);  
 Ks=Ks+ass3f(K269,id269,tdf);  
 Ks=Ks+ass3f(K270,id270,tdf);  
 Ks=Ks+ass3f(K271,id271,tdf);  
 Ks=Ks+ass3f(K272,id272,tdf);

%Beam

Ks=Ks+ass3f(K273,id273,tdf);  
 Ks=Ks+ass3f(K274,id274,tdf);  
 Ks=Ks+ass3f(K275,id275,tdf);  
 Ks=Ks+ass3f(K276,id276,tdf);  
 Ks=Ks+ass3f(K277,id277,tdf);  
 Ks=Ks+ass3f(K278,id278,tdf);  
 Ks=Ks+ass3f(K279,id279,tdf);  
 Ks=Ks+ass3f(K280,id280,tdf);  
 Ks=Ks+ass3f(K281,id281,tdf);  
 Ks=Ks+ass3f(K282,id282,tdf);  
 Ks=Ks+ass3f(K283,id283,tdf);  
 Ks=Ks+ass3f(K284,id284,tdf);  
 Ks=Ks+ass3f(K285,id285,tdf);  
 Ks=Ks+ass3f(K286,id286,tdf);  
 Ks=Ks+ass3f(K287,id287,tdf);  
 Ks=Ks+ass3f(K288,id288,tdf);  
 Ks=Ks+ass3f(K289,id289,tdf);  
 Ks=Ks+ass3f(K290,id290,tdf);  
 Ks=Ks+ass3f(K291,id291,tdf);  
 Ks=Ks+ass3f(K292,id292,tdf);  
 Ks=Ks+ass3f(K293,id293,tdf);  
 Ks=Ks+ass3f(K294,id294,tdf);  
 Ks=Ks+ass3f(K295,id295,tdf);  
 Ks=Ks+ass3f(K296,id296,tdf);  
 Ks=Ks+ass3f(K297,id297,tdf);  
 Ks=Ks+ass3f(K298,id298,tdf);  
 Ks=Ks+ass3f(K299,id299,tdf);  
 Ks=Ks+ass3f(K300,id300,tdf);  
 Ks=Ks+ass3f(K301,id301,tdf);  
 Ks=Ks+ass3f(K302,id302,tdf);  
 Ks=Ks+ass3f(K303,id303,tdf);  
 Ks=Ks+ass3f(K304,id304,tdf);

Ks=Ks+ass3f(K305,id305,tdf);  
 Ks=Ks+ass3f(K306,id306,tdf);  
 Ks=Ks+ass3f(K307,id307,tdf);  
 Ks=Ks+ass3f(K308,id308,tdf);  
 Ks=Ks+ass3f(K309,id309,tdf);  
 Ks=Ks+ass3f(K310,id310,tdf);  
 Ks=Ks+ass3f(K311,id311,tdf);  
 Ks=Ks+ass3f(K312,id312,tdf);  
 Ks=Ks+ass3f(K313,id313,tdf);  
 Ks=Ks+ass3f(K314,id314,tdf);  
 Ks=Ks+ass3f(K315,id315,tdf);  
 Ks=Ks+ass3f(K316,id316,tdf);  
 Ks=Ks+ass3f(K317,id317,tdf);  
 Ks=Ks+ass3f(K318,id318,tdf);  
 Ks=Ks+ass3f(K319,id319,tdf);  
 Ks=Ks+ass3f(K320,id320,tdf);  
 Ks=Ks+ass3f(K321,id321,tdf);  
 Ks=Ks+ass3f(K322,id322,tdf);  
 Ks=Ks+ass3f(K323,id323,tdf);  
 Ks=Ks+ass3f(K324,id324,tdf);  
 Ks=Ks+ass3f(K325,id325,tdf);  
 Ks=Ks+ass3f(K326,id326,tdf);  
 Ks=Ks+ass3f(K327,id327,tdf);  
 Ks=Ks+ass3f(K328,id328,tdf);  
 Ks=Ks+ass3f(K329,id329,tdf);  
 Ks=Ks+ass3f(K330,id330,tdf);  
 Ks=Ks+ass3f(K331,id331,tdf);  
 Ks=Ks+ass3f(K332,id332,tdf);  
 Ks=Ks+ass3f(K333,id333,tdf);  
 Ks=Ks+ass3f(K334,id334,tdf);  
 Ks=Ks+ass3f(K335,id335,tdf);  
 Ks=Ks+ass3f(K336,id336,tdf);  
 Ks=Ks+ass3f(K337,id337,tdf);  
 Ks=Ks+ass3f(K338,id338,tdf);  
 Ks=Ks+ass3f(K339,id339,tdf);  
 Ks=Ks+ass3f(K340,id340,tdf);  
 Ks=Ks+ass3f(K341,id341,tdf);  
 Ks=Ks+ass3f(K342,id342,tdf);  
 Ks=Ks+ass3f(K343,id343,tdf);  
 Ks=Ks+ass3f(K344,id344,tdf);  
 Ks=Ks+ass3f(K345,id345,tdf);  
 Ks=Ks+ass3f(K346,id346,tdf);  
 Ks=Ks+ass3f(K347,id347,tdf);  
 Ks=Ks+ass3f(K348,id348,tdf);  
 Ks=Ks+ass3f(K349,id349,tdf);  
 Ks=Ks+ass3f(K350,id350,tdf);  
 Ks=Ks+ass3f(K351,id351,tdf);  
 Ks=Ks+ass3f(K352,id352,tdf);  
 Ks=Ks+ass3f(K353,id353,tdf);  
 Ks=Ks+ass3f(K354,id354,tdf);  
 Ks=Ks+ass3f(K355,id355,tdf);  
 Ks=Ks+ass3f(K356,id356,tdf);  
 Ks=Ks+ass3f(K357,id357,tdf);  
 Ks=Ks+ass3f(K358,id358,tdf);  
 Ks=Ks+ass3f(K359,id359,tdf);  
 Ks=Ks+ass3f(K360,id360,tdf);  
 Ks=Ks+ass3f(K361,id361,tdf);  
 Ks=Ks+ass3f(K362,id362,tdf);  
 Ks=Ks+ass3f(K363,id363,tdf);  
 Ks=Ks+ass3f(K364,id364,tdf);  
 Ks=Ks+ass3f(K365,id365,tdf);  
 Ks=Ks+ass3f(K366,id366,tdf);  
 Ks=Ks+ass3f(K367,id367,tdf);  
 Ks=Ks+ass3f(K368,id368,tdf);  
 Ks=Ks+ass3f(K369,id369,tdf);  
 Ks=Ks+ass3f(K370,id370,tdf);  
 Ks=Ks+ass3f(K371,id371,tdf);  
 Ks=Ks+ass3f(K372,id372,tdf);  
 Ks=Ks+ass3f(K373,id373,tdf);  
 Ks=Ks+ass3f(K374,id374,tdf);  
 Ks=Ks+ass3f(K375,id375,tdf);









```

Ks=Ks+ass3f(K660,id660,tdf);
Ks=Ks+ass3f(K661,id661,tdf);
Ks=Ks+ass3f(K662,id662,tdf);
Ks=Ks+ass3f(K663,id663,tdf);
Ks=Ks+ass3f(K664,id664,tdf);
Ks=Ks+ass3f(K665,id665,tdf);
Ks=Ks+ass3f(K666,id666,tdf);
Ks=Ks+ass3f(K667,id667,tdf);
Ks=Ks+ass3f(K668,id668,tdf);
Ks=Ks+ass3f(K669,id669,tdf);
Ks=Ks+ass3f(K670,id670,tdf);
Ks=Ks+ass3f(K671,id671,tdf);
Ks=Ks+ass3f(K672,id672,tdf);
Ks=Ks+ass3f(K673,id673,tdf);
Ks=Ks+ass3f(K674,id674,tdf);
Ks=Ks+ass3f(K675,id675,tdf);
Ks=Ks+ass3f(K676,id676,tdf);
Ks=Ks+ass3f(K677,id677,tdf);
Ks=Ks+ass3f(K678,id678,tdf);
Ks=Ks+ass3f(K679,id679,tdf);
Ks=Ks+ass3f(K680,id680,tdf);
Ks=Ks+ass3f(K681,id681,tdf);
Ks=Ks+ass3f(K682,id682,tdf);
Ks=Ks+ass3f(K683,id683,tdf);
Ks=Ks+ass3f(K684,id684,tdf);
Ks=Ks+ass3f(K685,id685,tdf);
Ks=Ks+ass3f(K686,id686,tdf);
Ks=Ks+ass3f(K687,id687,tdf);
Ks=Ks+ass3f(K688,id688,tdf);
Ks=Ks+ass3f(K689,id689,tdf);
Ks=Ks+ass3f(K690,id690,tdf);
Ks=Ks+ass3f(K691,id691,tdf);
Ks=Ks+ass3f(K692,id692,tdf);
Ks=Ks+ass3f(K693,id693,tdf);
Ks=Ks+ass3f(K694,id694,tdf);
Ks=Ks+ass3f(K695,id695,tdf);
Ks=Ks+ass3f(K696,id696,tdf);

Kf=Ks;
nf=size(Kf);
nn=nf/2;
Rsi=zeros(1632,1);
Rsi(1570,1)=1000;
Rsi(1624,1)=1000;
dsi=Kf\Rsi;

nf=size(Kf);
nn=nf/2;

%Condensation dofs that do not relate
to rigid floor dof
Kc=kcon(Kf,816,816);

%Transformation matrix
xm=12;
ym=12;

a22=trjs((ym),(xm));
a23=trjs((ym),(xm-6));
a24=trjs((ym),(xm-12));
a25=trjs((ym),(xm-18));
a26=trjs((ym),(xm-24));
a27=trjs((ym-6),(xm));
a28=trjs((ym-6),(xm-6));
a29=trjs((ym-6),(xm-12));
a30=trjs((ym-6),(xm-18));
a31=trjs((ym-6),(xm-24));
a32=trjs((ym-12),(xm));
a33=trjs((ym-12),(xm-6));
a34=trjs((ym-12),(xm-12));
a35=trjs((ym-12),(xm-18));

a36=trjs((ym-12),(xm-24));
a37=trjs((ym-18),(xm));
a38=trjs((ym-18),(xm-6));
a39=trjs((ym-18),(xm-12));
a40=trjs((ym-18),(xm-18));
a41=trjs((ym-18),(xm-24));
a42=trjs((ym-24),(xm));
a43=trjs((ym-24),(xm-6));
a44=trjs((ym-24),(xm-12));
a45=trjs((ym-24),(xm-18));
a46=trjs((ym-24),(xm-24));

xm=10;
ym=10;

a47=trjs((ym),(xm));
a48=trjs((ym),(xm-6));
a49=trjs((ym),(xm-12));
a50=trjs((ym),(xm-18));
a51=trjs((ym),(xm-24));
a52=trjs((ym-6),(xm));
a53=trjs((ym-6),(xm-6));
a54=trjs((ym-6),(xm-12));
a55=trjs((ym-6),(xm-18));
a56=trjs((ym-6),(xm-24));
a57=trjs((ym-12),(xm));
a58=trjs((ym-12),(xm-6));
a59=trjs((ym-12),(xm-12));
a60=trjs((ym-12),(xm-18));
a61=trjs((ym-12),(xm-24));
a62=trjs((ym-18),(xm));
a63=trjs((ym-18),(xm-6));
a64=trjs((ym-18),(xm-12));
a65=trjs((ym-18),(xm-18));
a66=trjs((ym-18),(xm-24));
a67=trjs((ym-24),(xm));
a68=trjs((ym-24),(xm-6));
a69=trjs((ym-24),(xm-12));
a70=trjs((ym-24),(xm-18));
a71=trjs((ym-24),(xm-24));

Rt1=[a22;a23;a24;a25;a26;a27;a28;a29;
a30;a31;a32;a33;a34;a35;a36;a37;a38;a
39;a40;a41;a42;a43;a44;a45;a46];
Rt2=[a47;a48;a49;a50;a51;a52;a53;a54;
a55;a56;a57;a58;a59;a60;a61;a62;a63;a
64;a65;a66;a67];
Rt3=[Rt1;zeros(741,3)];
Rt4=[zeros(75,3);Rt1;zeros(666,3)];
Rt5=[zeros(150,3);Rt1;zeros(591,3)];
Rt6=[zeros(225,3);Rt1;zeros(516,3)];
Rt7=[zeros(300,3);Rt1;zeros(441,3)];
Rt8=[zeros(375,3);Rt2;zeros(378,3)];
Rt9=[zeros(438,3);Rt2;zeros(315,3)];
Rt10=[zeros(501,3);Rt2;zeros(252,3)];
Rt11=[zeros(564,3);Rt2;zeros(189,3)];
Rt12=[zeros(627,3);Rt2;zeros(126,3)];
Rt13=[zeros(690,3);Rt2;zeros(63,3)];
Rt14=[zeros(753,3);Rt2];
Rt=[Rt3 Rt4 Rt5 Rt6 Rt7 Rt8 Rt9 Rt10
Rt11 Rt12 Rt13 Rt14];

%Building Stiffness Matrix
K3D=Rt'*Kc*Rt; % Matriks kekakuan
gedung -----

%Building Displacement
R3D=zeros(36,1);
X3D=inv(K3D)*R3D;

%Building Mass Matrix
%M1=[169.101 0 0;0 169.101 0; 0 0
16233.696]; %***my = 126.826

```

```

M1=[169.101 0 0;0 169.101 0; 0 0
16233.696]; %%%my = 126.8626

%M2=[126.826 0 0;0 126.826 0; 0 0
11160.688]; %%%my = 126.826
M2=[126.826 0 0;0 126.826 0; 0 0
11160.688]; %%%my = 126.8626

M3=[M1;zeros(33,3)];
M4=[zeros(3,3);M1;zeros(30,3)];
M5=[zeros(6,3);M1;zeros(27,3)];
M6=[zeros(9,3);M1;zeros(24,3)];
M7=[zeros(12,3);M1;zeros(21,3)];
M8=[zeros(15,3);M2;zeros(18,3)];
M9=[zeros(18,3);M2;zeros(15,3)];
M10=[zeros(21,3);M2;zeros(12,3)];
M11=[zeros(24,3);M2;zeros(9,3)];
M12=[zeros(27,3);M2;zeros(6,3)];
M13=[zeros(30,3);M2;zeros(3,3)];
M14=[zeros(33,3);M2];
M3D=[M3 M4 M5 M6 M7 M8 M9 M10 M11 M12
M13 M14]; %matriks massa

C3D=zeros(36,36);

%System matrix
[n,n]=size(K3D);
A3D=[zeros(n,n) eye(n);
-M3D\K3D -M3D\C3D];
damp(A3D); %%%

%---Hitungan w-----
n=size(M3D,1);
[eigv,eigval]=eig(M3D\K3D);
[cirfre,worder]=sort(sqrt(diag(eigval)
)));
modeshape=eigv(:,worder);
for i=1:n;

modes(:,i)=modeshape(:,i)/modeshape(n
,i);
end
%%Stiffness Proportional Damping

w1=cirfre(1); %6.34 %GANTI YANG
SESUAI
ak=2*0.02/w1; %damping ratio = 2 %
C3D=ak*K3D; %Matriks redaman -----
-----
A3D1=[zeros(n,n) eye(n);
-M3D\K3D -M3D\C3D];
damp(A3D1); %%%

w2=cirfre(2); %6.34 %GANTI YANG
SESUAI
ak=2*0.02/w2; %damping ratio = 2 %
C3D=ak*K3D; %Matriks redaman -----
-----
A3D2=[zeros(n,n) eye(n);
-M3D\K3D -M3D\C3D];
damp(A3D2); %%%

```

*Lampiran 2. Hasil Output SAP 2000*

**Table: Modal Periods and Frequencies**

Model	Period	Frequeny	Circular Freq
Number	Time	Cycle/Time	Radians/Time
Mode 1	0.5468	1.1234	5.224
Mode 2	0.5232	1.1576	5.227
Mode 3	0.4589	1.4562	5.234

**Table: Displacement At Diaphragm Center of Mass**

Story	Diaphragm	Load	Point	X	Y	UX	UY	RZ
	m							
STORY12	D1	GEMPA	48	10	10	0.0024	0.0000	0.00003
STORY11	D1	GEMPA	49	10	10	0.0023	0.0000	0.00003
STORY10	D1	GEMPA	50	10	10	0.0021	0.0000	0.00003
STORY9	D1	GEMPA	51	10	10	0.0018	0.0000	0.00003
STORY8	D1	GEMPA	52	10	10	0.0016	0.0000	0.00002
STORY7	D1	GEMPA	53	10	10	0.0013	0.0000	0.00002
STORY6	D1	GEMPA	54	10	10	0.0011	0.0000	0.00002
STORY5	D1	GEMPA	55	12	12	0.0008	0.0000	0.00001
STORY4	D1	GEMPA	56	12	12	0.0006	0.0000	0.00001
STORY3	D1	GEMPA	57	12	12	0.0004	0.0000	0.00001
STORY2	D1	GEMPA	58	12	12	0.0002	0.0000	0.00000
STORY1	D1	GEMPA	59	12	12	0.0000	0.0000	0.00000

**Table: Element Forces – Frames, Part 1 of 2**

Frame	Station	OutputCase	CaseType	P	V2	V3	T	M2
Text	m	Text	Text	KN	KN	KN	KN-m	KN-m
837	0.00000	STATIC-1	LinStatic	854.188	79.894	3.969	3.5868	18.68

**Table: Element Forces - Frames, Part 2 of 2**

Frame	Station	OutputCase	M3	FrameElem	ElemStation
Text	m	Text	KN-m	Text	m
837	0.00000	STATIC-1	429.5883	837	0.00000